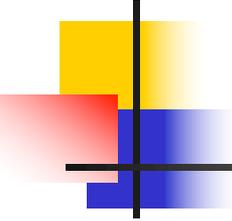


# Knowledge Compilers

---

**Adnan Darwiche**

**Computer Science Department, UCLA**

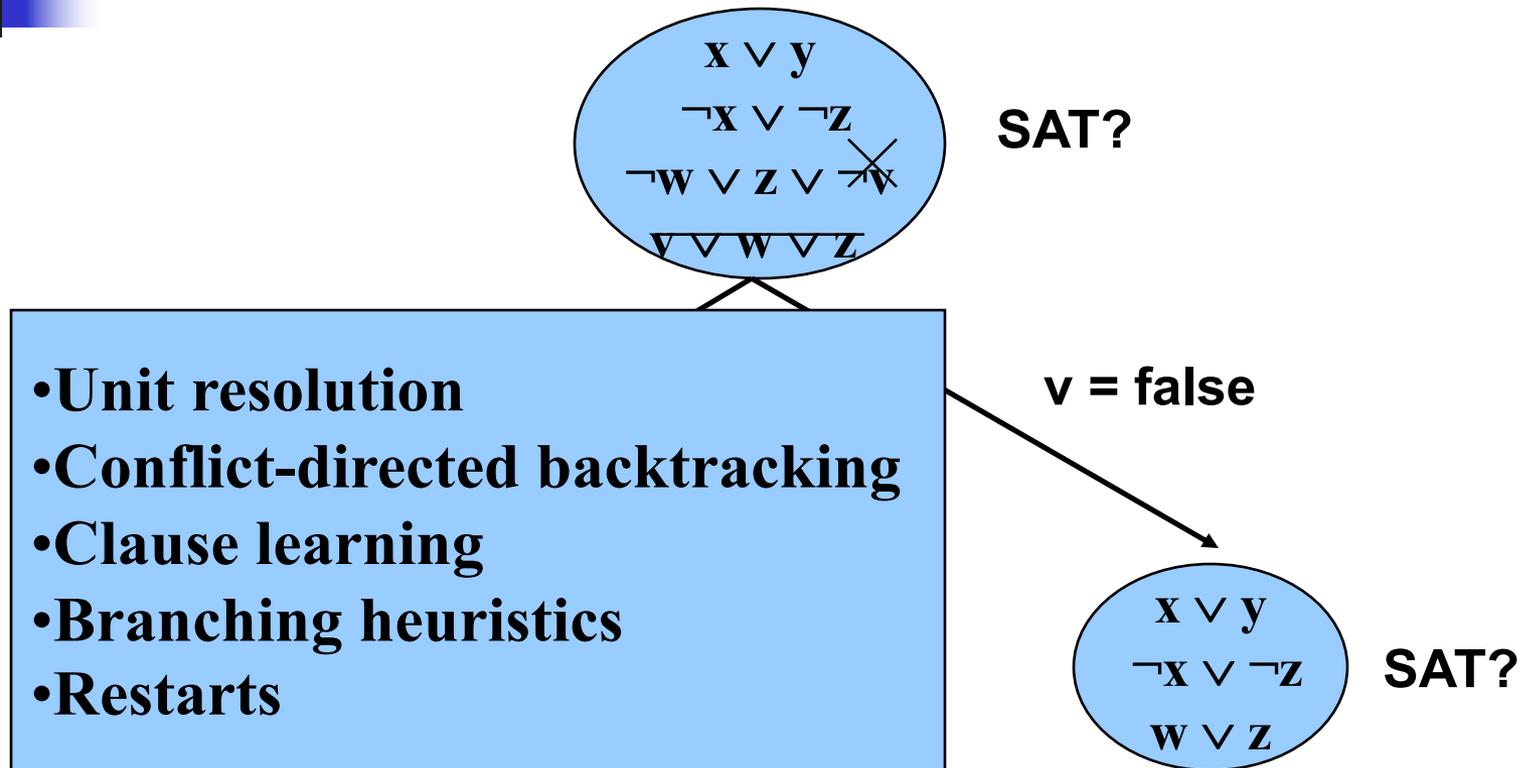


# Building Compilers

---

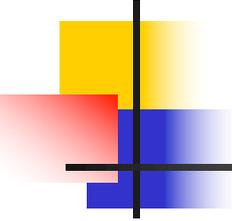
- To-down approaches:
  - Based on exhaustive search
  
- Bottom-up approaches:
  - Based on transformations

# SAT by DPLL Search



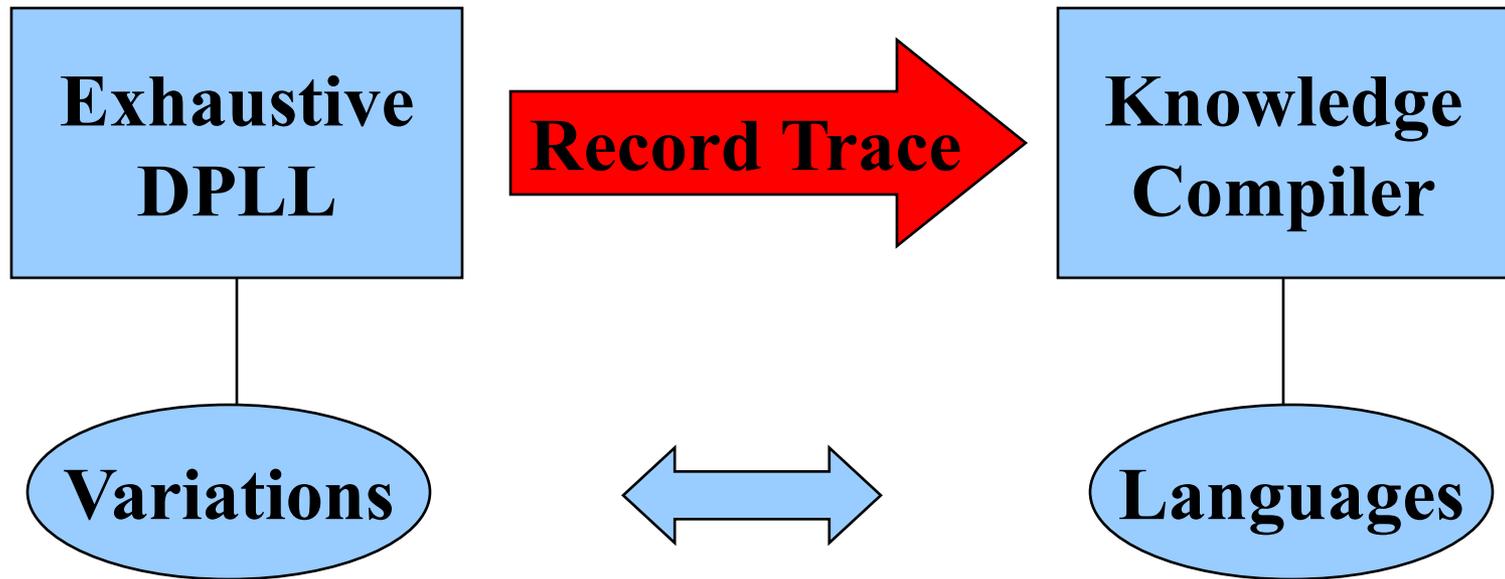
Terminating condition for recursion:

empty set (satisfied), or empty clause (contradiction)

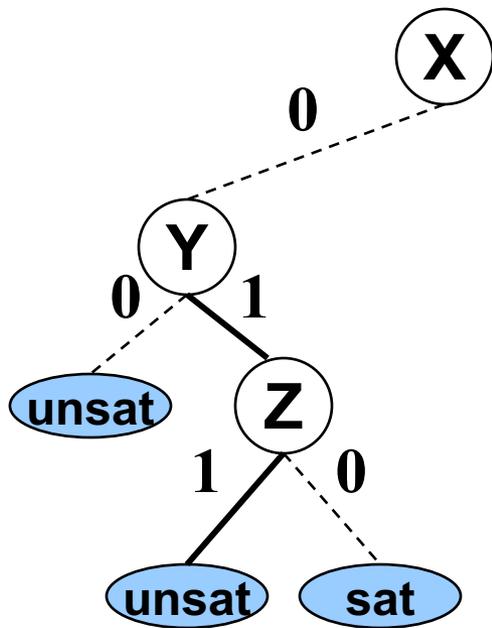


# The Language of Search

---



# Trace of DPLL



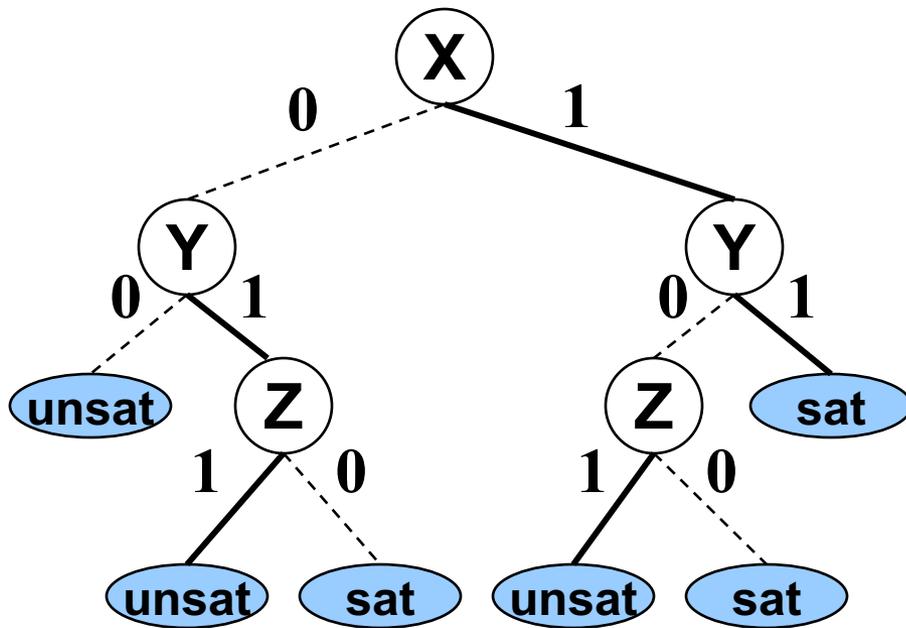
$$X \vee Y$$

$$X \vee \neg Y \vee \neg Z$$

$$\neg X \vee Y \vee \neg Z$$

# Exhaustive DPLL

## Run to Exhaustion

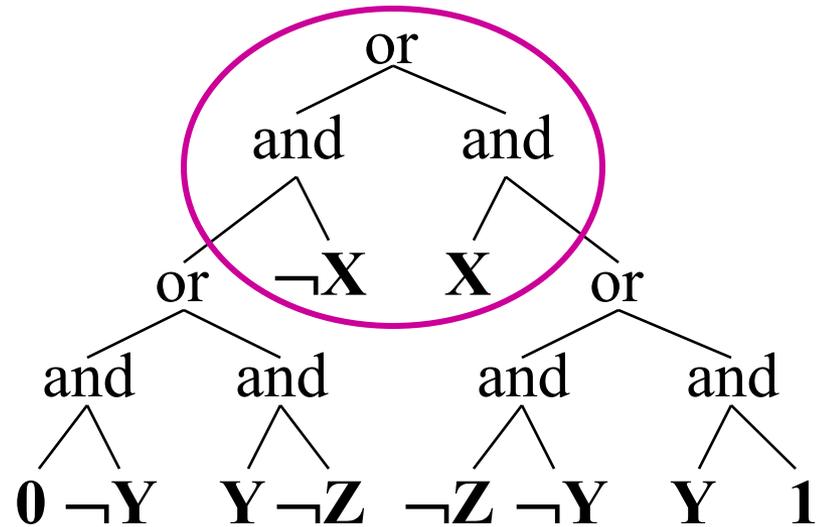
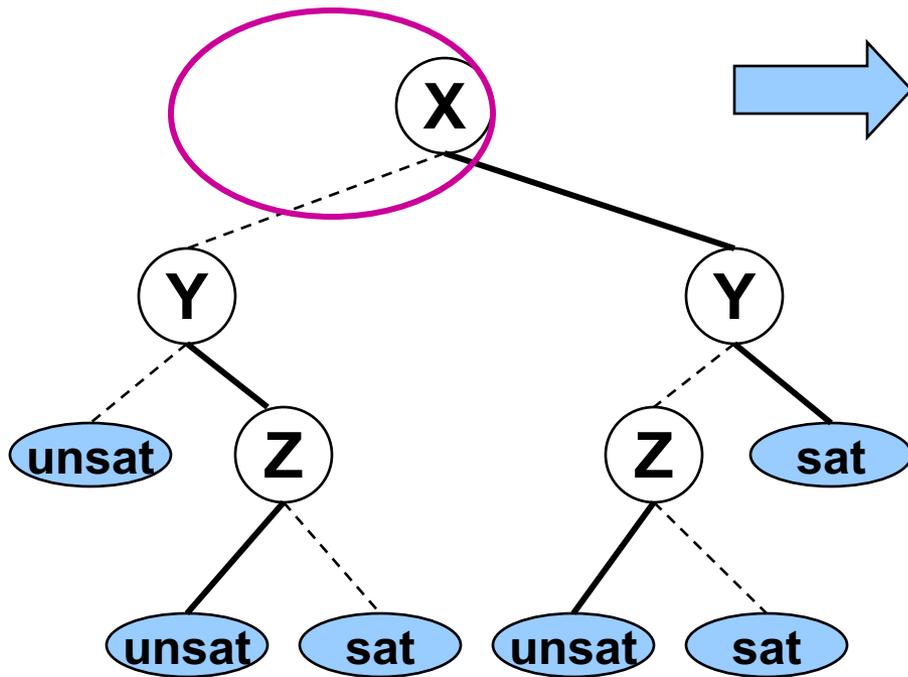


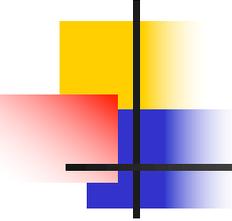
$$X \vee Y$$

$$X \vee \neg Y \vee \neg Z$$

$$\neg X \vee Y \vee \neg Z$$

# Trace of DPLL: a Formula



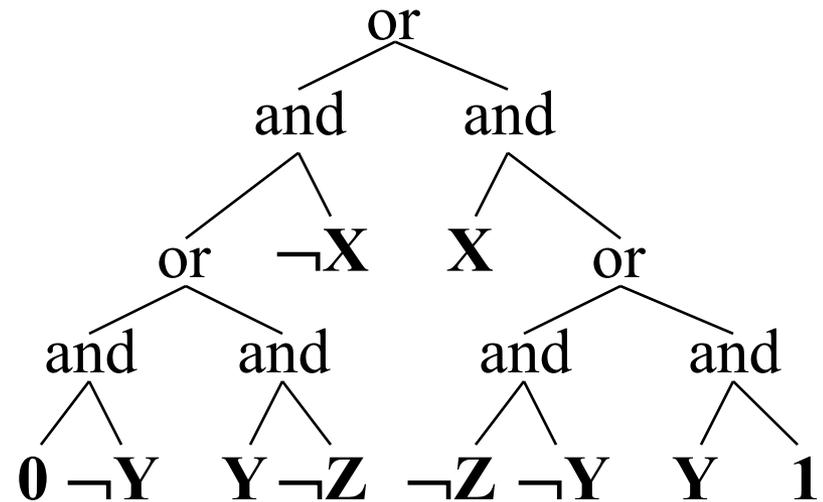


# Trace of DPLL: a Formula

---

**Equivalent to  
original CNF**

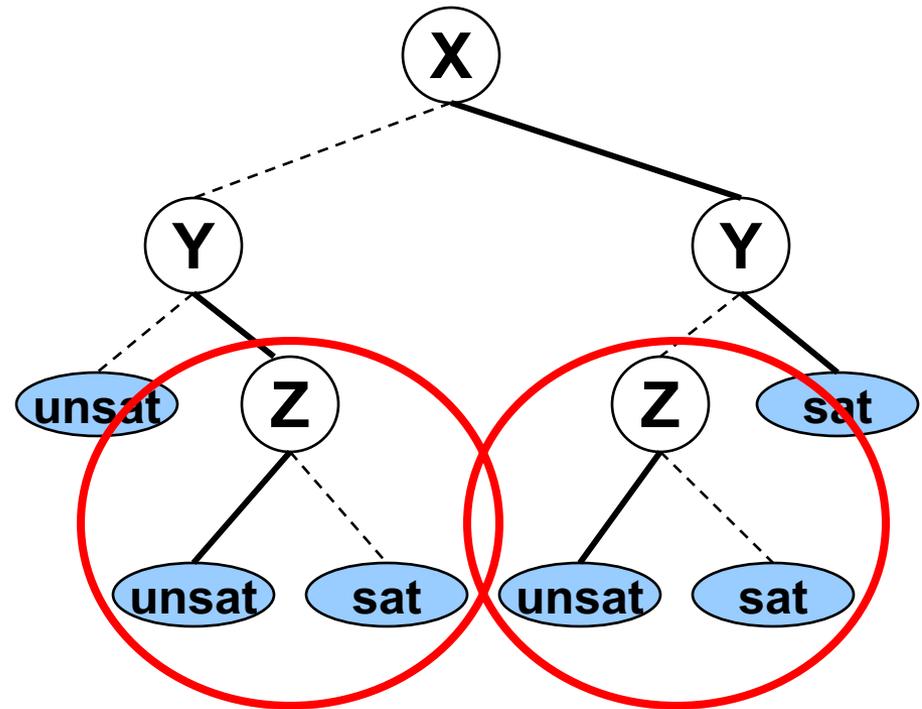
**Tractable  
(e.g., count models)**



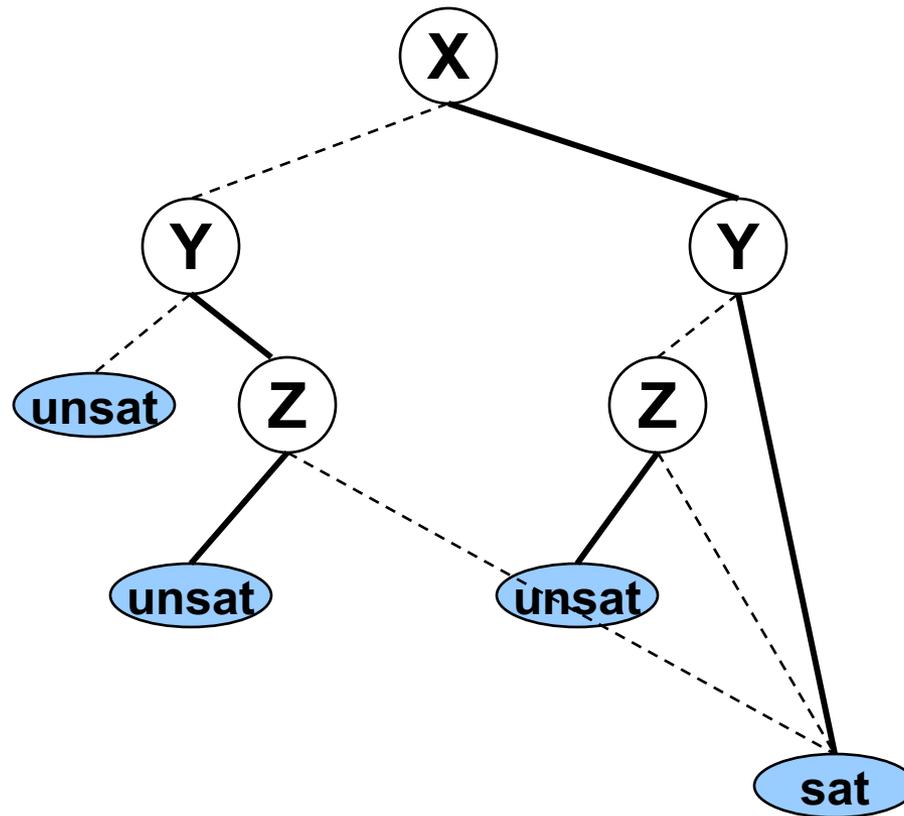
# Dealing with Redundancy

**Level One:** Do not record redundant portions of trace

**Level Two:** Try not to solve equivalent subproblems

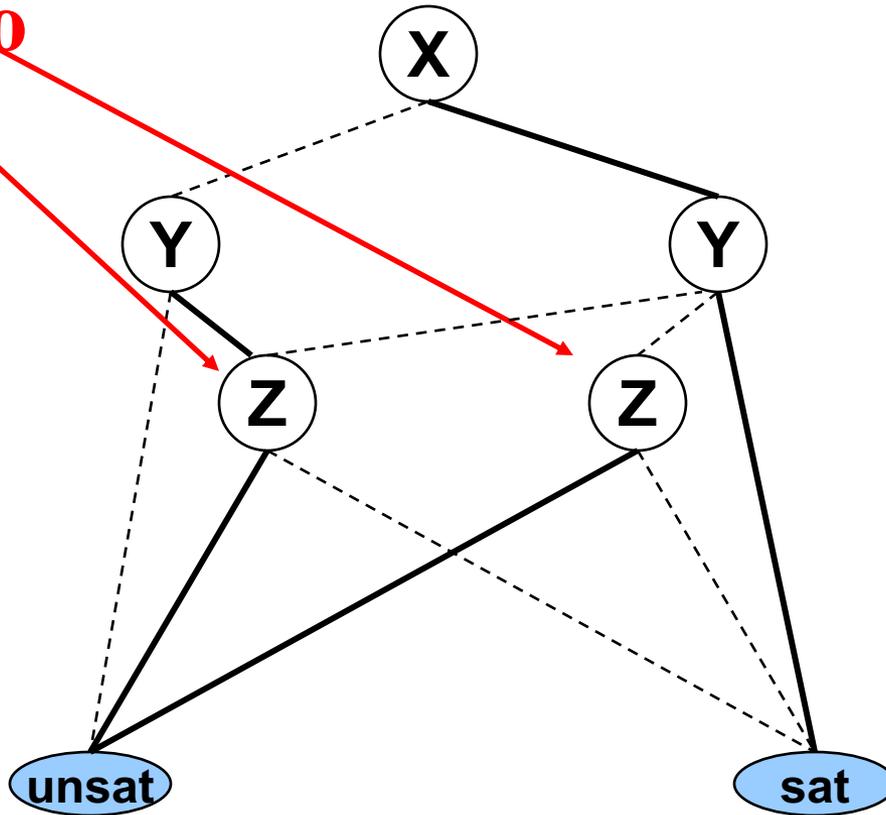


# Dealing with Redundancy

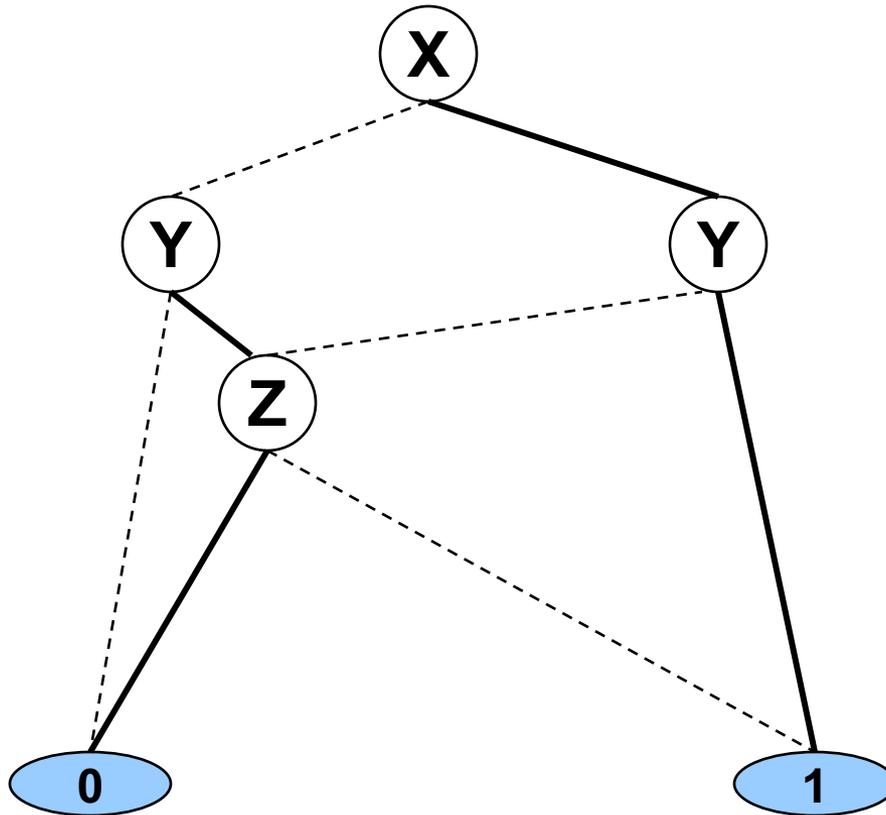


# Dealing with Redundancy

Simply create to existing node

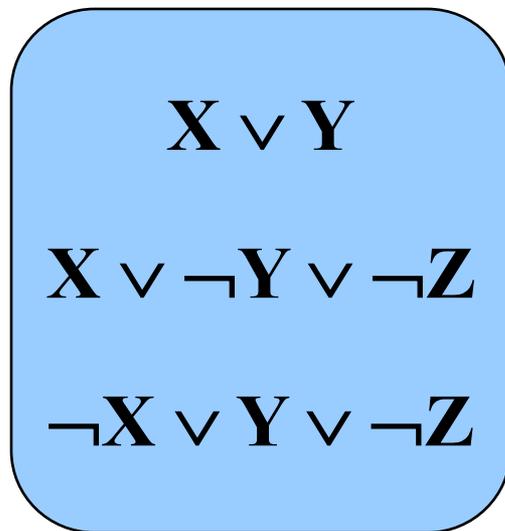


# This is an OBDD!



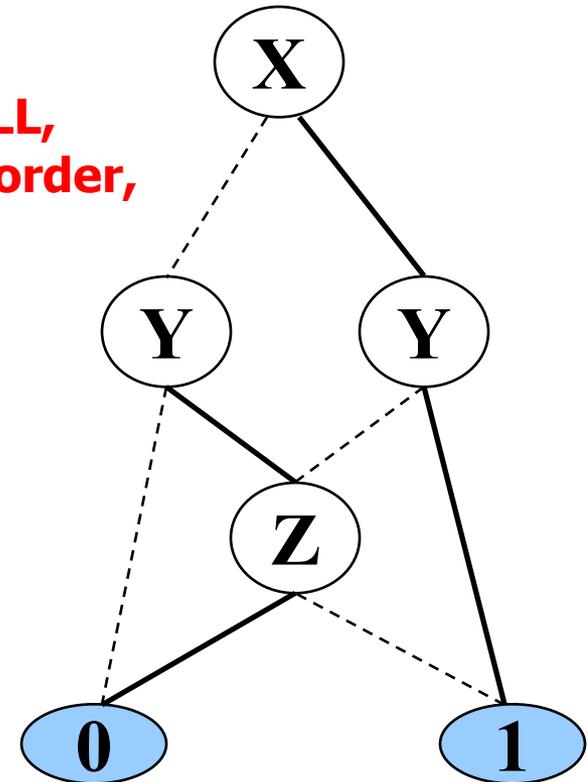


# A Non-traditional OBDD Compiler



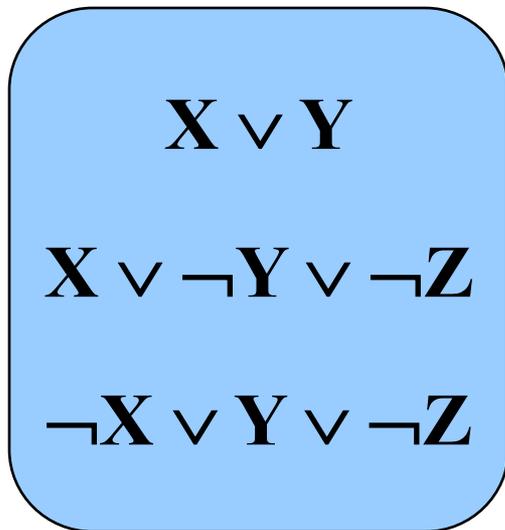
Exhaustive DPLL,  
Fixed variable order,  
Unique nodes

Compile



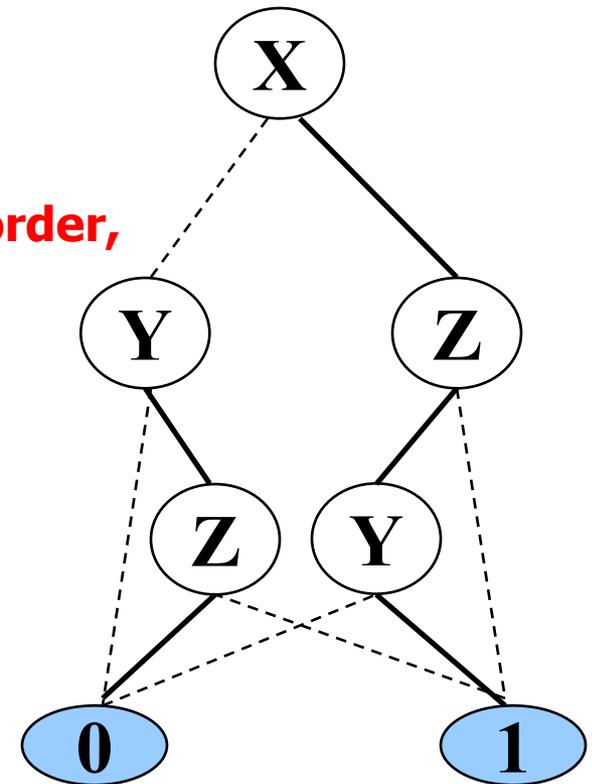
New complexity guarantees

# FBDD

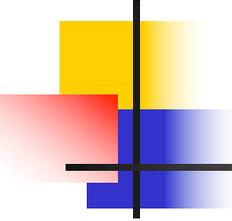


Exhaustive DPLL,  
Dynamic variable order,  
Unique nodes

Compile



NNF + decision, decomposability



# Dealing with Redundancy

---

- **Level One: Unique nodes (done)**
- **Level Two: Avoid redundant compilation (searches)**

# Redundant Compilation

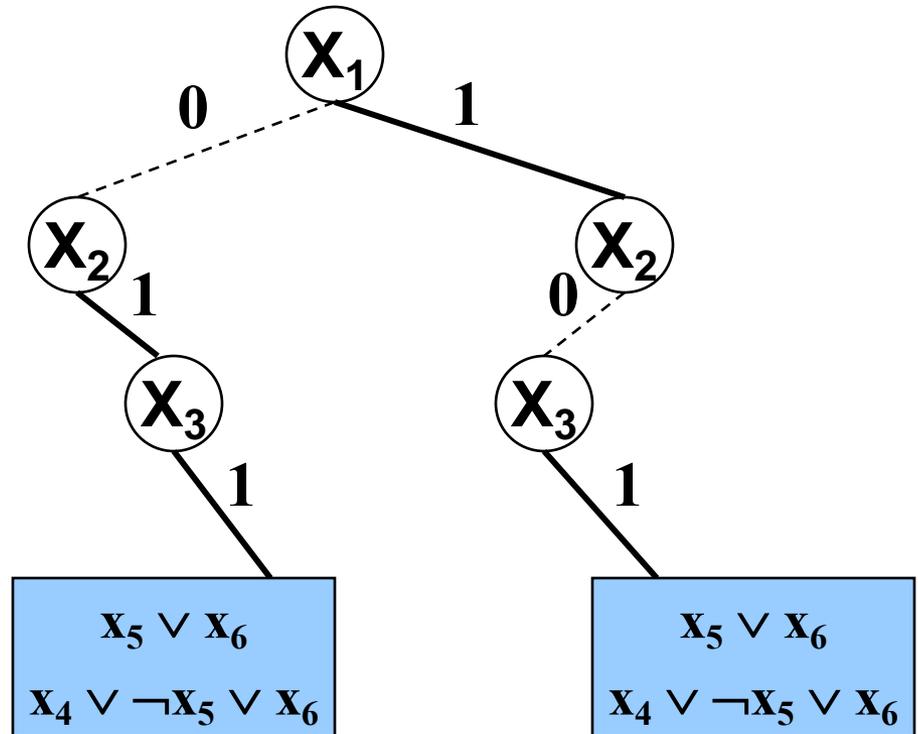
$$x_5 \vee x_6$$

$$x_4 \vee \neg x_5 \vee x_6$$

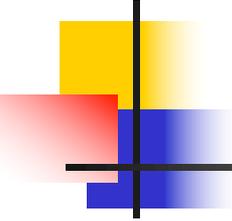
$$x_1 \vee x_3 \vee x_4 \vee x_5$$

$$x_2 \vee x_3$$

$$x_1 \vee x_2 \vee \neg x_3$$



**Formula Caching: complexity guarantees**



# Beyond BDDs...

---

**Plain DPLL**



**FBDD**

**Fixed Variable  
Ordering**

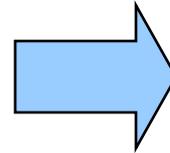


**OBDD**

# Decomposition (Component Analysis)

---

**Solve disjoint  
subproblems  
independently**



**d-DNNF**

**Combine as  
AND node**

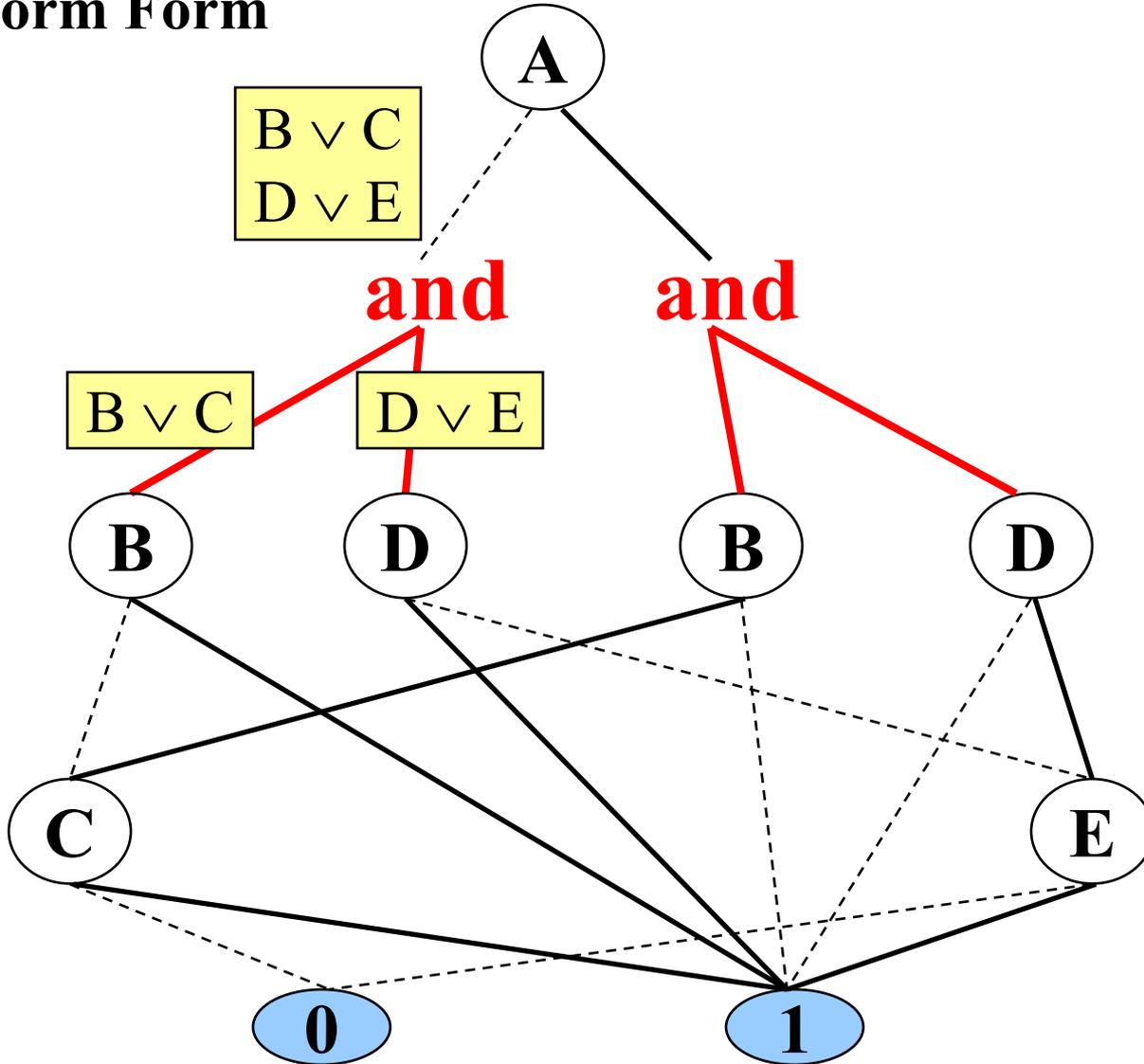
**Deterministic**

**Decomposable**

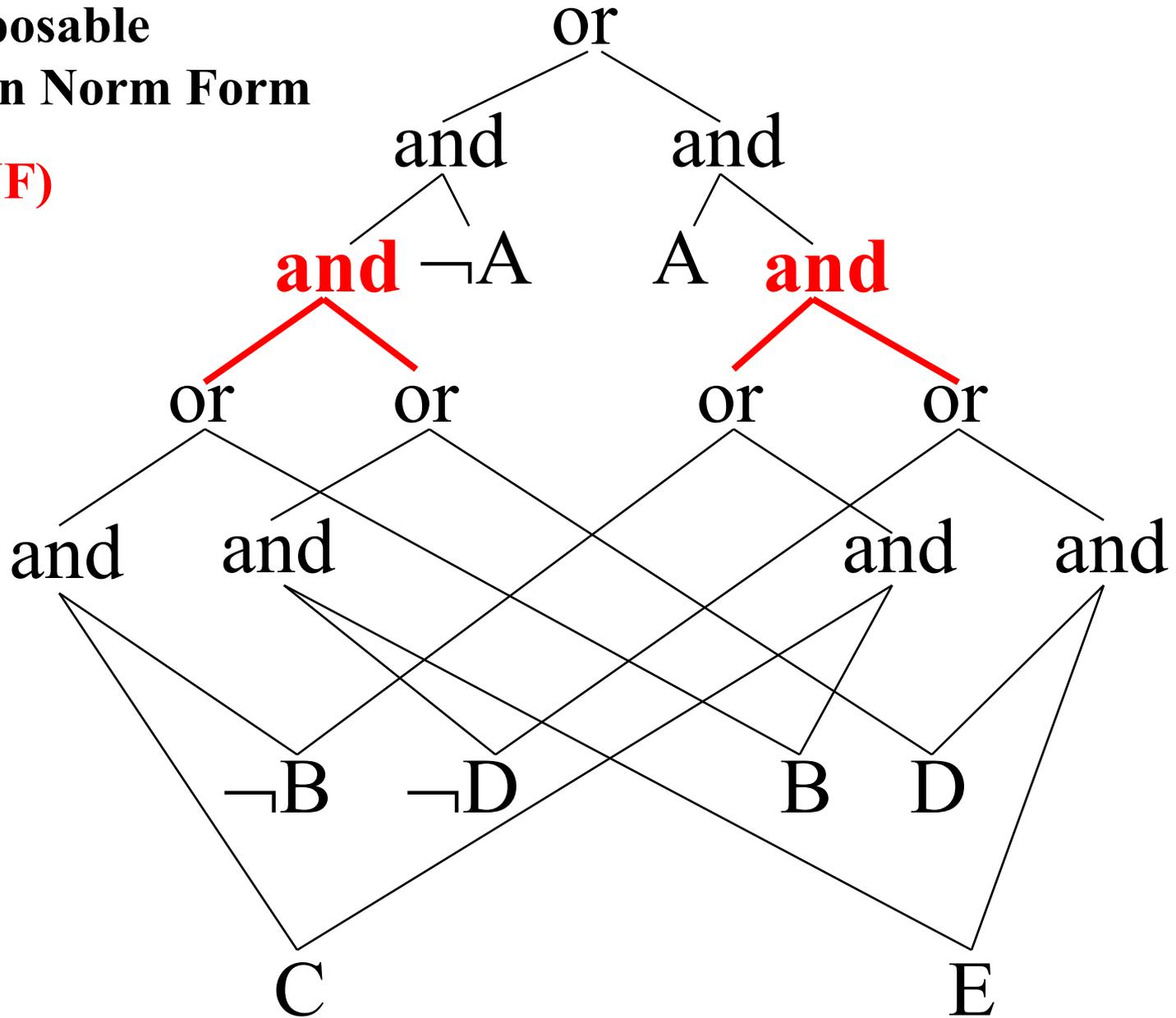
**Negation Norm Form**

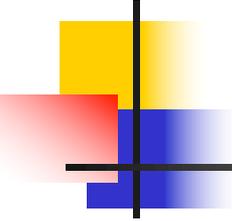
**(d-DNNF)**

$A \vee B \vee C$	$\neg A \vee \neg B \vee C$
$A \vee D \vee E$	$\neg A \vee \neg D \vee E$



**Deterministic**  
**Decomposable**  
**Negation Normal Form**  
**(d-DNNF)**

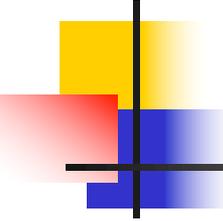




# Decomposition Strategies

---

- Static (c2d)
  - Hypergraph partitioning pre-compilation
  - Strategy captured using a dtree (decomposition tree)
- Dynamic (Dsharp/Cachet)
  - Dynamic variable orderings
  - Lazy detection of decompositions
- Mixed (D4)
  - Hypergraph partitioning during compilation
  - Done selectively (using dtrees)



# The Language of Search

---

**Fixed Variable  
Ordering**



**OBDD**

**Plain DPLL**



**FBDD**

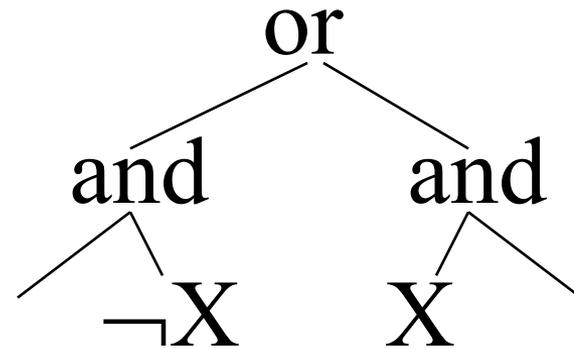
**Allowing  
Decomposition**



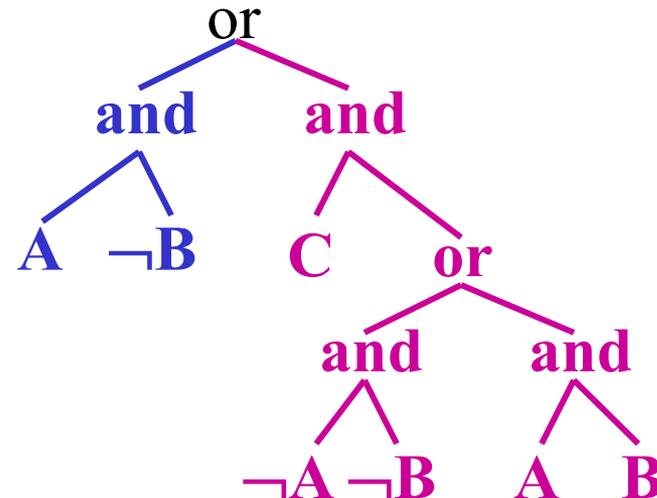
**d-DNNF**

# Limitation of DPLL: General determinism

**Decision nodes  
(Decision-DNNF)**



**Deterministic nodes  
(d-DNNF)**

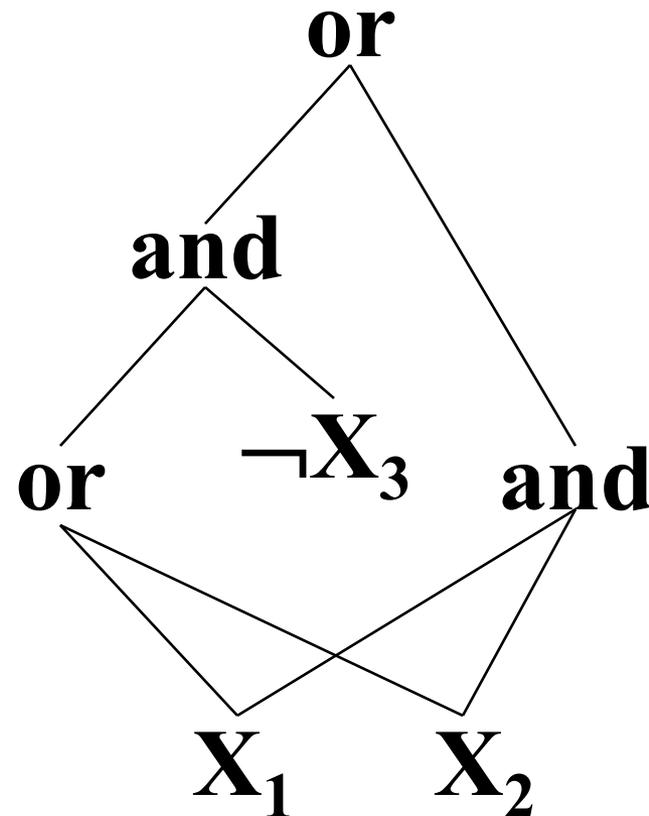


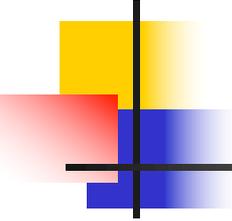
# Beyond DPLL:

## Decomposability (D) without determinism (d)

### DNNF:

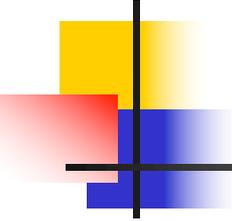
CO, CE, ME,  
exist quantification





# Bottom-up Compilation

---

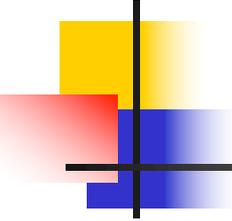


# Bottom-up Compilation

---

**CNF:**  $(x + y) (y + z)$

Variable order:  $x, y, z$



# Bottom-up Compilation

---

**CNF:**  $(x + y) (y + z)$

Variable order:  $x, y, z$

***Apply:***

combines two OBDDs  
using Boolean operators

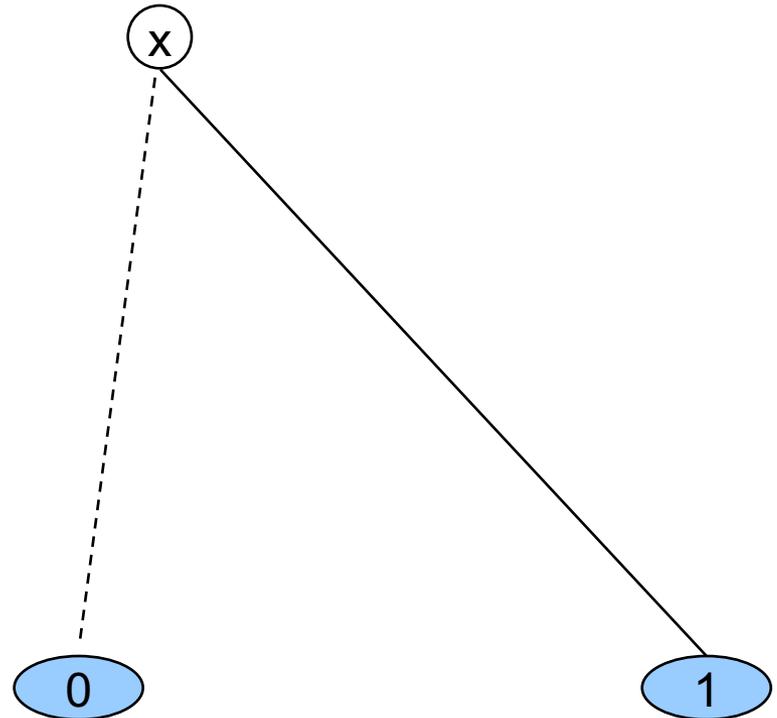
# Bottom-up Compilation

**CNF:**  $(x + y) (y + z)$

Variable order:  $x, y, z$

***Apply:***

combines two OBDDs  
using Boolean operators



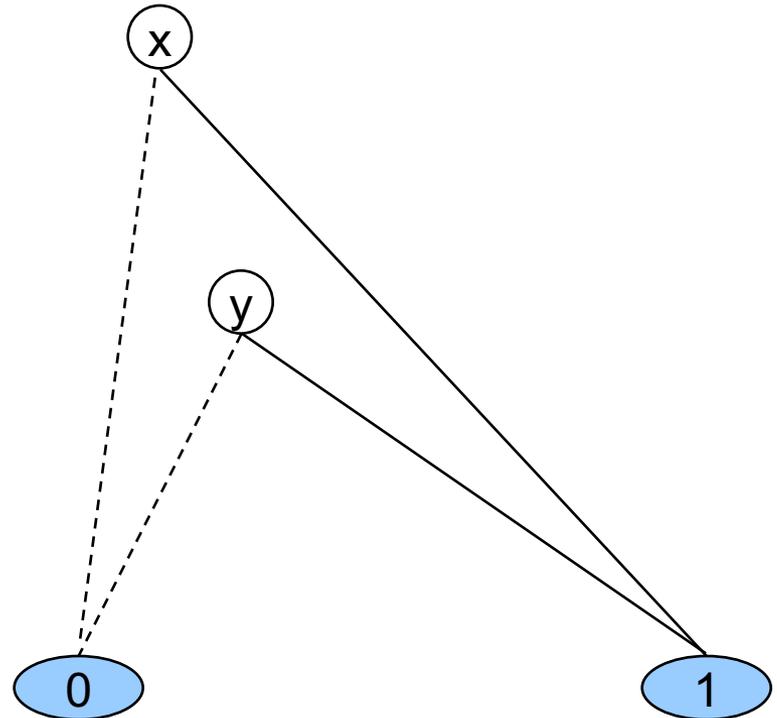
# Bottom-up Compilation

**CNF:**  $(x + y) (y + z)$

Variable order:  $x, y, z$

***Apply:***

combines two OBDDs  
using Boolean operators



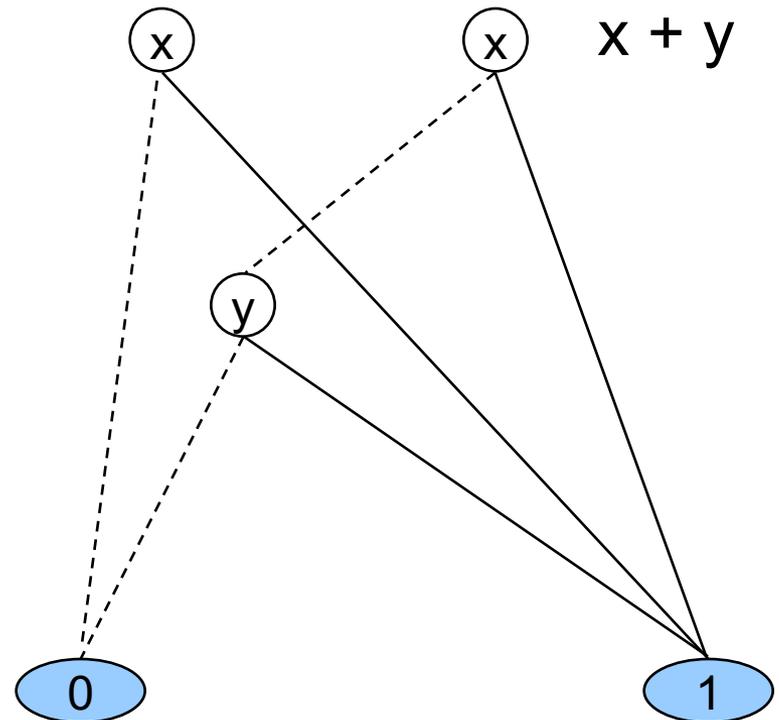
# Bottom-up Compilation

**CNF:**  $(x + y) (y + z)$

Variable order:  $x, y, z$

**Apply:**

combines two OBDDs  
using Boolean operators



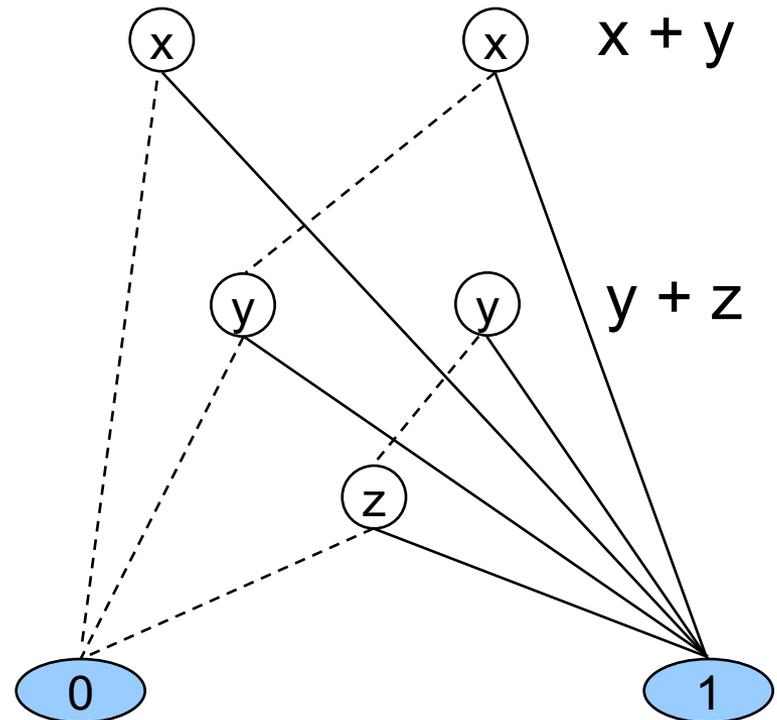
# Bottom-up Compilation

**CNF:**  $(x + y) (y + z)$

Variable order:  $x, y, z$

**Apply:**

combines two OBDDs  
using Boolean operators



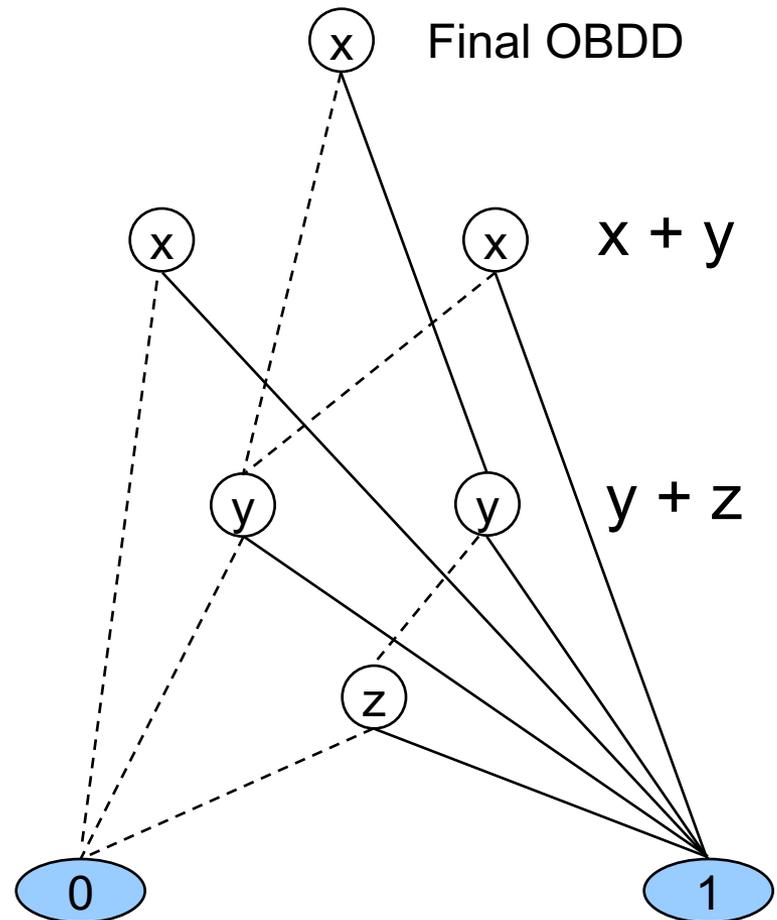
# Bottom-up Compilation

**CNF:**  $(x + y) (y + z)$

Variable order:  $x, y, z$

**Apply:**

combines two OBDDs  
using Boolean operators



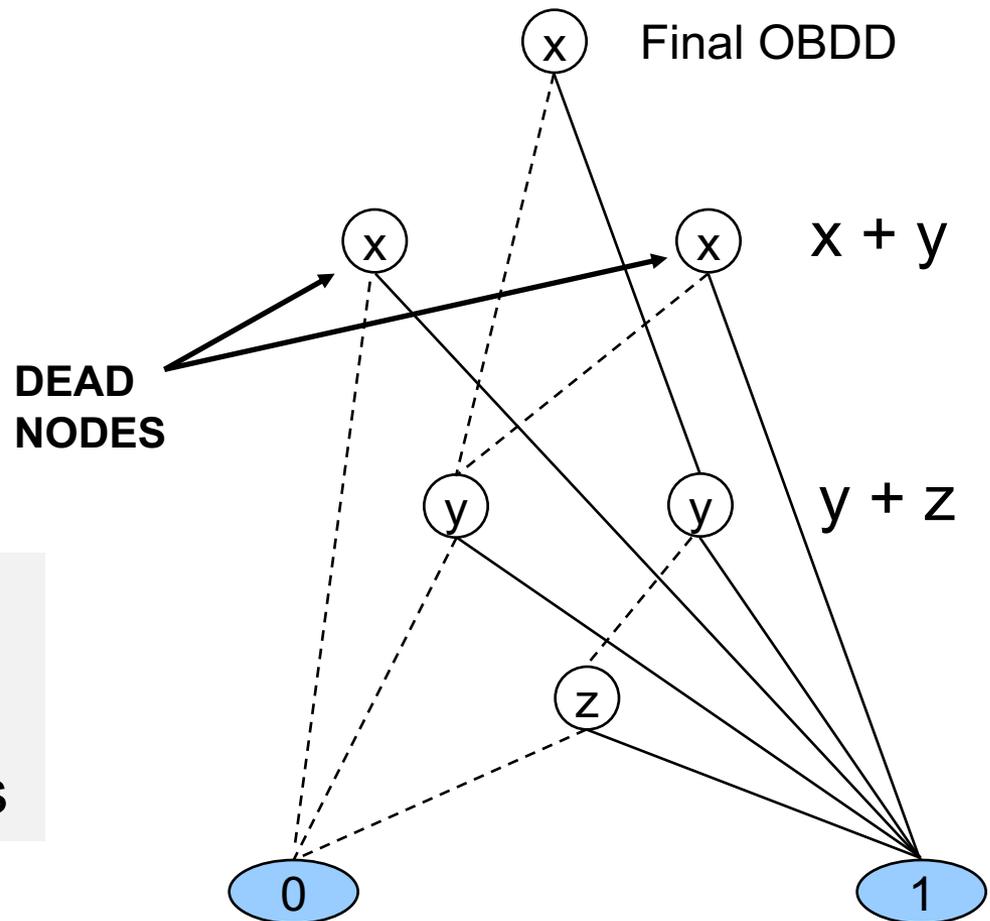
# Bottom-up Compilation

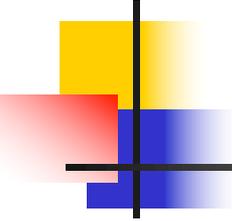
**CNF:**  $(x + y) (y + z)$

Variable order:  $x, y, z$

**Apply:**

combines two OBDDs  
using Boolean operators

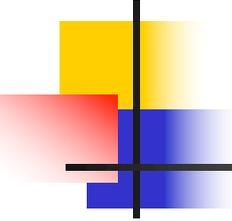




# Bottom-up Compilation

---

- Requires:
  - *Apply* (conjoin, disjoin, etc)
  - Garbage collection of dead nodes
- Challenges:
  - Good variable order
  - Good schedule of Apply operations
- uf100-08 (32 models):
  - 176 nodes in final OBDD under MINCE variable order
  - 30,640,582 intermediate nodes using CUDD package



# Canonicity in Compilation

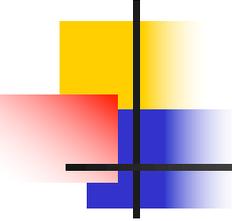
---

- OBDDs are canonical  
**variable order  $\rightarrow$  unique OBDD**

(reduced OBDDs)

- SDDs are canonical  
**vtree  $\rightarrow$  unique SDD**

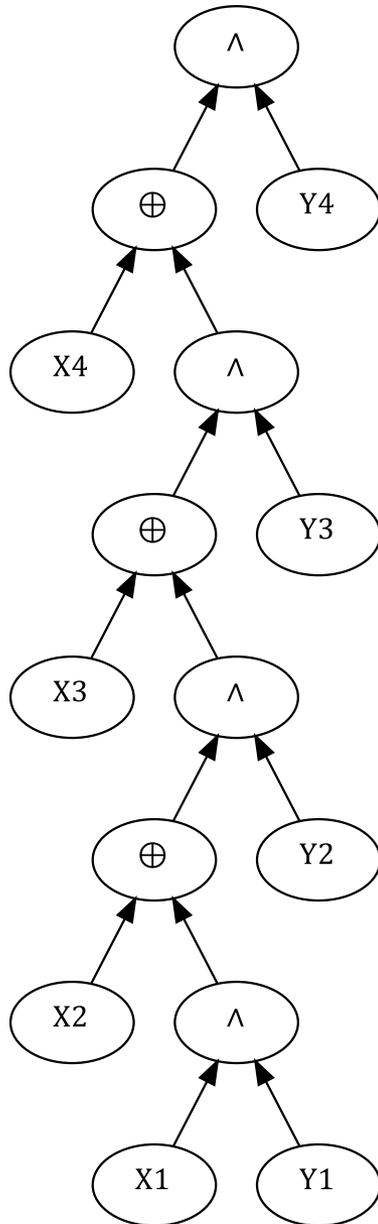
(trimmed and compressed SDDs)



# Vtrees Matter!

---

- A vtree can have a significant impact on the size of an SDD
- Good vtrees can be obtained either
  - **Statically**: by analyzing the Boolean function structure before compilation
  - **Dynamically**: by searching for an appropriate vtree during compilation

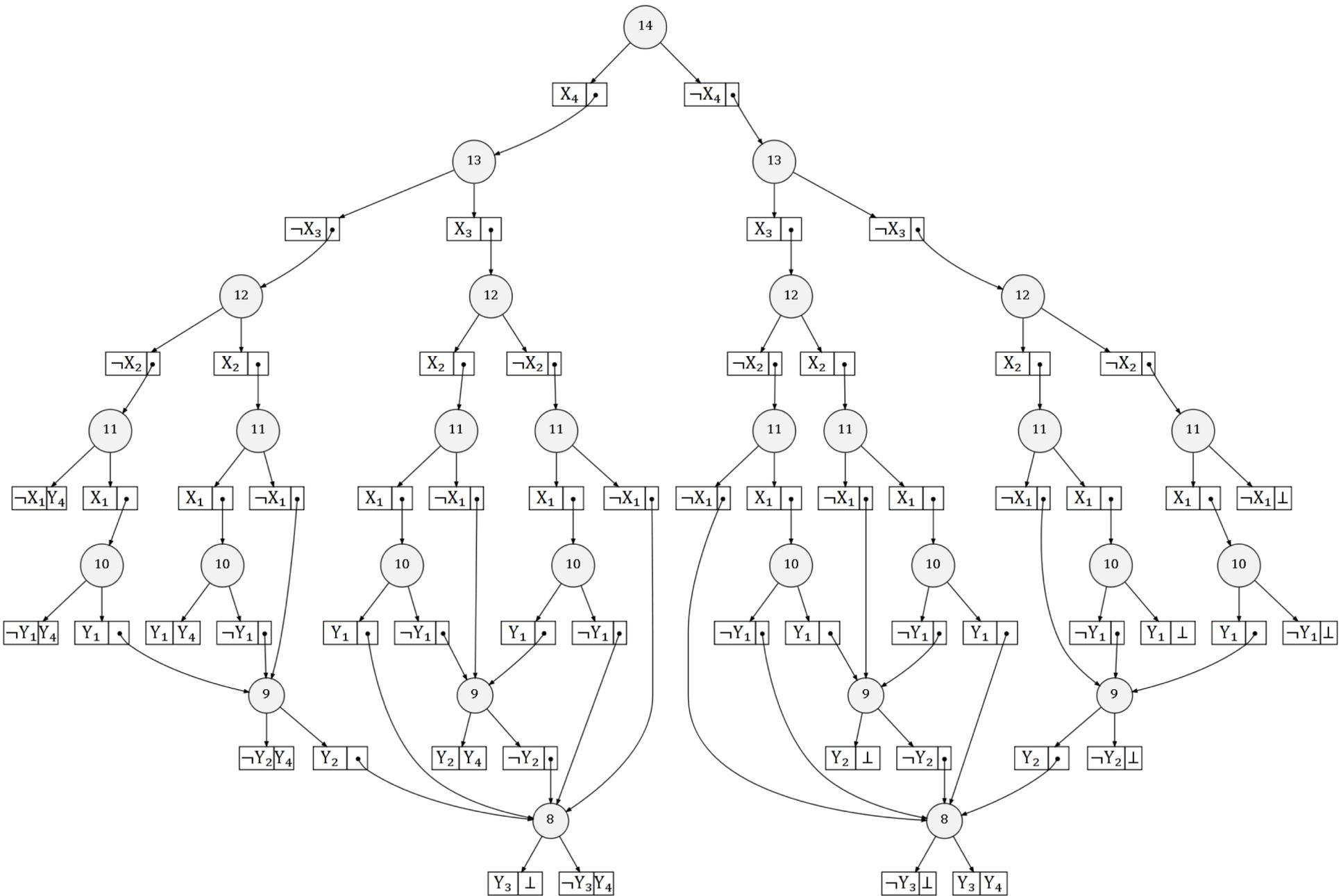


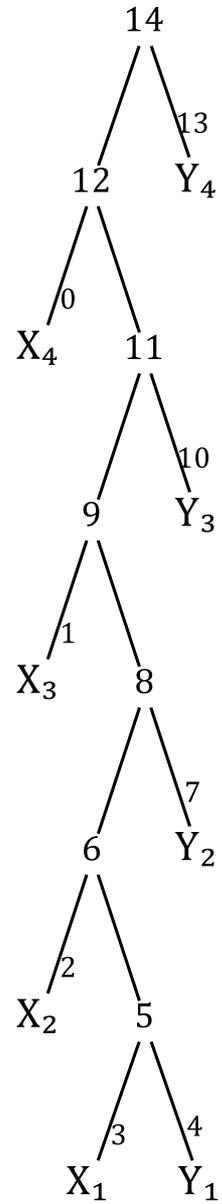
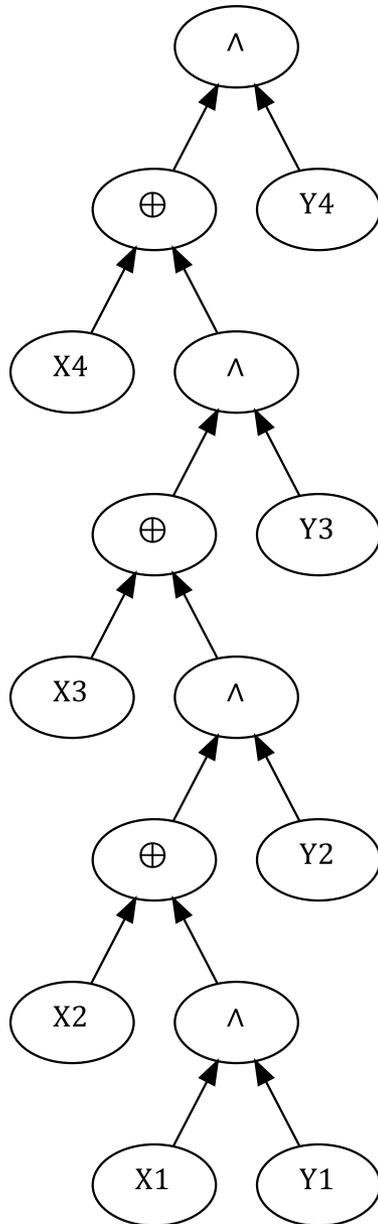
variables

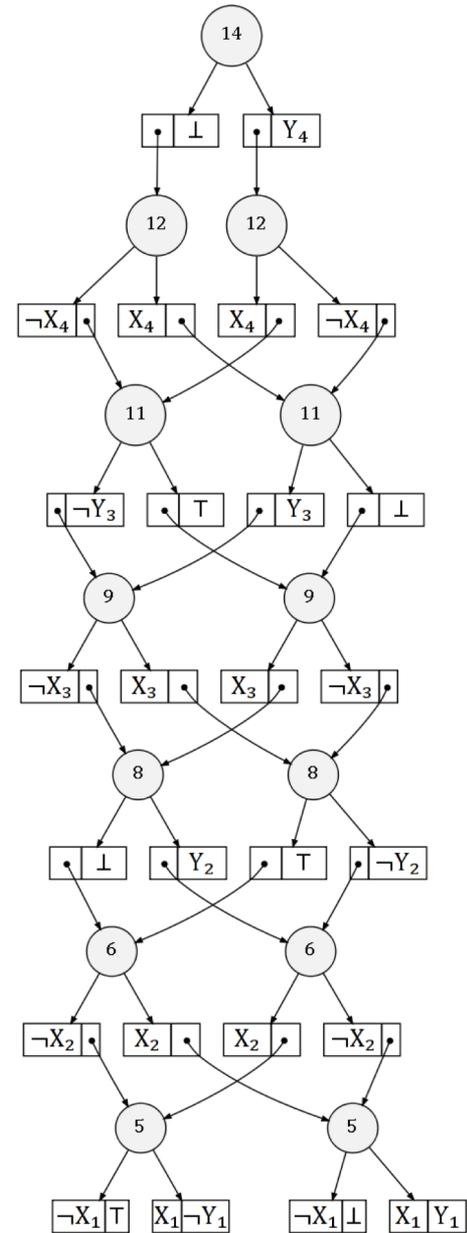
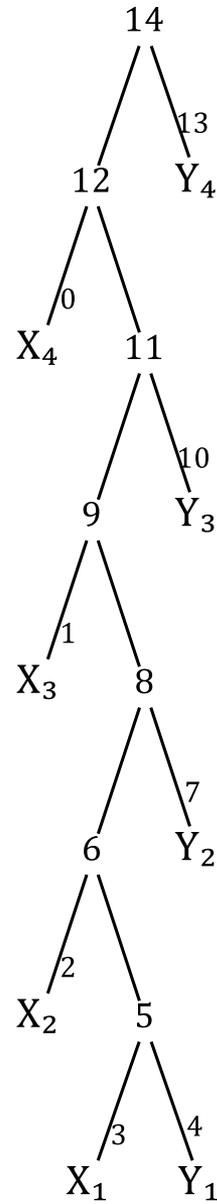
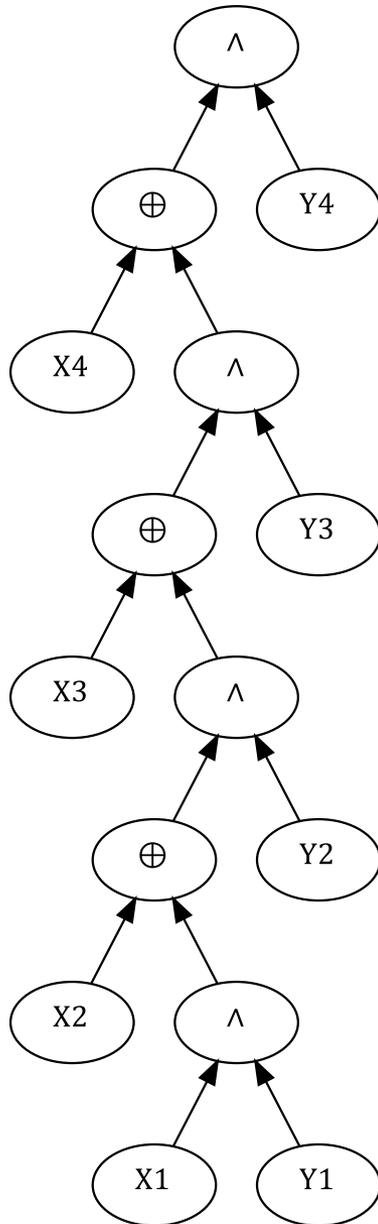
$\mathbf{X} = \{ X_1 X_2 X_3 \dots X_n \}$

$\mathbf{Y} = \{ Y_1 Y_2 Y_3 \dots Y_n \}$

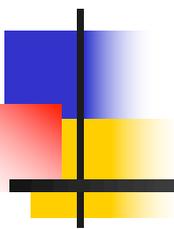




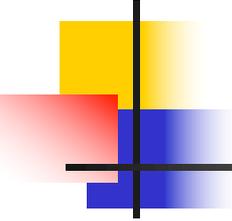




# **Vtree Search: Minimizing SDD Size**

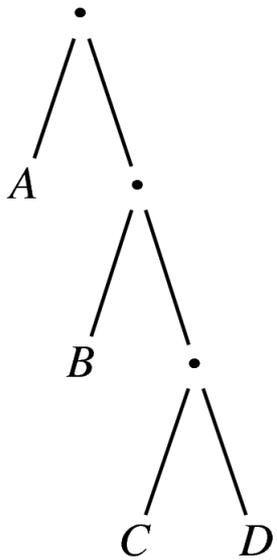


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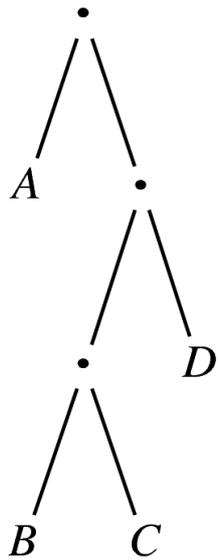


# Dissecting Variable Orders

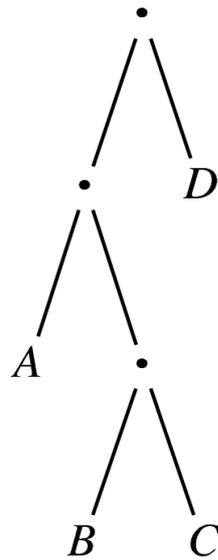
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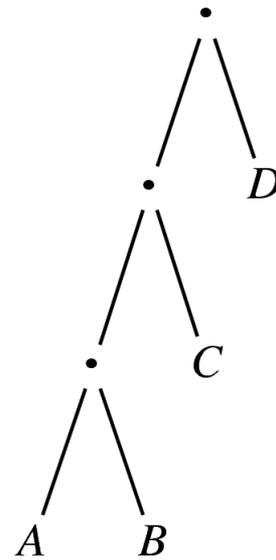
*ABCD*



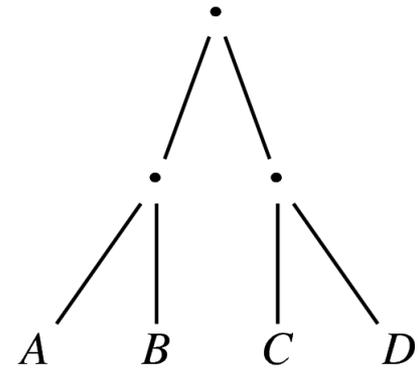
*ABCD*



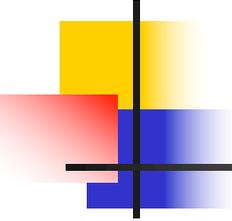
*ABCD*



*ABCD*



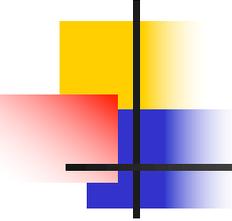
*ABCD*



# Vtrees Matter!

---

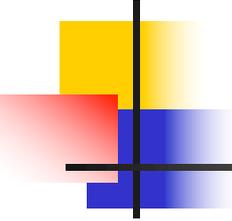
- The choice of a vtree can lead to exponential difference in the size of an SDD
- The choice of a dissection can also lead to exponential differences in the size of an SDD



# Searching Over Vtrees

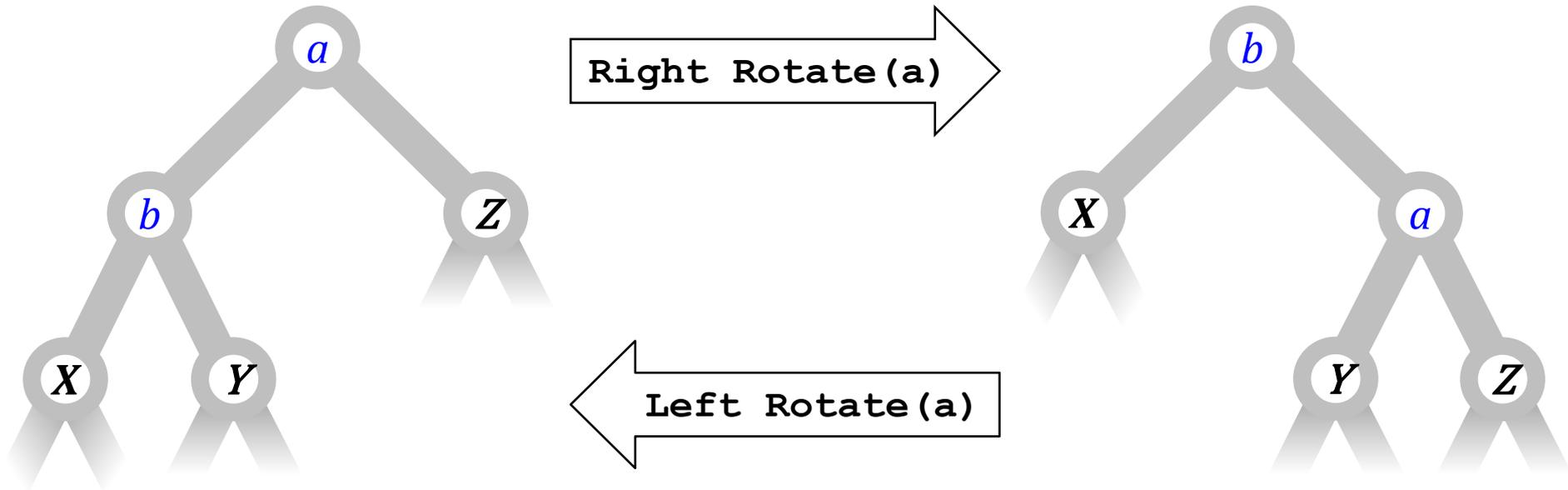
---

- Double search problem:
  - Find variable order
  - Find dissection
- Tree operations:
  - Rotation (left, right)
  - Swapping
- Can enumerate all vtrees

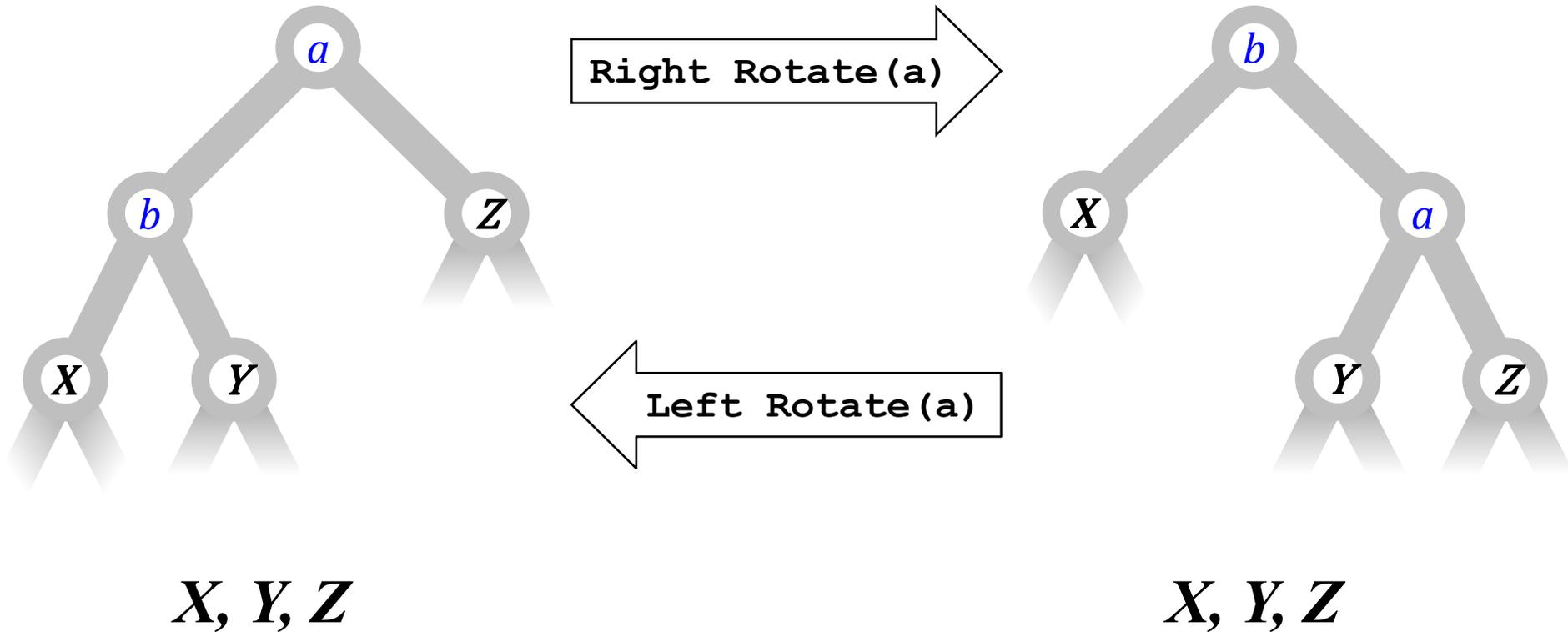


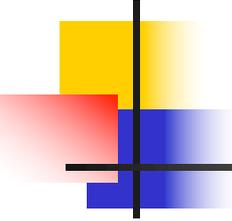
# Tree Rotations

---



# Rotation Preserves Order

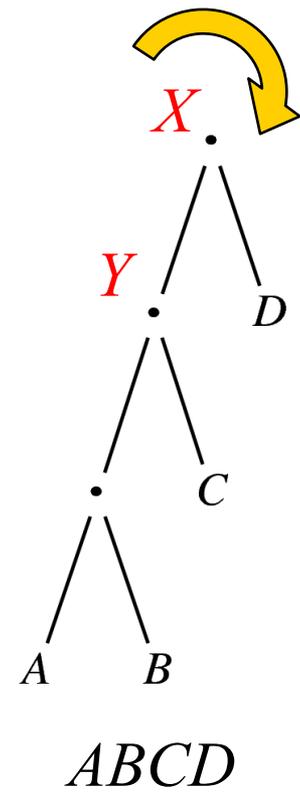
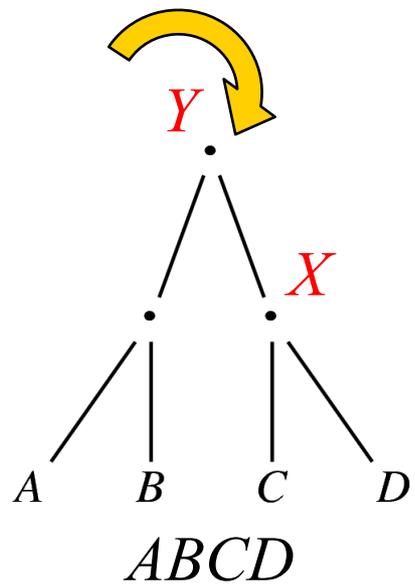
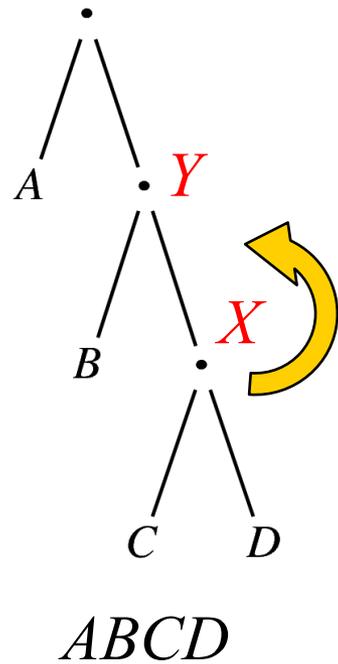
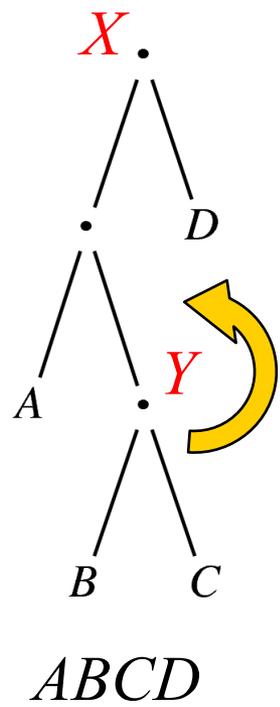
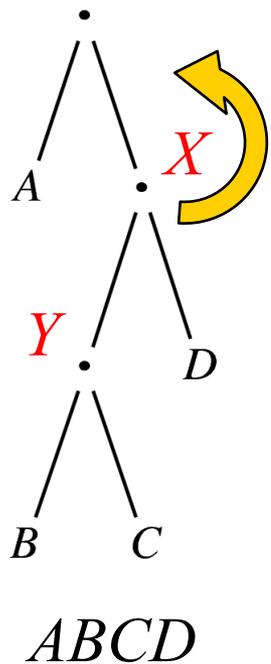




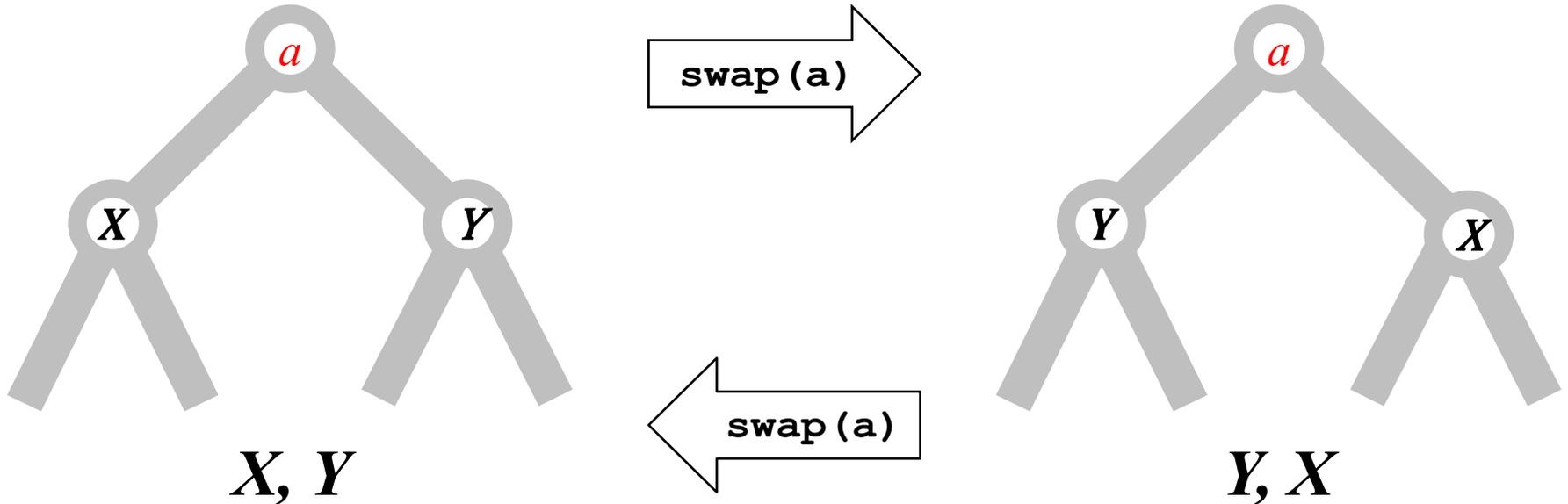
# Enumerating Dissections

---

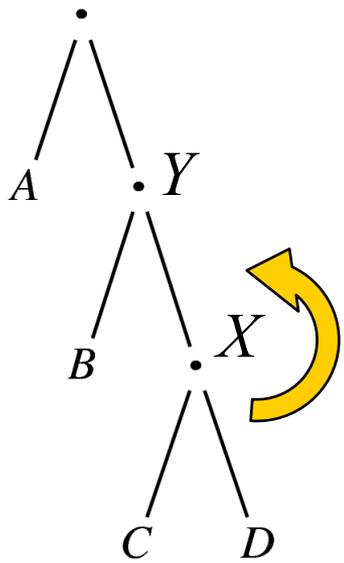
- Rotations can enumerate all dissections of a given variable order
- Systematic methods exist for this purpose
- See, e.g., Knuth's  
Art of Computer Programming, Volume 4, Fascicle 4: Generating All Trees



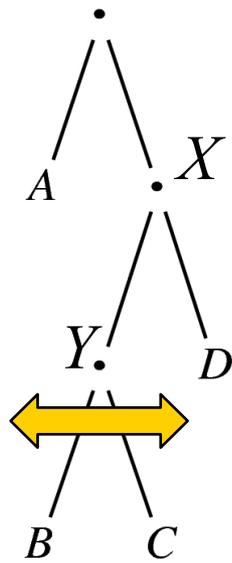
# Swapping Changes Order



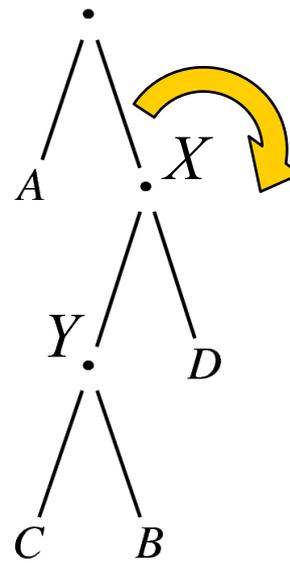
# Rotate + Swap



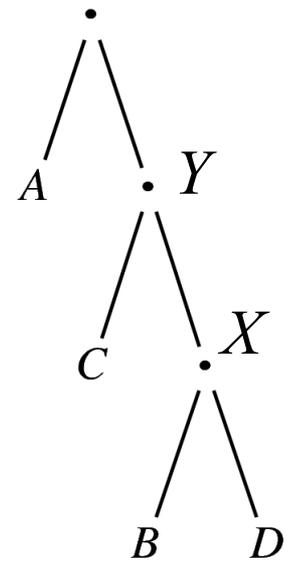
*ABCD*



*ABCD*

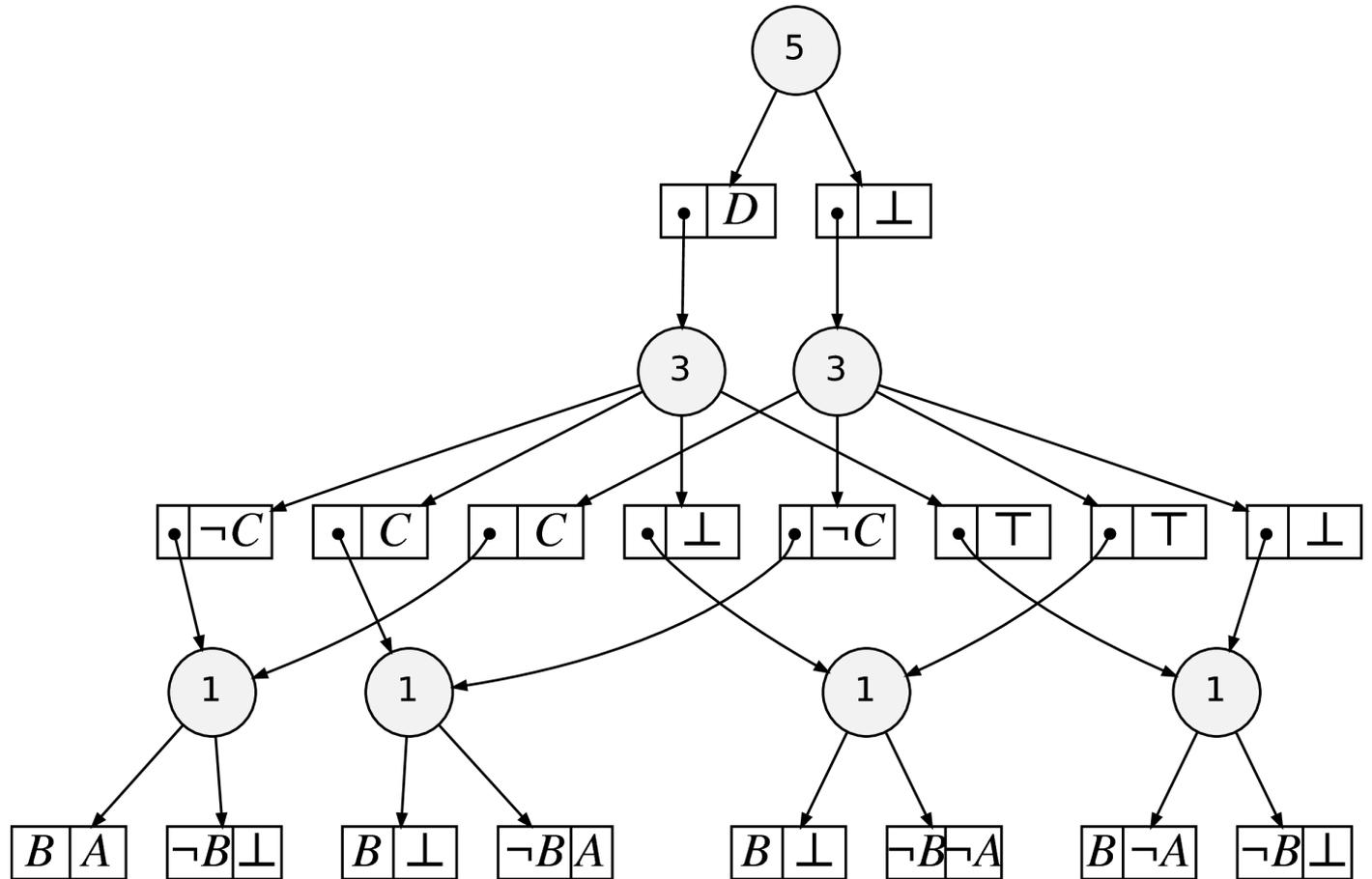
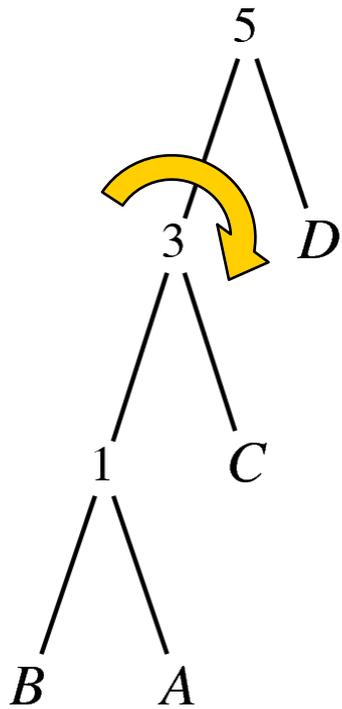


*ACBD*

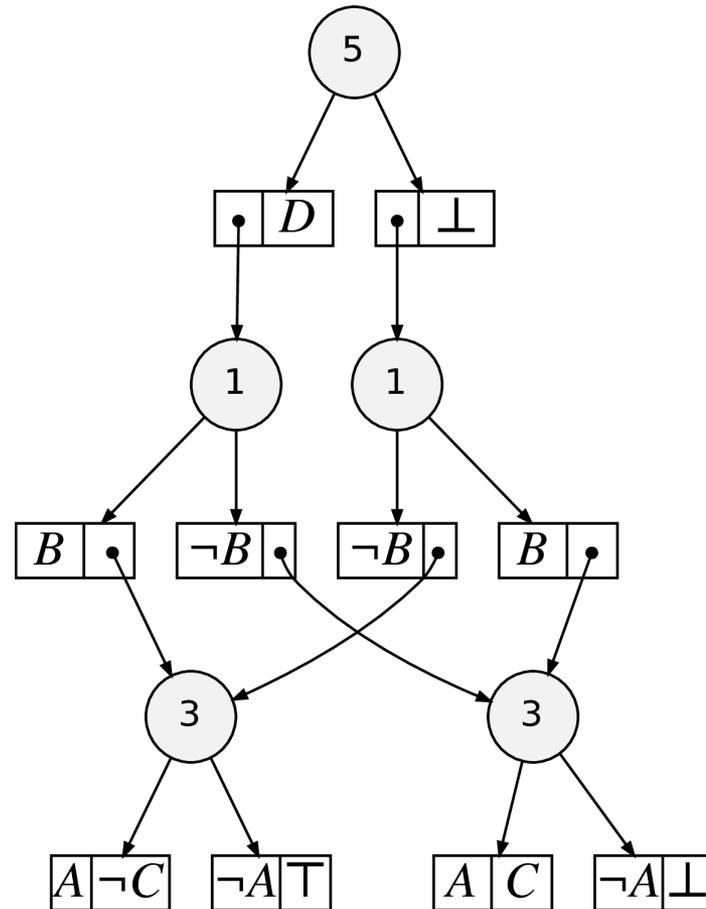
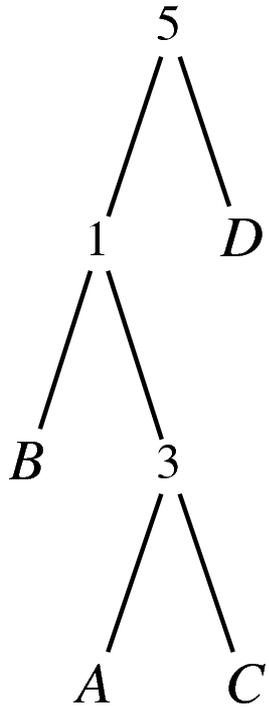


*ACBD*

# The SDD Package



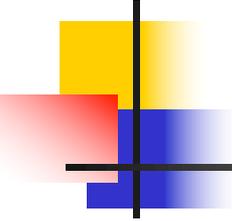
# The SDD Package



**The**

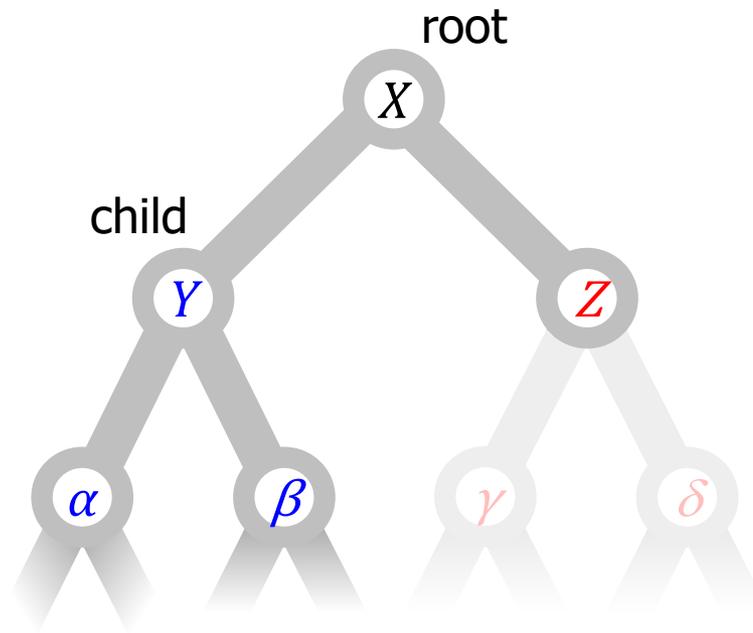
**Fragment Abstraction**

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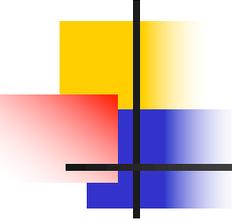


# Vtree Fragments

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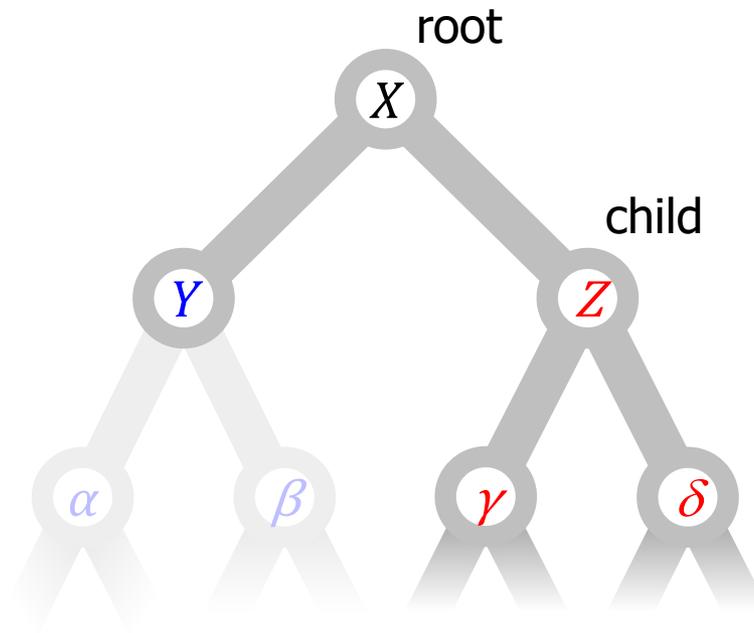


left-linear fragment

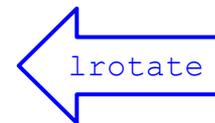
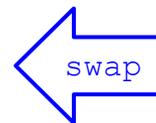
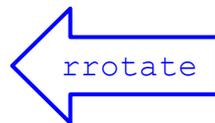
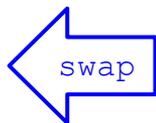
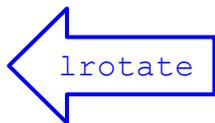
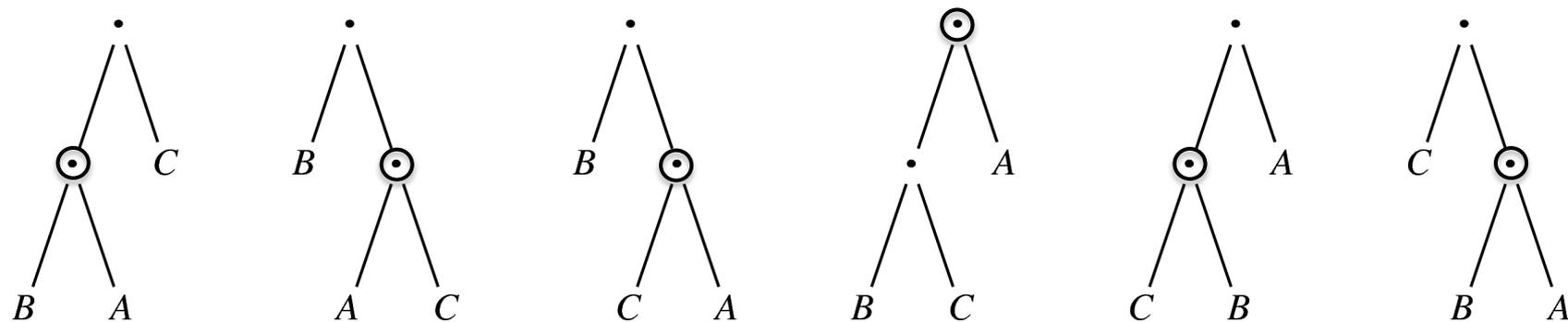
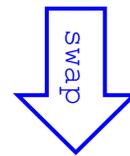
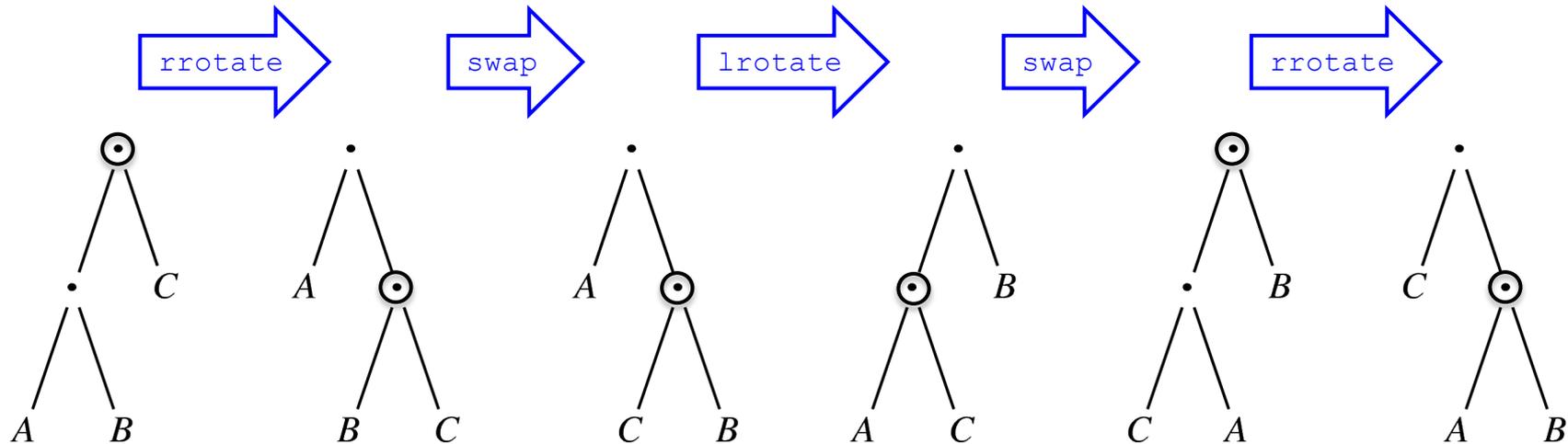


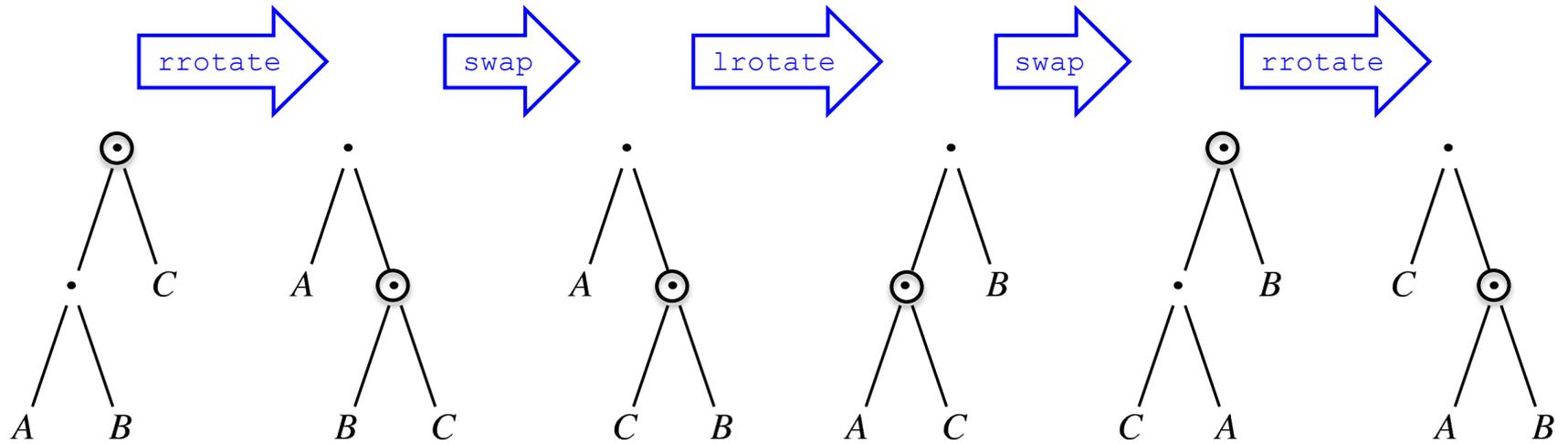
# Vtree Fragments

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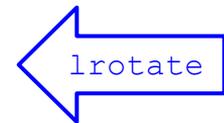
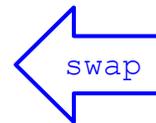
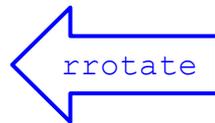
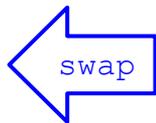
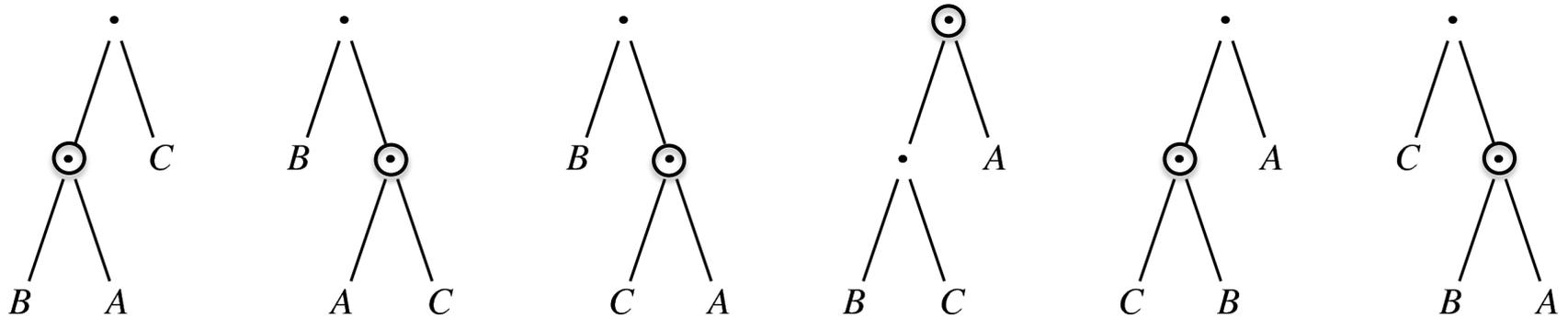
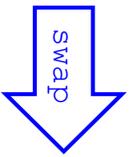


right-linear fragment



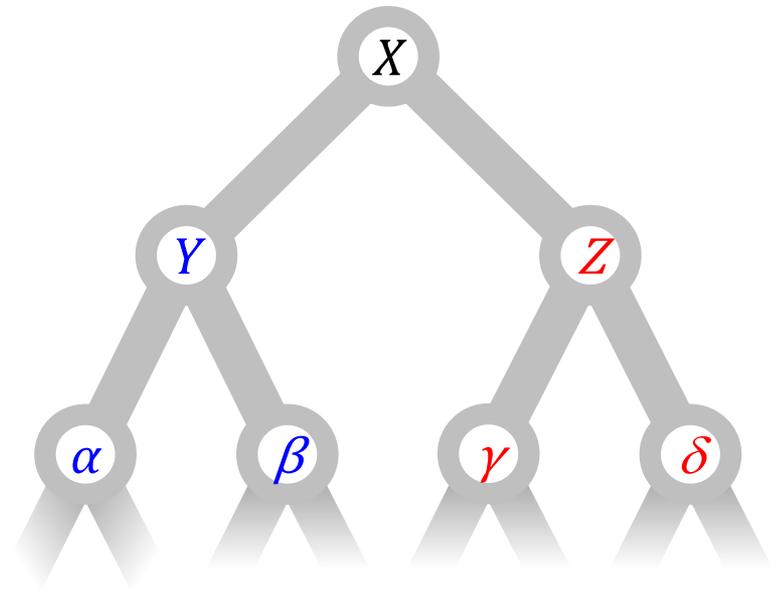


**Fragment Operations**  
Next, Previous, Goto, ...



# Greedy Vtree Search

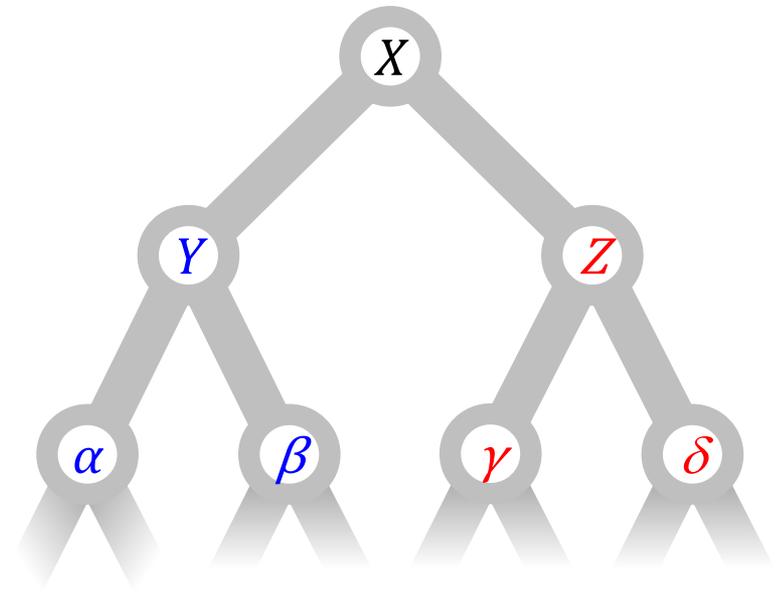
- Traverse vtree bottom-up
- Try enumerating 12 vtrees of left-linear fragment
- Try enumerating 12 vtrees of right-linear fragment
- 24 vtrees in total
- Greedily accept best vtree
- Prune parts of search space

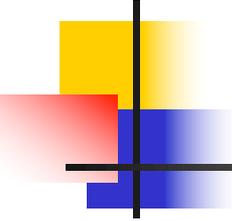


# The SDD Package

## Opportunities

- vtree search algorithms
- Triggers for vtree search
- Static methods for constructing vtrees
- Heuristics for scheduling Apply operations





# The SDD Package

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- <http://reasoning.cs.ucla.edu/sdd>
- Written in C
- Available as open-source
- Code for compiling CNFs/DNFs into SDDs (includes heuristic for scheduling Apply)
- Two manuals: beginner and advanced

# UCLA Automated Reasoning Group



4:30

**The Three Eras**

**Knowledge Representation and Reasoning**  
(models); logic  
AIGS

**Machine Learning**  
(models + functions); probability  
Statistical Optimisation

**Neural Networks**  
(functions); neural networks  
Engineering

12:15

**From Numbers to Decisions**

23:31

**Logic, Probability & Learning**

1:06:22



23:53

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