



Knowledge Compilers

Adnan Darwiche

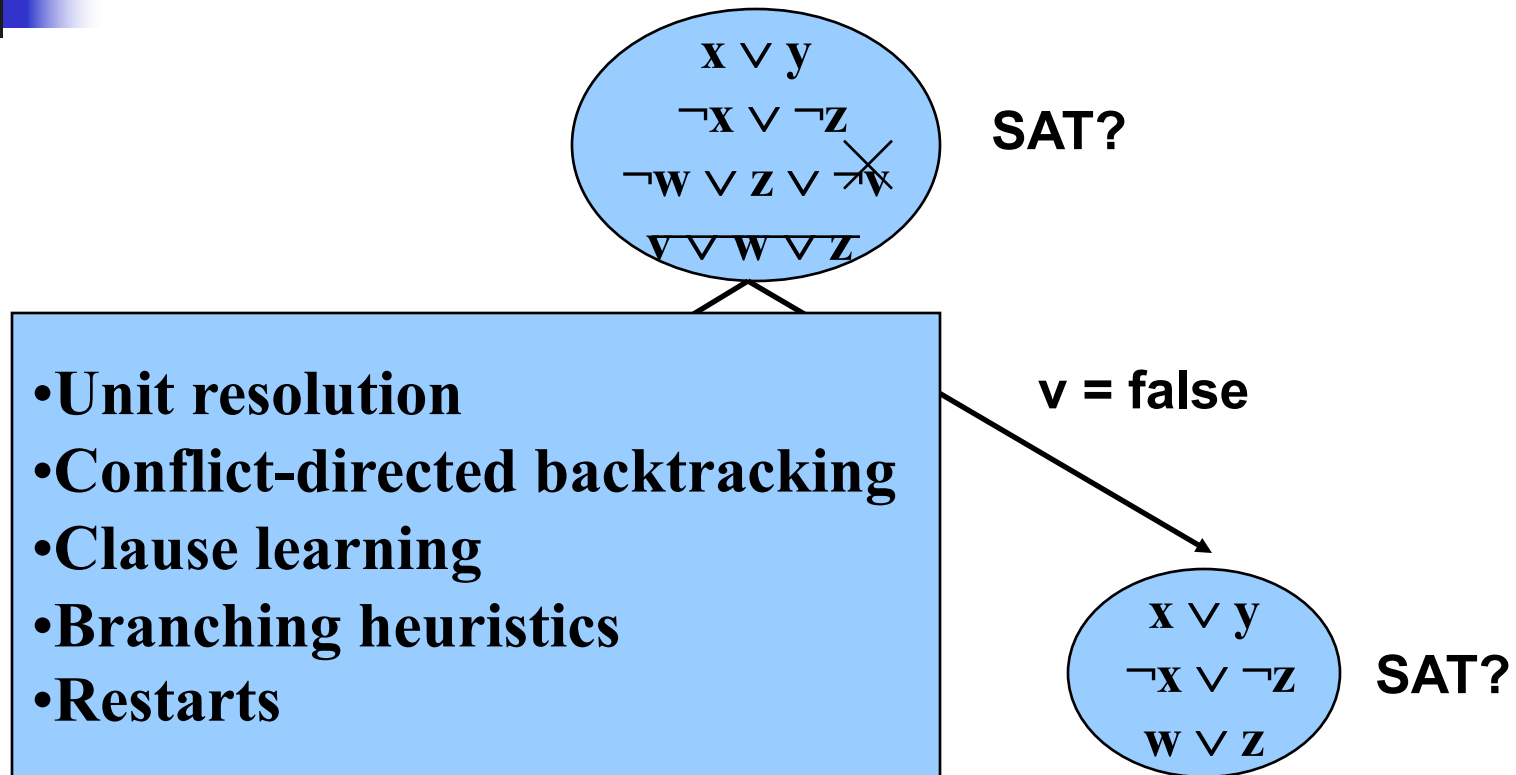
Computer Science Department, UCLA



Building Compilers

- To-down approaches:
 - Based on exhaustive search
- Bottom-up approaches:
 - Based on transformations

SAT by DPLL Search

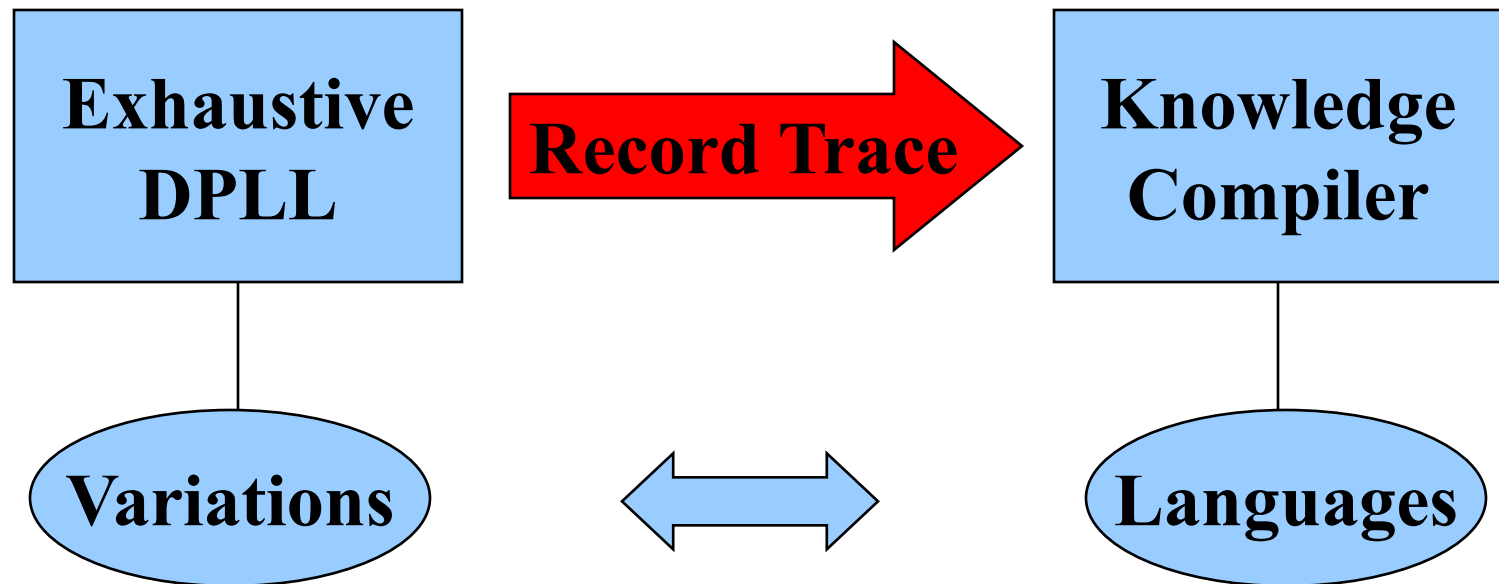


Terminating condition for recursion:

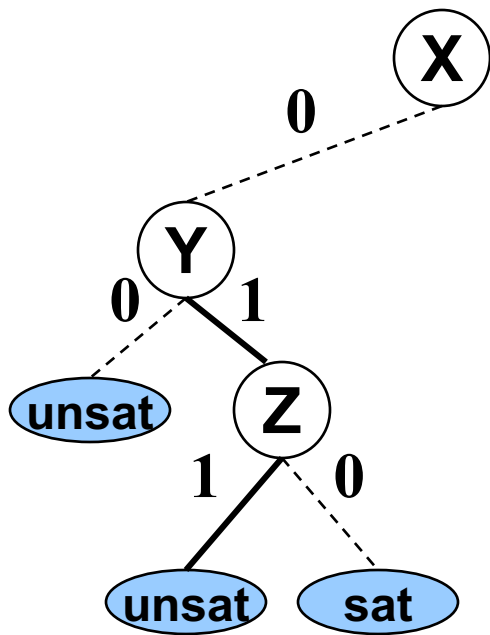
empty set (satisfied), or empty clause (contradiction)



The Language of Search



Trace of DPLL



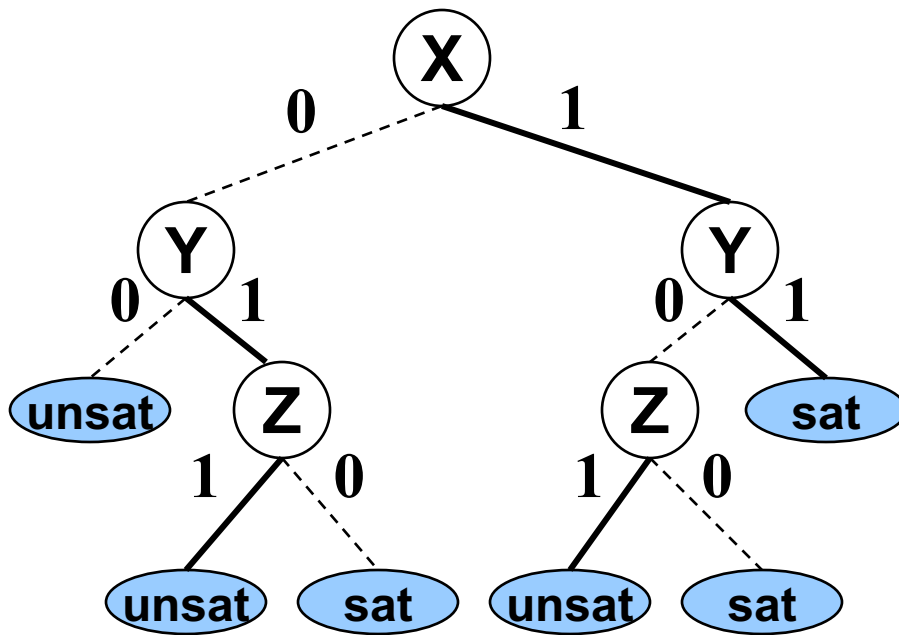
$$X \vee Y$$

$$X \vee \neg Y \vee \neg Z$$

$$\neg X \vee Y \vee \neg Z$$

Exhaustive DPLL

Run to Exhaustion

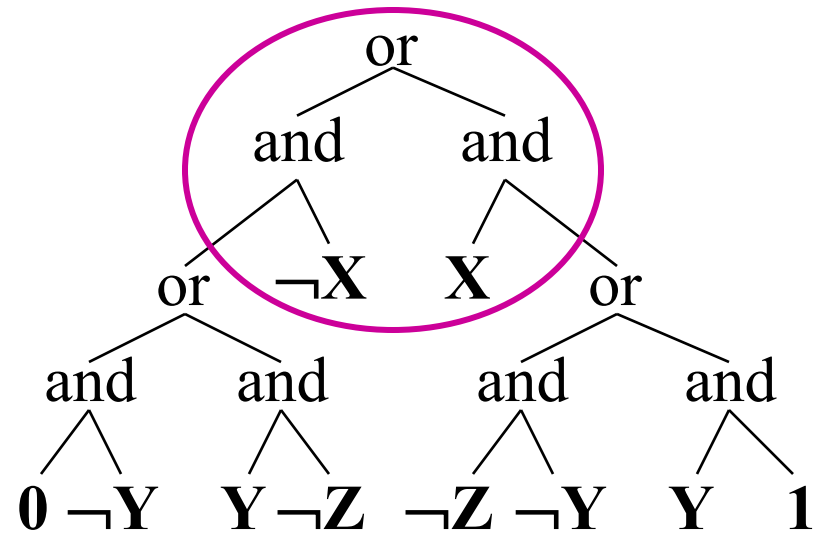
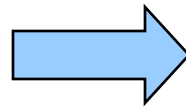
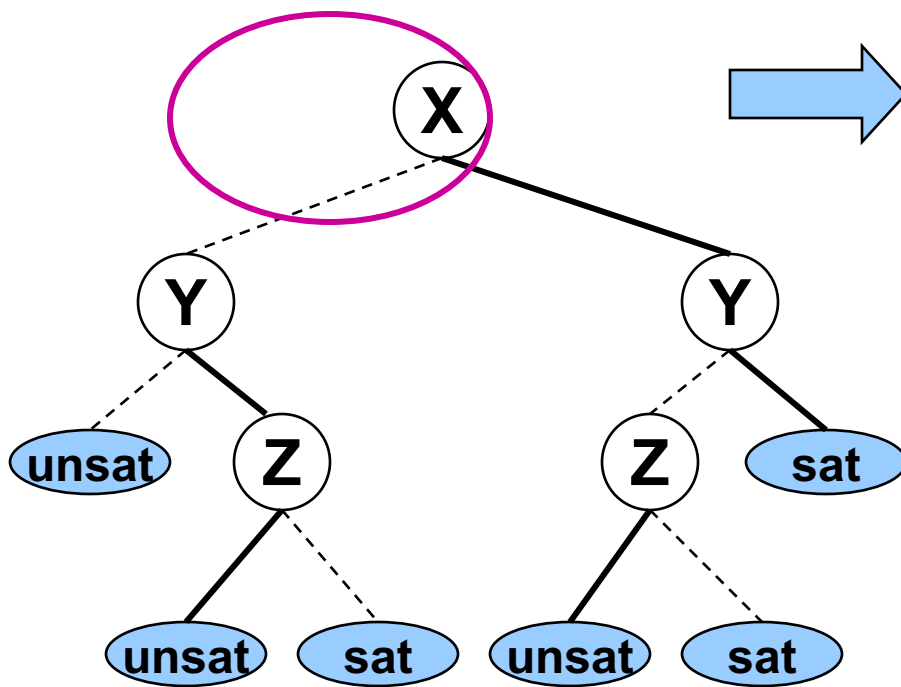


$$X \vee Y$$

$$X \vee \neg Y \vee \neg Z$$

$$\neg X \vee Y \vee \neg Z$$

Trace of DPLL: a Formula

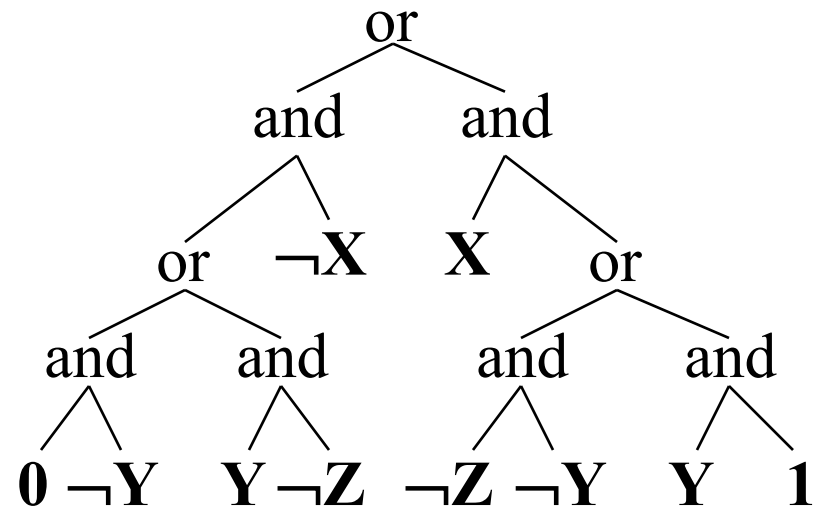




Trace of DPLL: a Formula

**Equivalent to
original CNF**

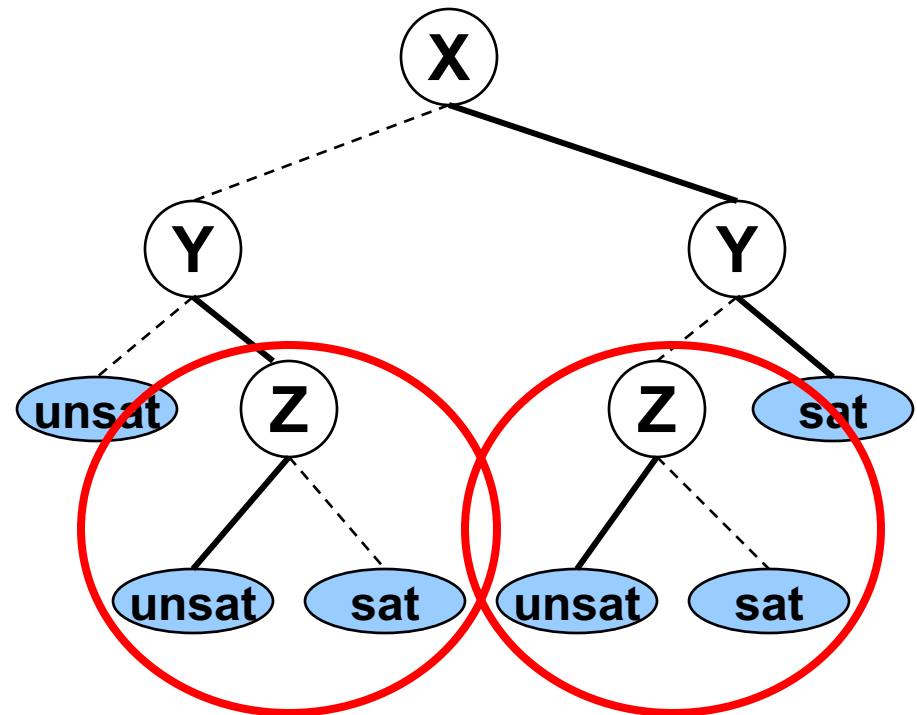
Tractable
(e.g., count models)



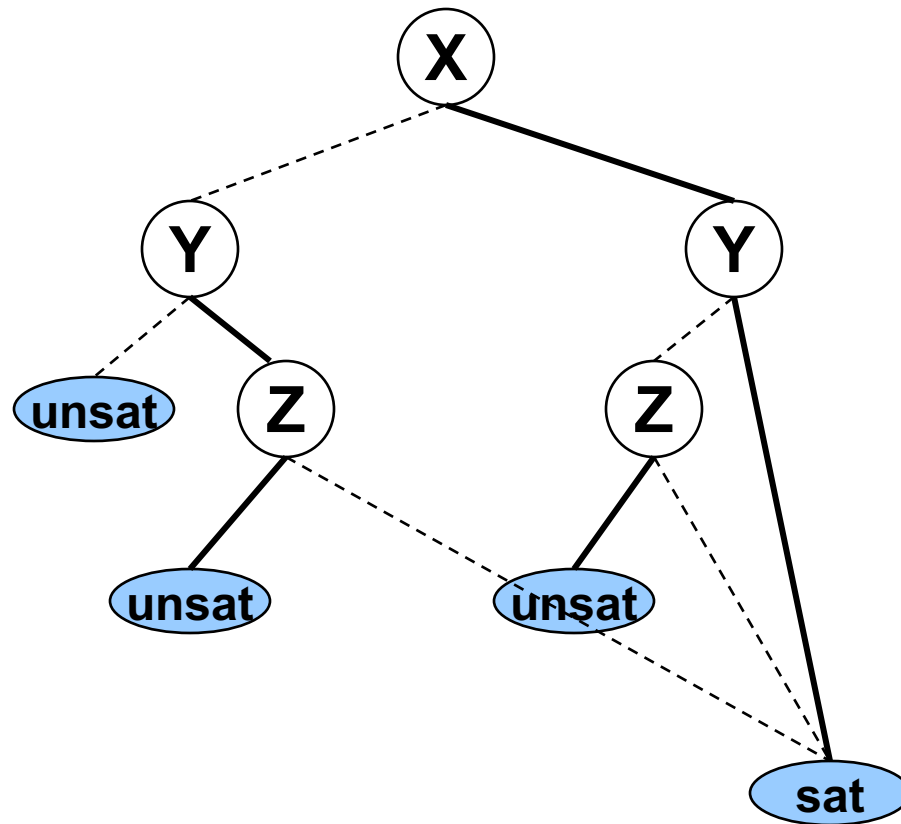
Dealing with Redundancy

Level One: Do not record redundant portions of trace

Level Two: Try not to solve equivalent subproblems

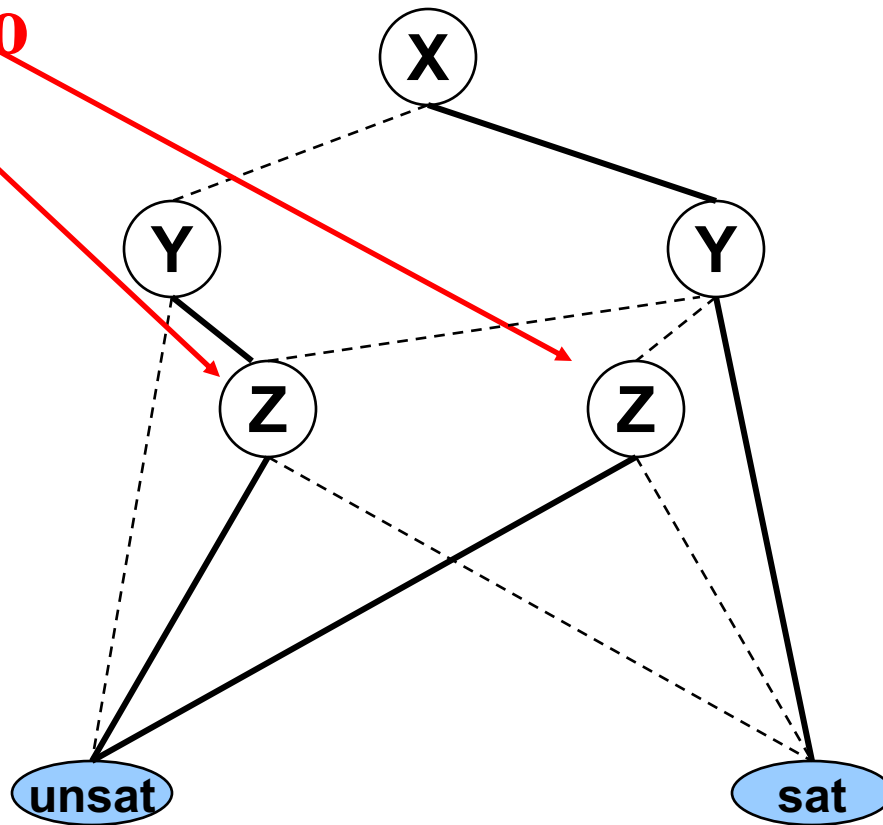


Dealing with Redundancy



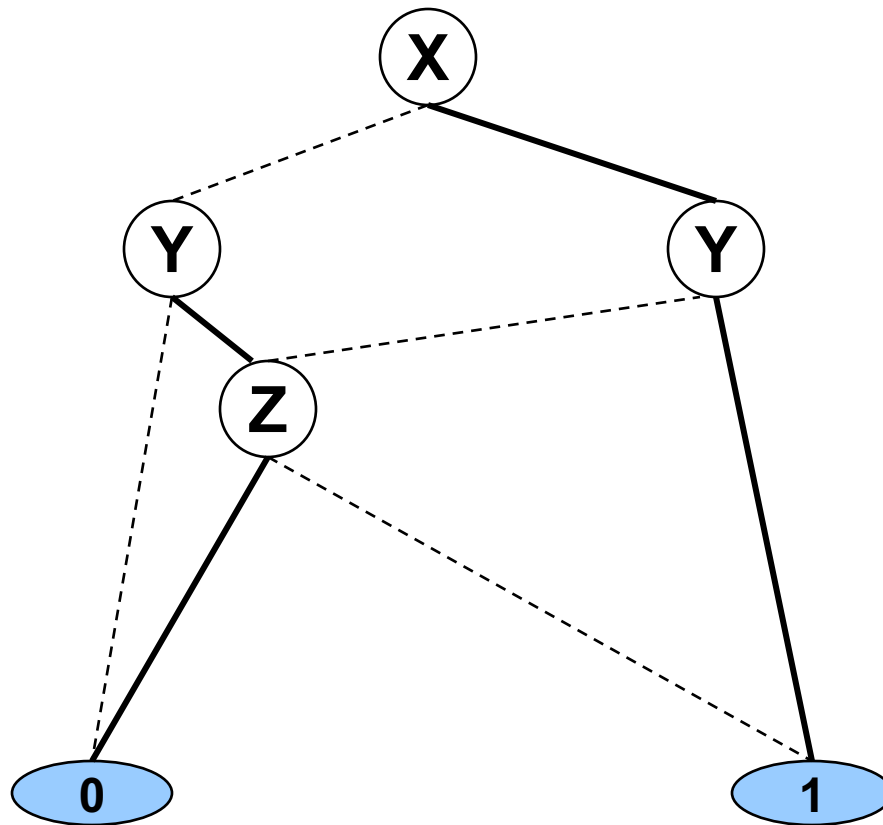
Dealing with Redundancy

**Simply create to
existing node**



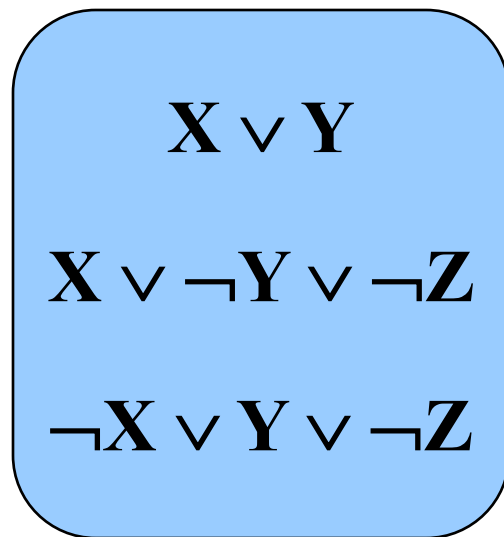


This is an OBDD!



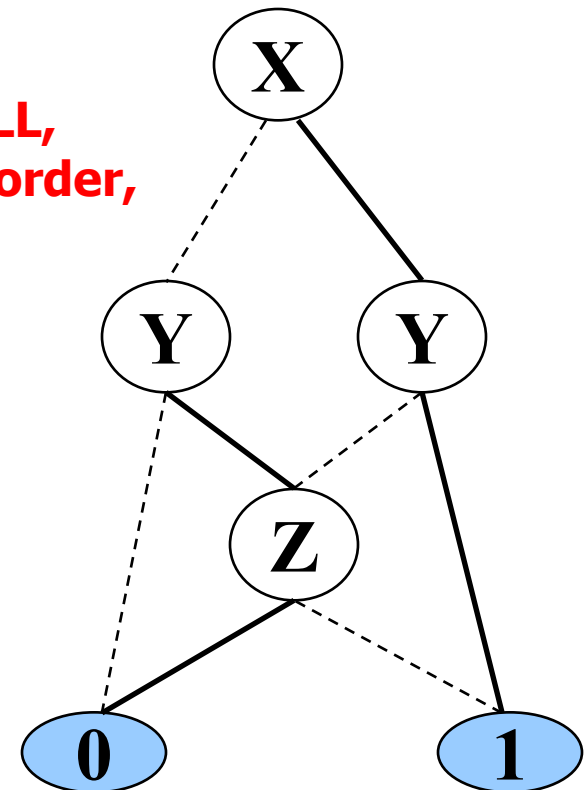


A Non-traditional OBDD Compiler



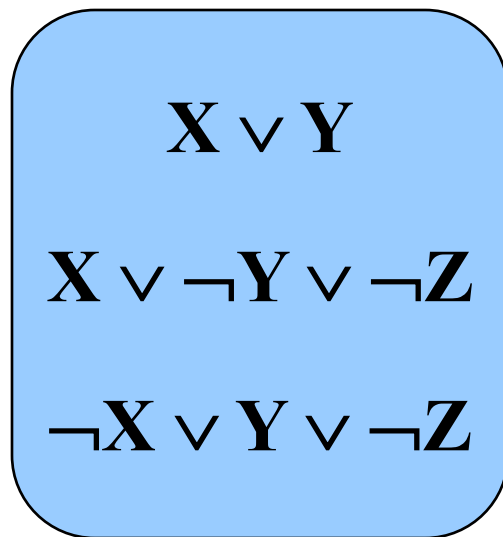
Exhaustive DPLL,
Fixed variable order,
Unique nodes

Compile



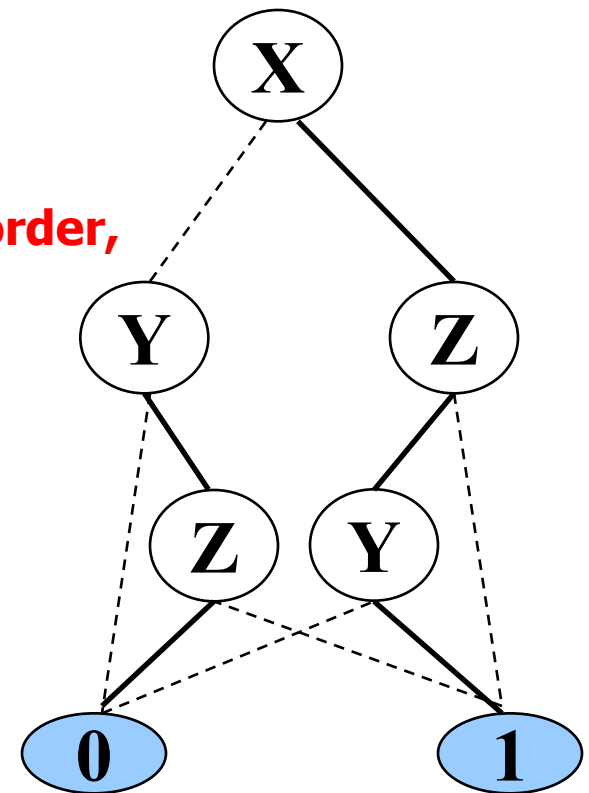
New complexity guarantees

FBDD



Exhaustive DPLL,
Dynamic variable order,
Unique nodes

Compile



NNF + decision, decomposability



Dealing with Redundancy

- **Level One: Unique nodes (done)**
- **Level Two: Avoid redundant compilation (searches)**

Redundant Compilation

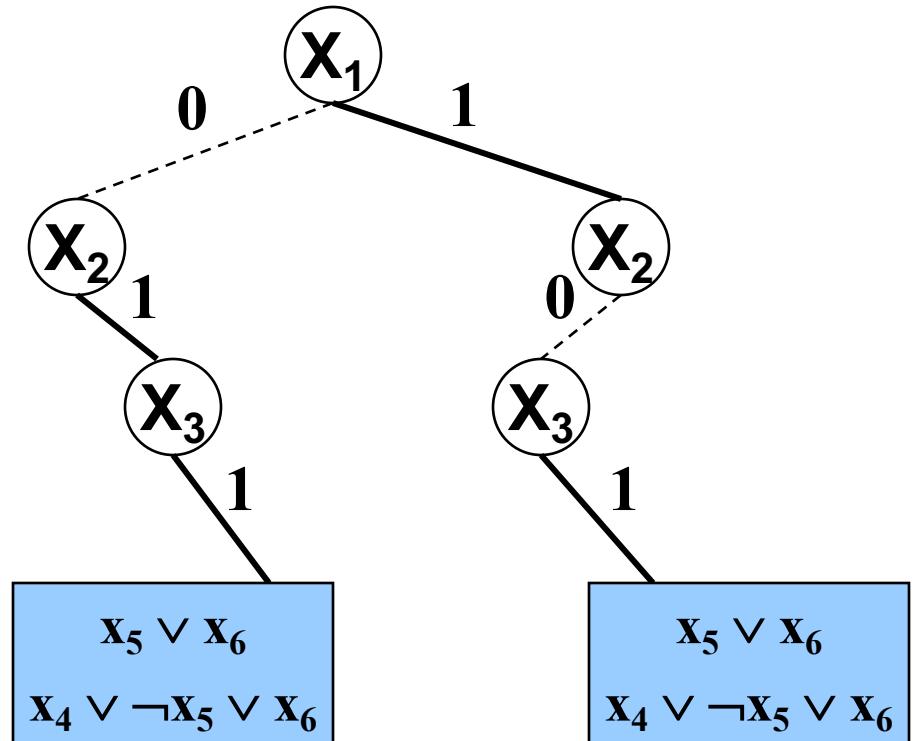
$$x_5 \vee x_6$$

$$x_4 \vee \neg x_5 \vee x_6$$

$$x_1 \vee x_3 \vee x_4 \vee x_5$$

$$x_2 \vee x_3$$

$$x_1 \vee x_2 \vee \neg x_3$$



Formula Caching: complexity guarantees



Beyond BDDs...

Plain DPLL



FBDD

**Fixed Variable
Ordering**

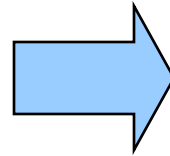


OBDD



Decomposition (Component Analysis)

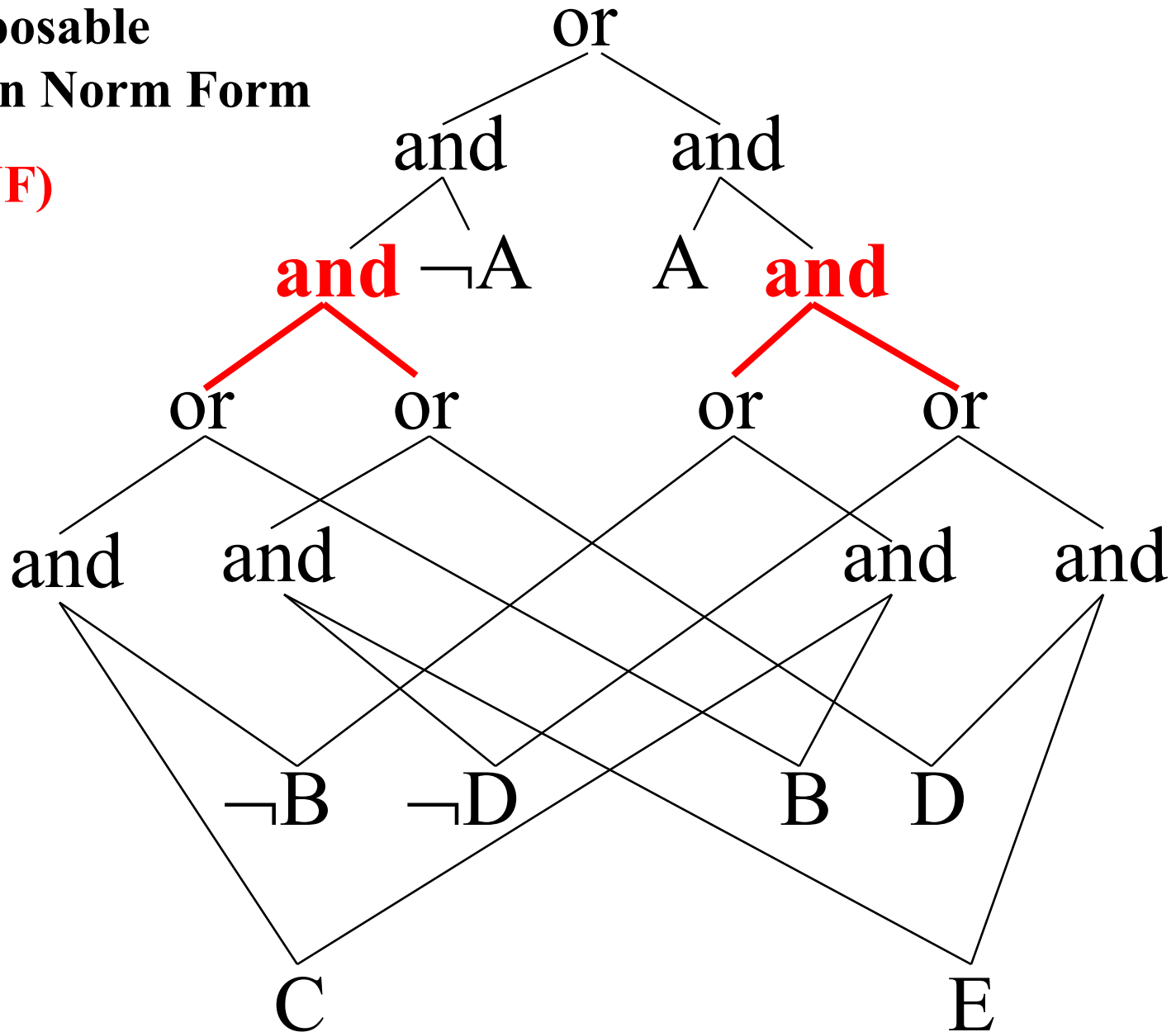
**Solve disjoint
subproblems
independently**



d-DNNF

**Combine as
AND node**

Deterministic
Decomposable
Negation Norm Form
(d-DNNF)





Decomposition Strategies

- Static (c2d)
 - Hypergraph partitioning pre-compilation
 - Strategy captured using a dtree (decomposition tree)
- Dynamic (Dsharp/Cachet)
 - Dynamic variable orderings
 - Lazy detection of decompositions
- Mixed (D4)
 - Hypergraph partitioning during compilation
 - Done selectively (using dtrees)



The Language of Search

**Fixed Variable
Ordering**



OBDD

Plain DPLL



FBDD

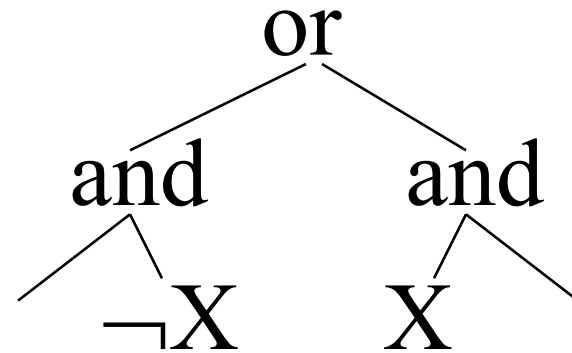
**Allowing
Decomposition**



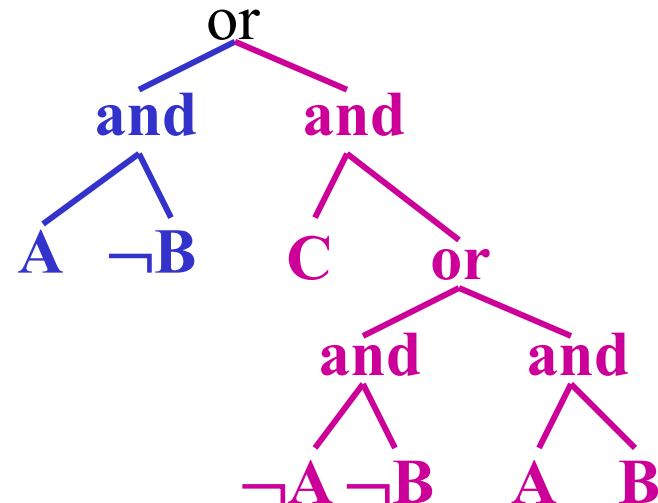
d-DNNF

Limitation of DPLL: General determinism

**Decision nodes
(Decision-DNNF)**



**Deterministic nodes
(d-DNNF)**

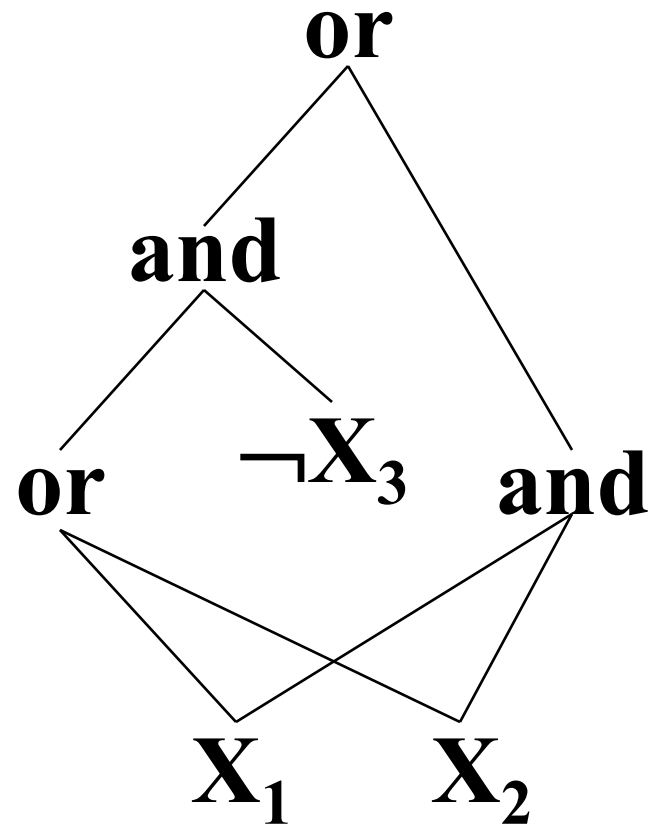


Beyond DPLL:

Decomposability (D) without
determinism (d)

DNNF:

CO, CE, ME,
exist quantification





Bottom-up Compilation



Bottom-up Compilation

CNF: $(x + y) (y + z)$

Variable order: x, y, z



Bottom-up Compilation

CNF: $(x + y) (y + z)$

Variable order: x, y, z

Apply:

combines two OBDDs
using Boolean operators

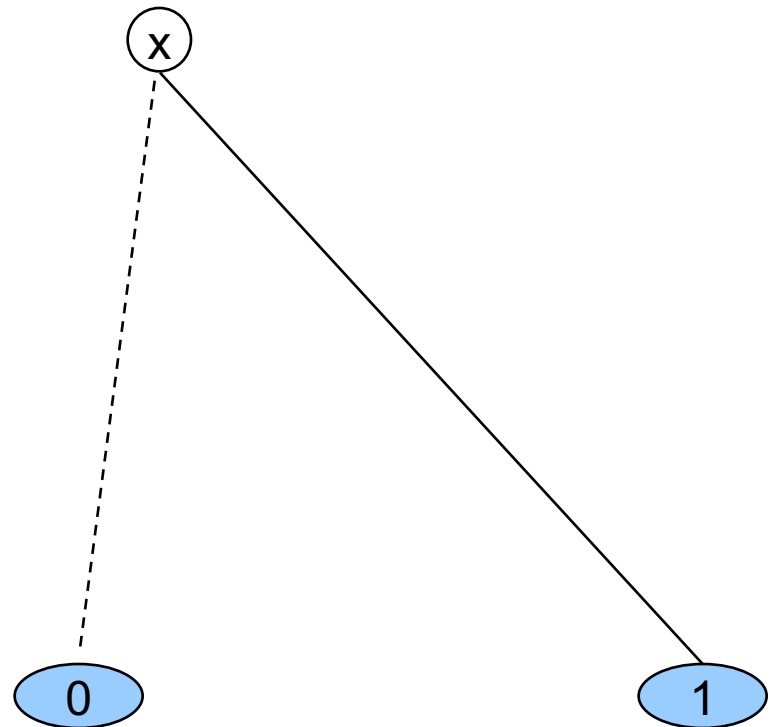
Bottom-up Compilation

CNF: $(x + y) (y + z)$

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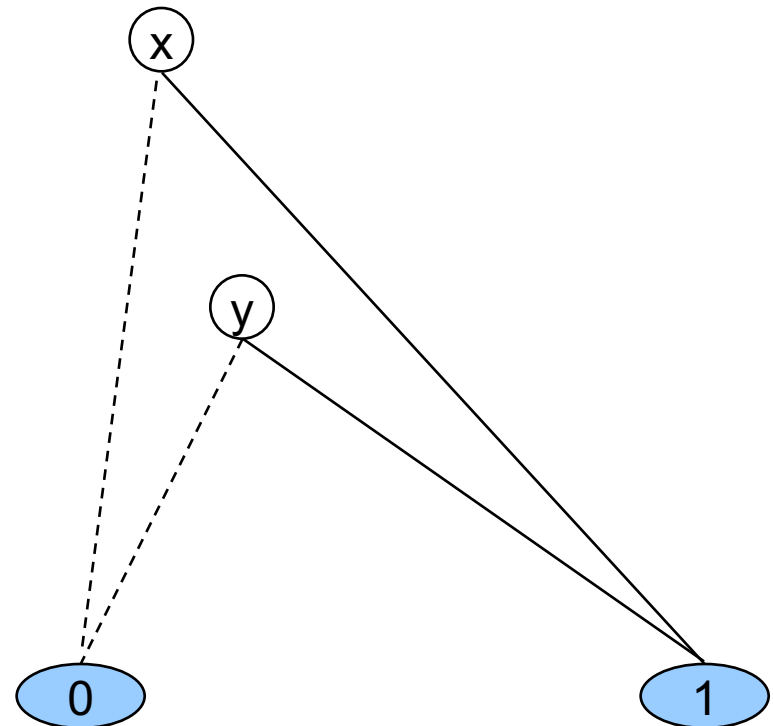
Bottom-up Compilation

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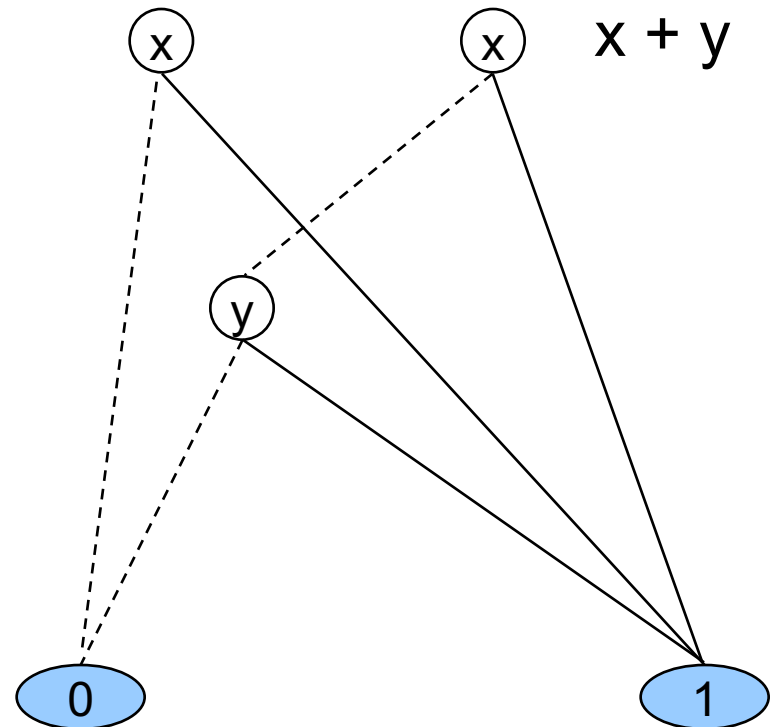
Bottom-up Compilation

CNF: $(x + y) (y + z)$

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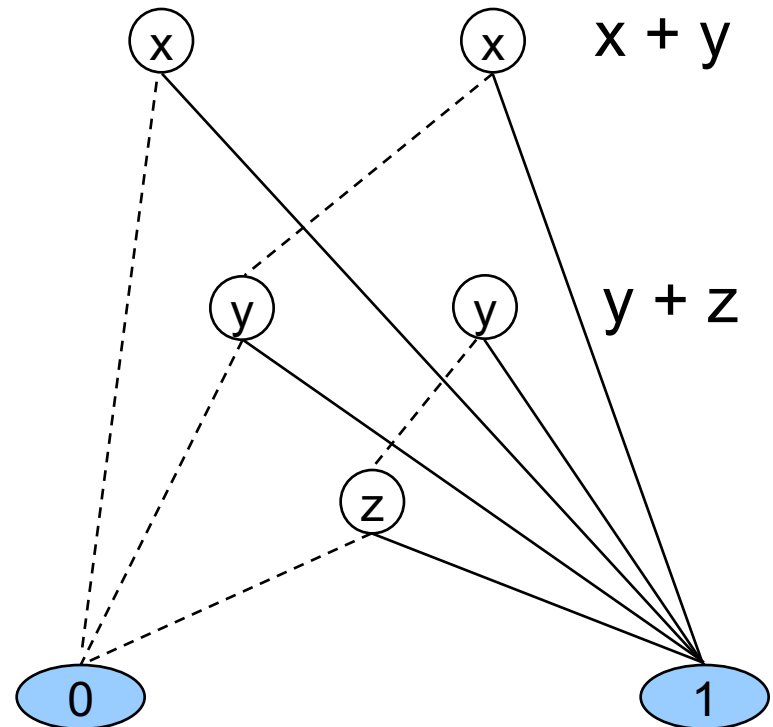
Bottom-up Compilation

CNF: $(x + y) (y + z)$

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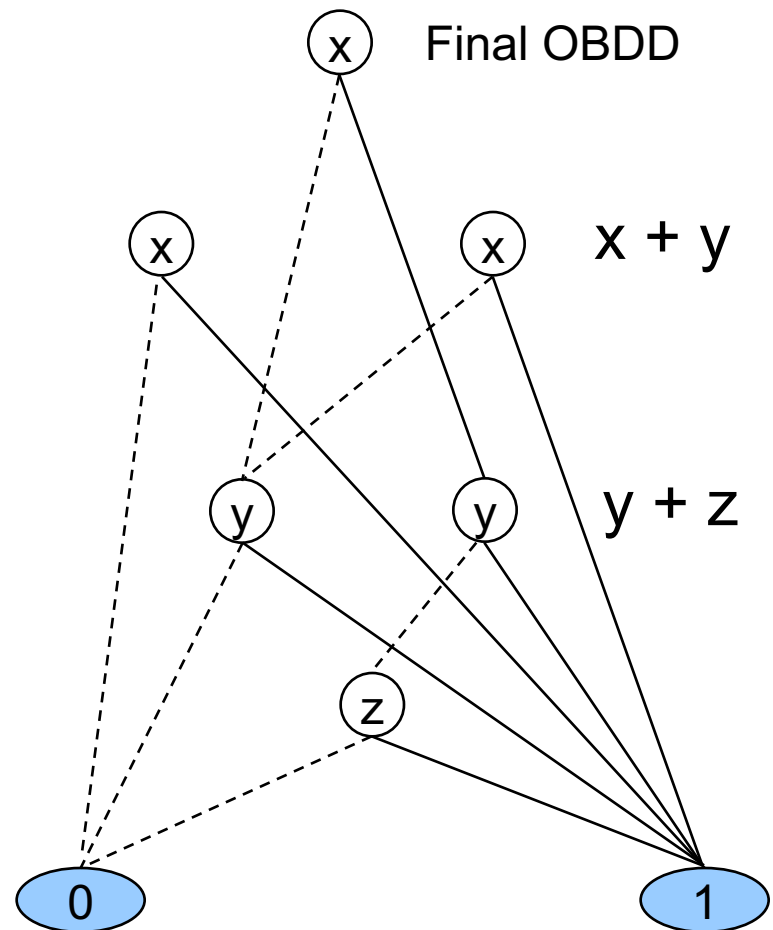
Bottom-up Compilation

CNF: $(x + y) (y + z)$

Variable order: x, y, z

Apply:

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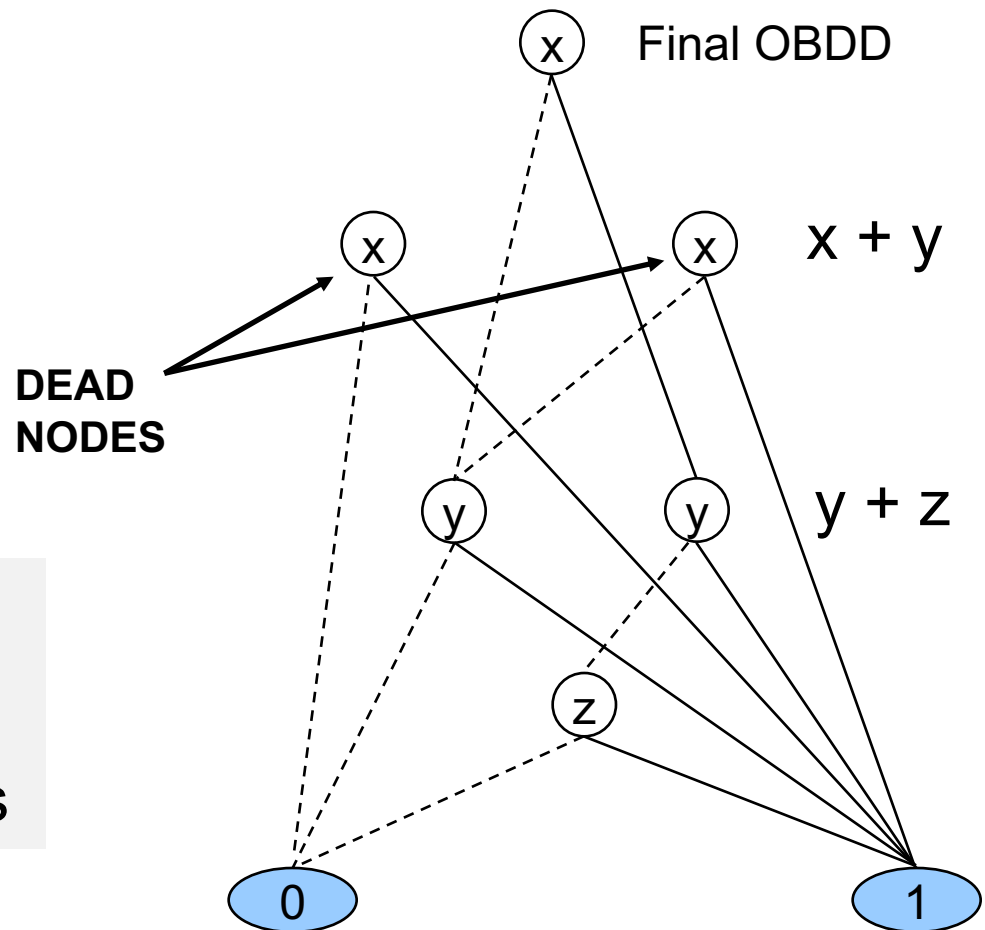
Bottom-up Compilation

CNF: $(x + y) (y + z)$

Variable order: x, y, z

Apply:

combines two OBDDs
using Boolean operators





Bottom-up Compilation

- Requires:
 - *Apply* (conjoin, disjoin, etc)
 - Garbage collection of dead nodes
- Challenges:
 - Good variable order
 - Good schedule of Apply operations
- uf100-08 (32 models):
 - 176 nodes in final OBDD under MINCE variable order
 - 30,640,582 intermediate nodes using CUDD package



Canonicity in Compilation

- OBDDs are canonical
variable order \rightarrow unique OBDD

(reduced OBDDs)

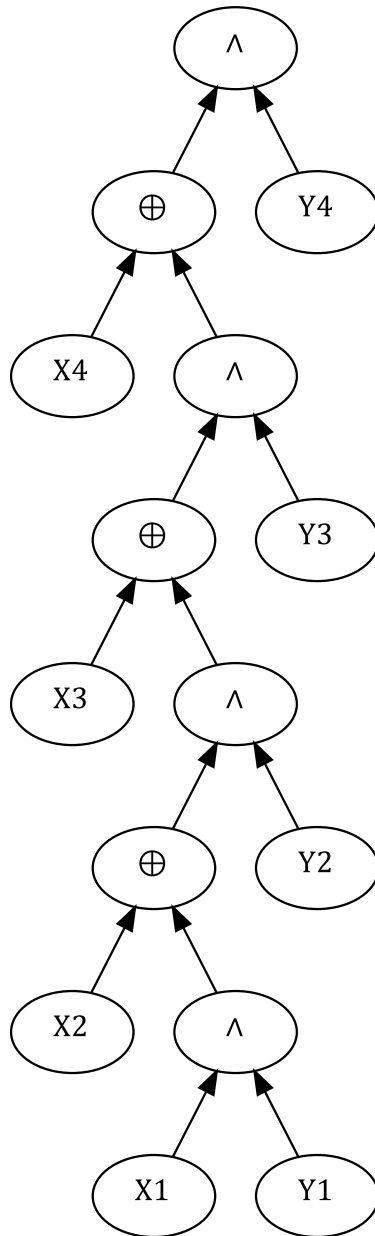
- SDDs are canonical
vtree \rightarrow unique SDD

(trimmed and compressed SDDs)



Vtrees Matter!

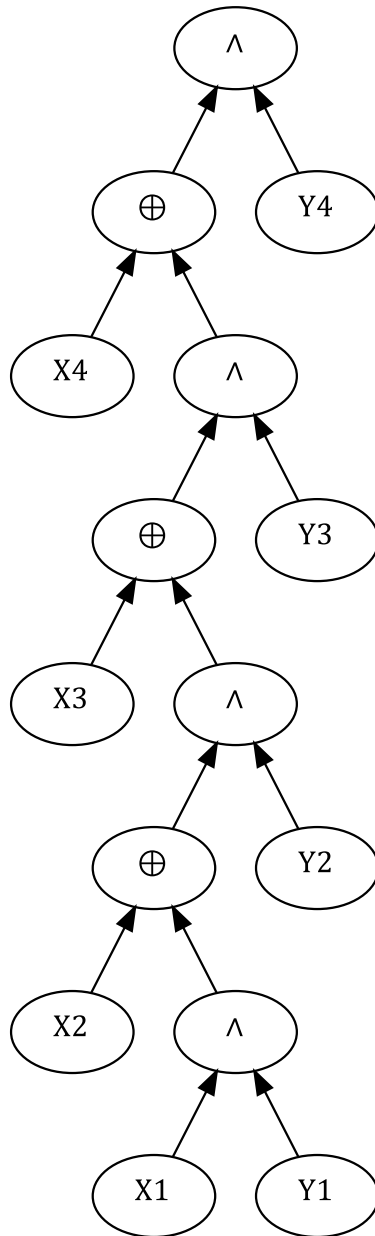
- A vtree can have a significant impact on the size of an SDD
- Good vtrees can be obtained either
 - **Statically**: by analyzing the Boolean function structure before compilation
 - **Dynamically**: by searching for an appropriate vtree during compilation



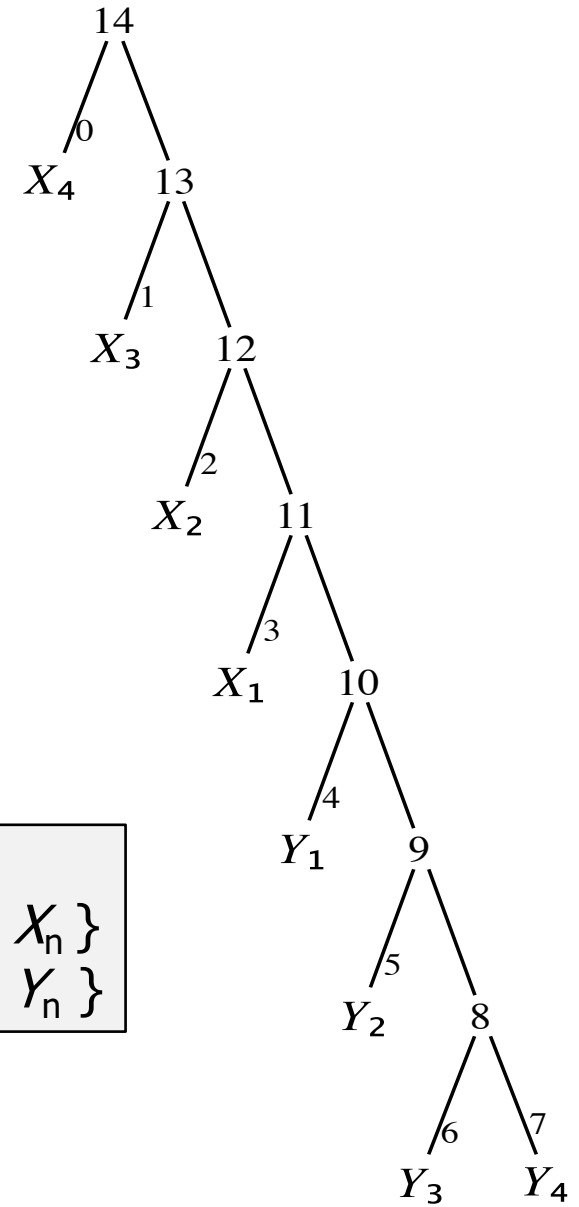
variables

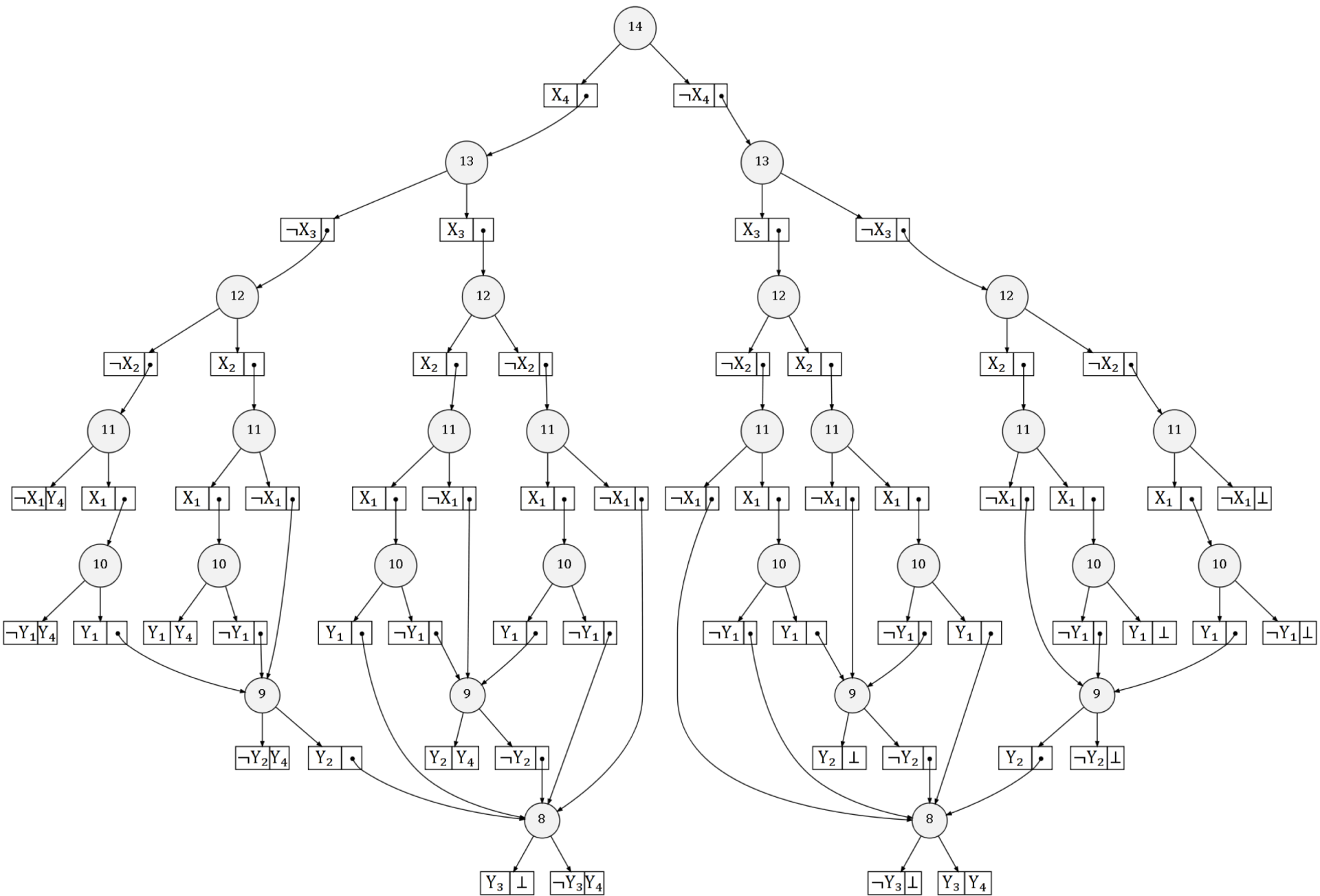
X = { X_1 X_2 X_3 ... X_n }

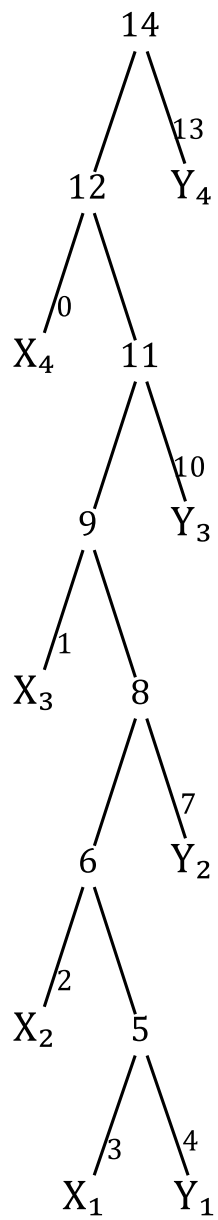
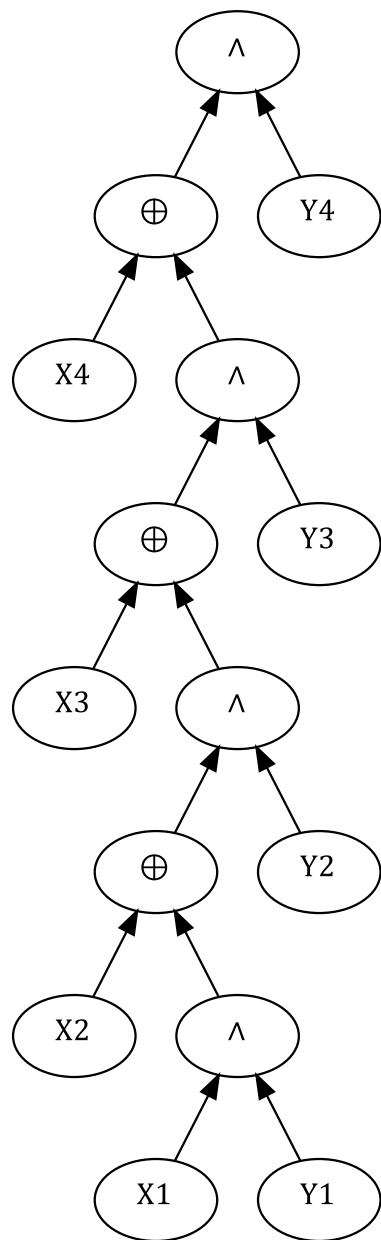
Y = { Y_1 Y_2 Y_3 ... Y_n }

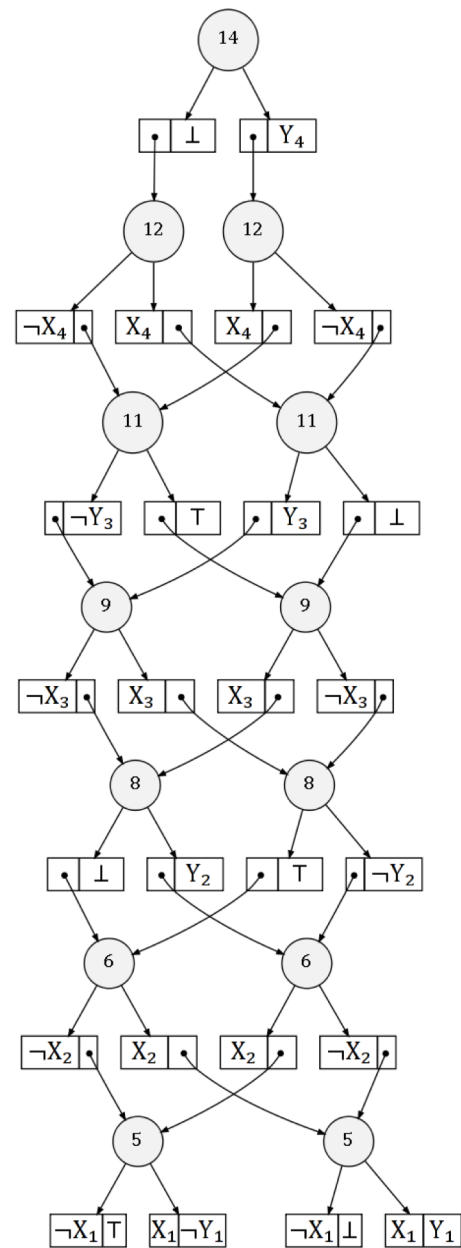
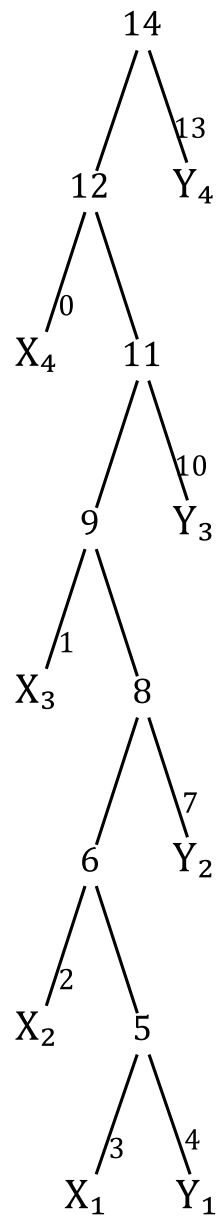
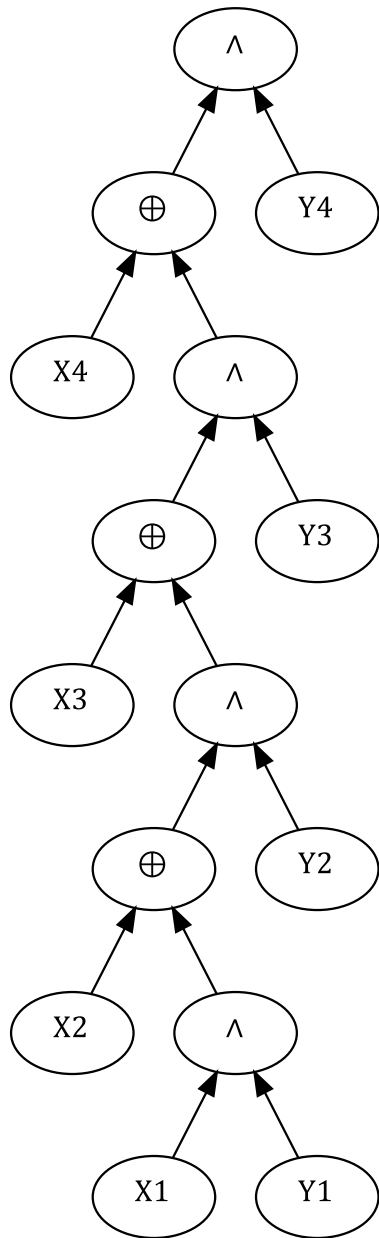


variables
 $\mathbf{X} = \{ X_1 X_2 X_3 \dots X_n \}$
 $\mathbf{Y} = \{ Y_1 Y_2 Y_3 \dots Y_n \}$







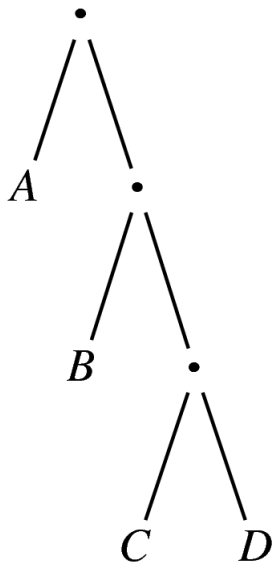


Vtree Search: Minimizing SDD Size

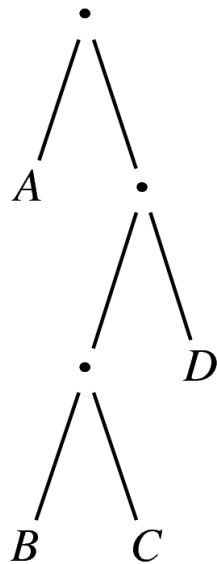




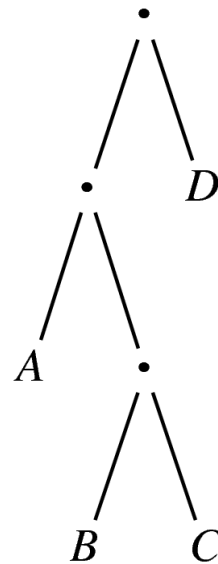
Dissecting Variable Orders



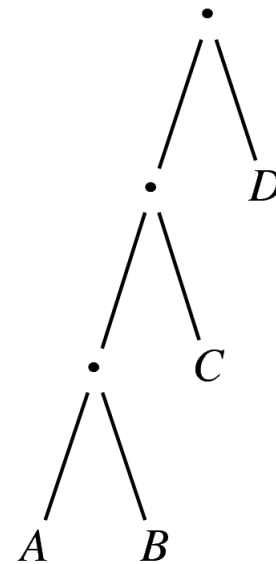
ABCD



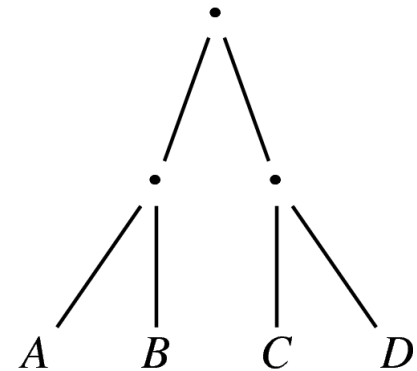
ABCD



ABCD



ABCD



ABCD



Vtrees Matter!

- The choice of a vtree can lead to exponential difference in the size of an SDD
- The choice of a dissection can also lead to exponential differences in the size of an SDD

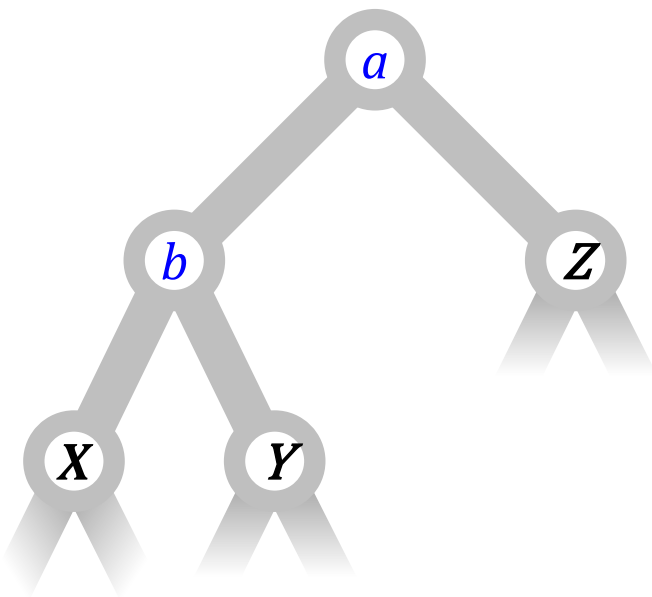


Searching Over Vtrees

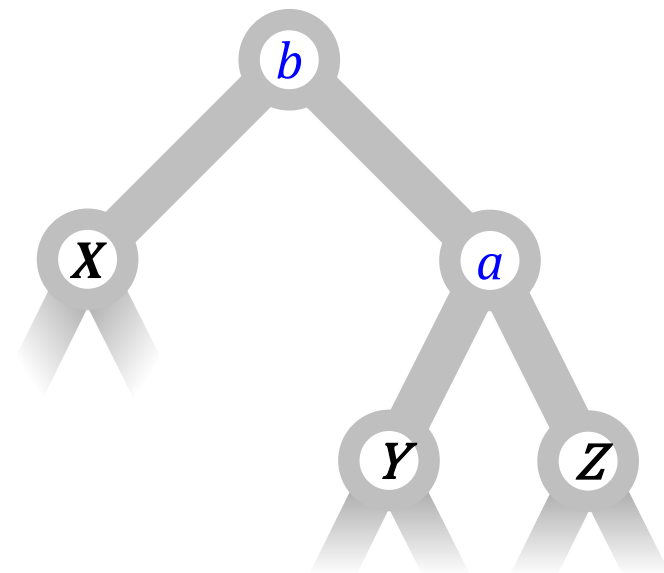
- Double search problem:
 - Find variable order
 - Find dissection
- Tree operations:
 - Rotation (left, right)
 - Swapping
- Can enumerate all vtrees



Tree Rotations



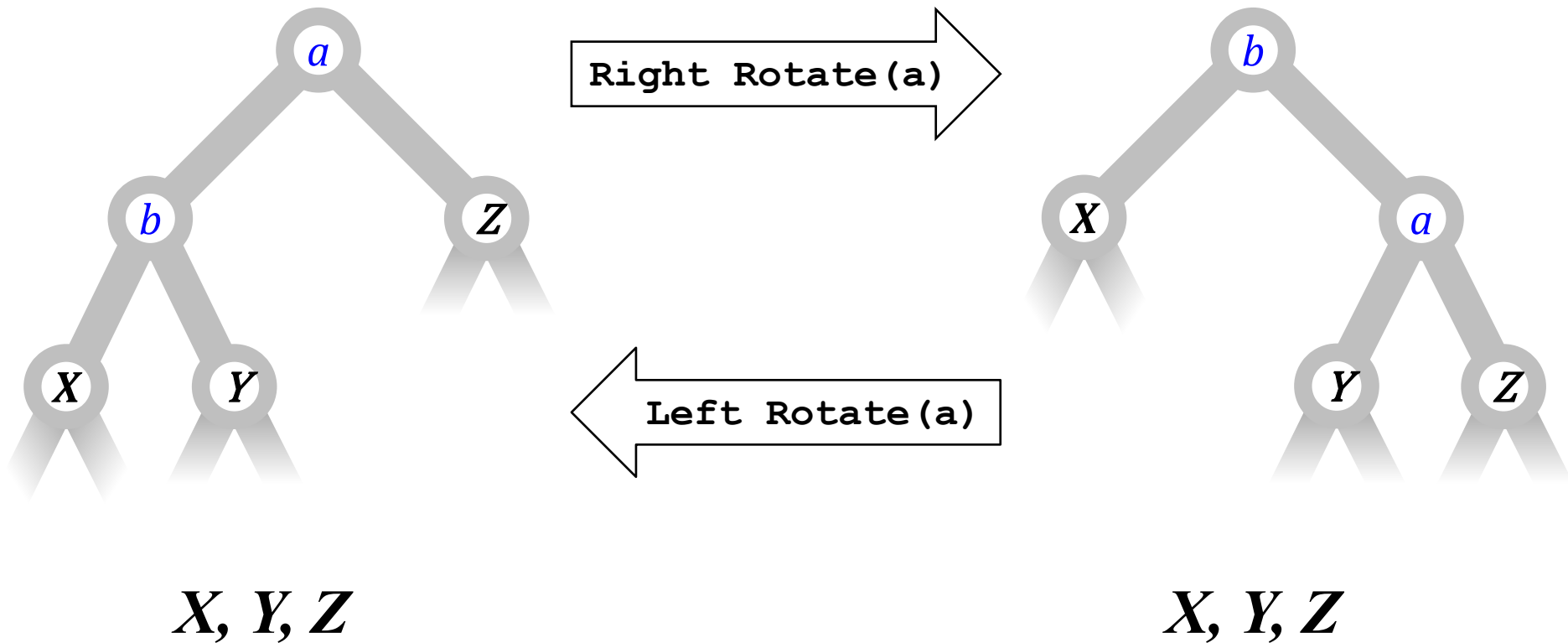
Right Rotate (*a*)



Left Rotate (*a*)



Rotation Preserves Order

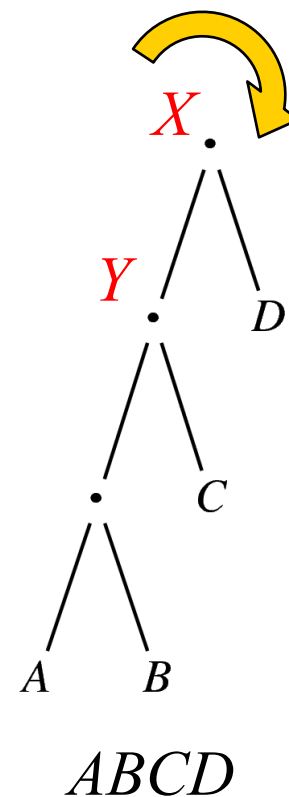
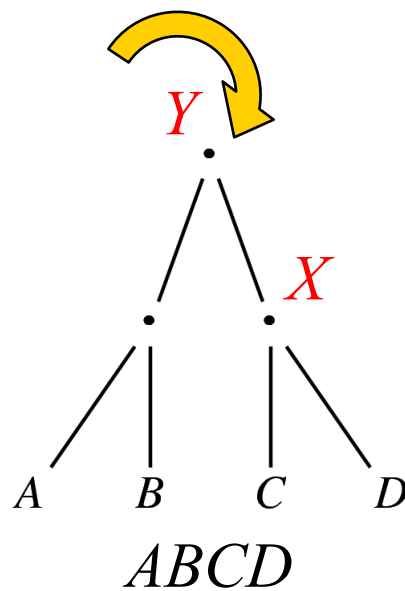
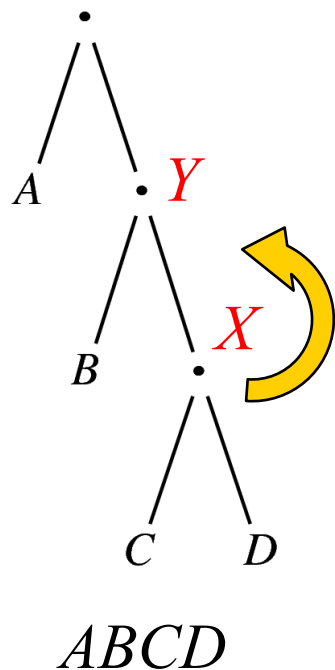
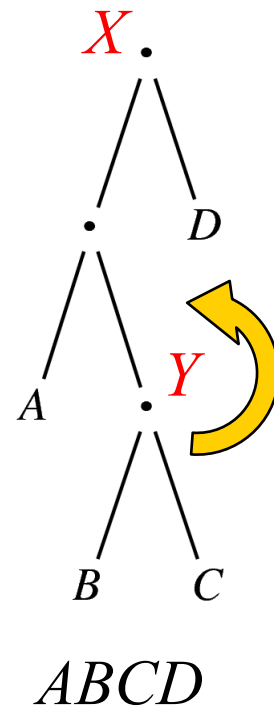
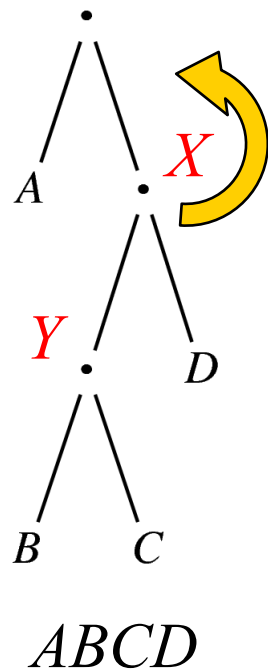




Enumerating Dissections

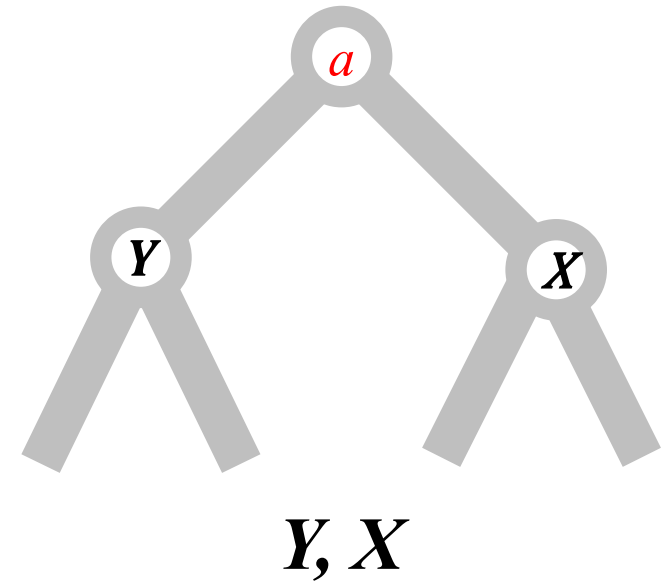
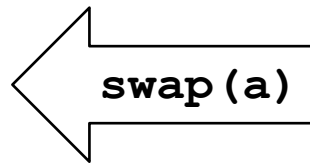
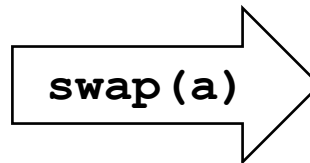
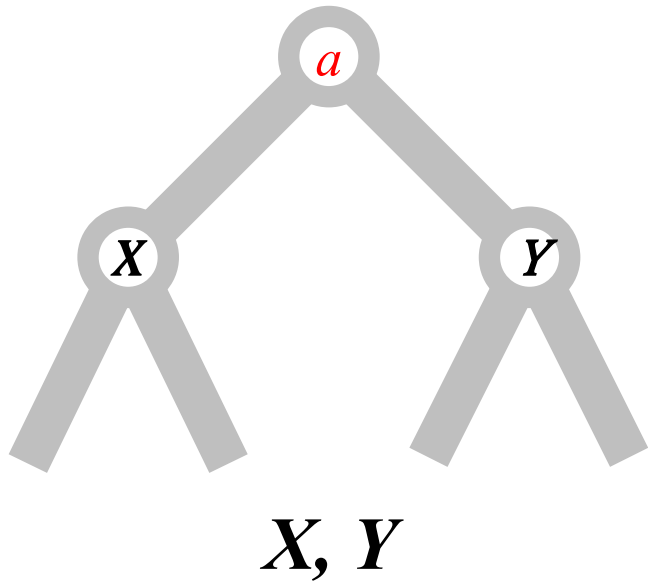
- Rotations can enumerate all dissection of a given variable order
- Systematic methods exist for this purpose
- See, e.g., Knuth's

Art of Computer Programming, Volume 4, Fascicle 4: Generating All Trees

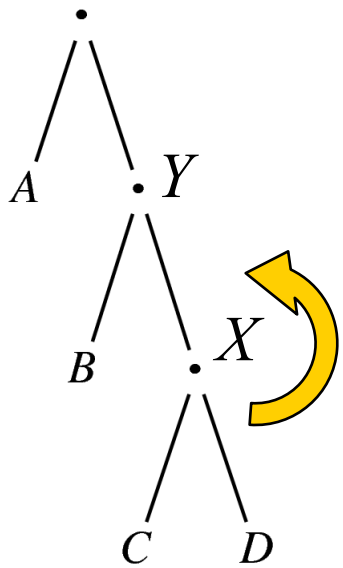




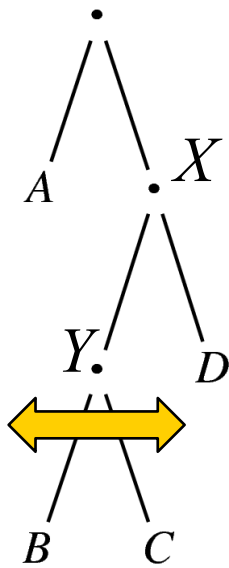
Swapping Changes Order



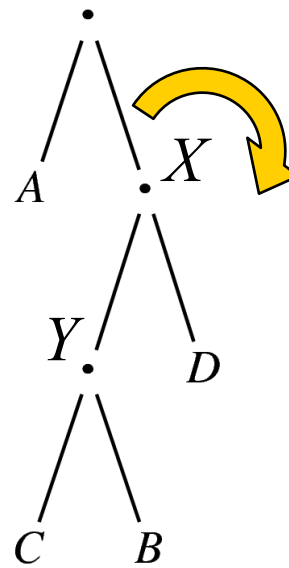
Rotate + Swap



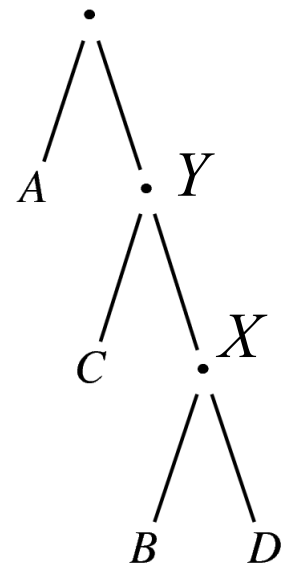
$ABCD$



$ABCD$

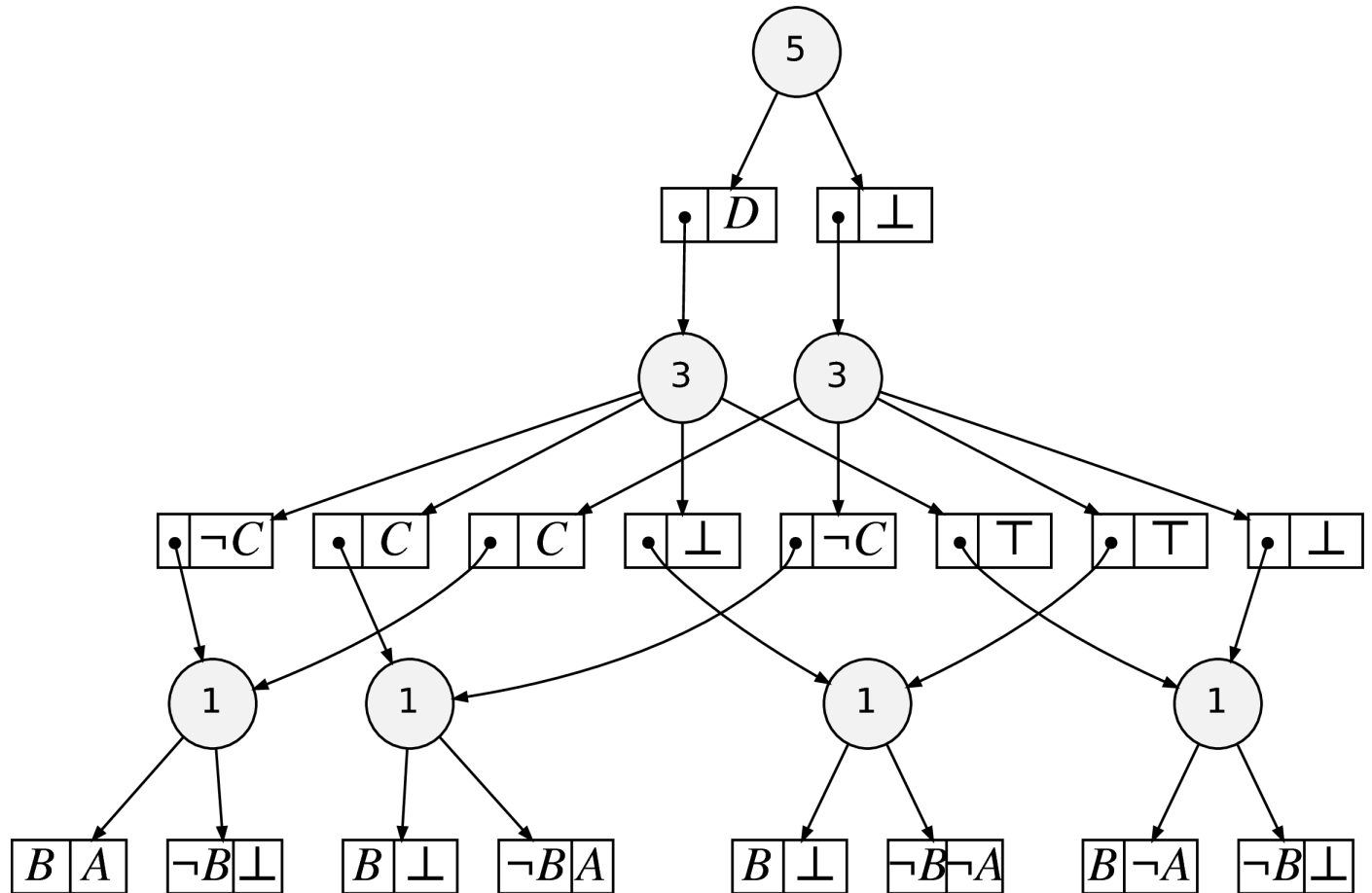
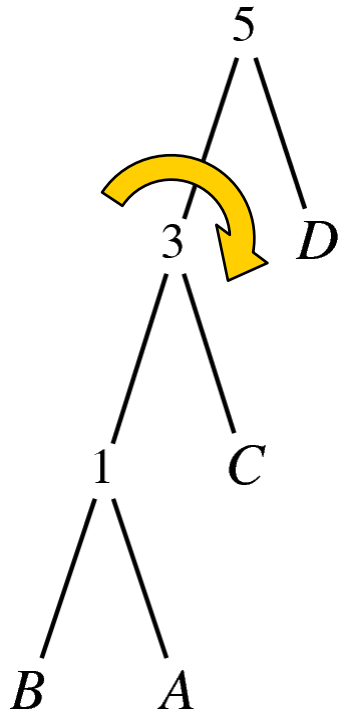


$ACBD$

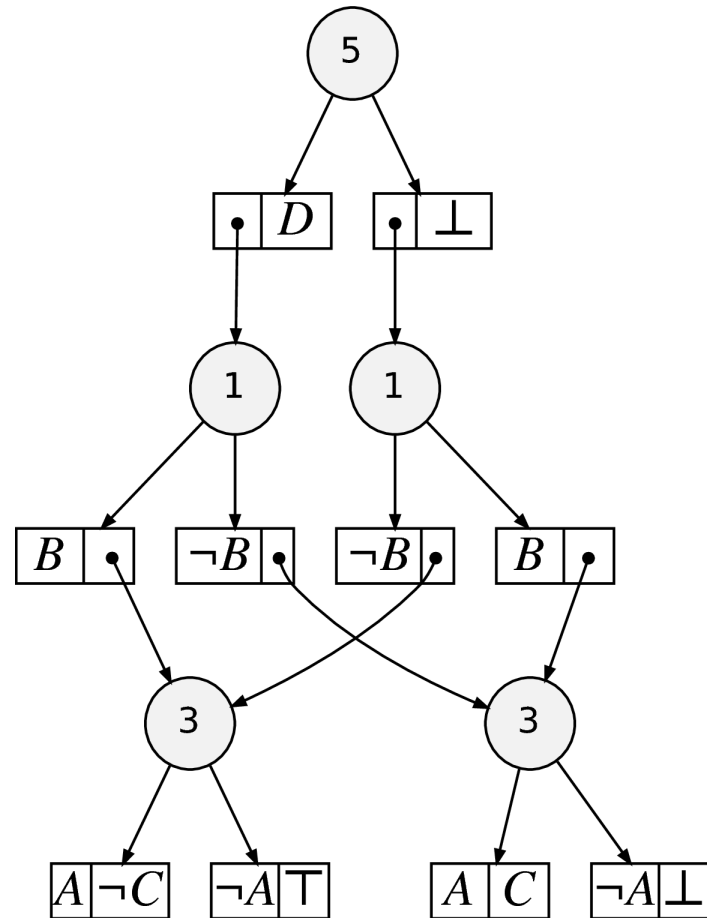
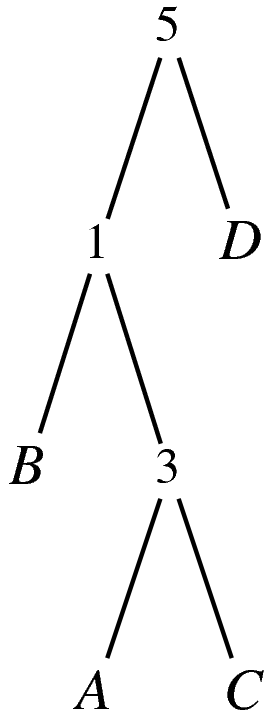


$ACBD$

The SDD Package

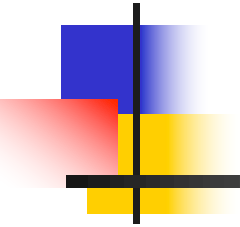


The SDD Package



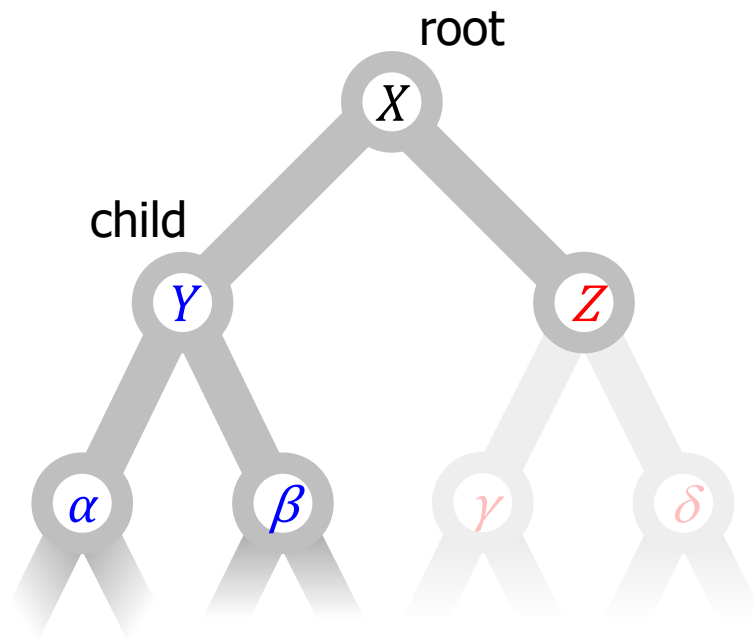
The

Fragment Abstraction





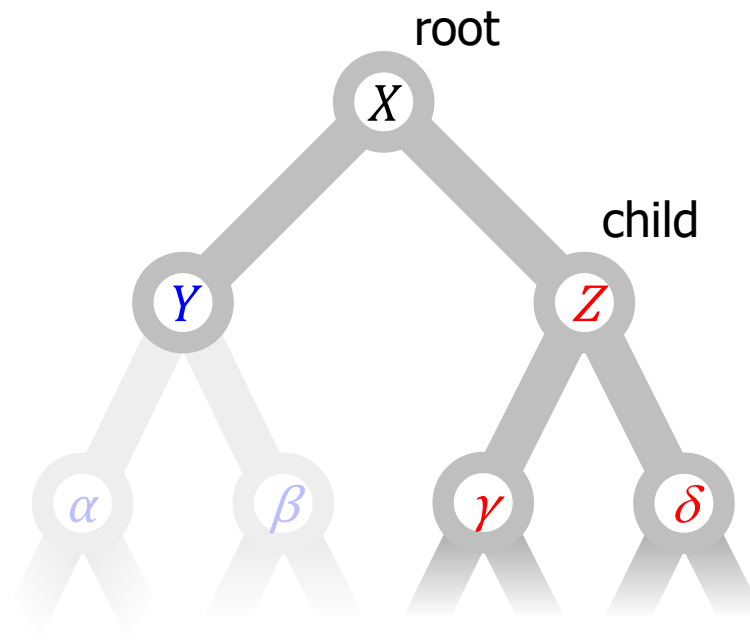
Vtree Fragments



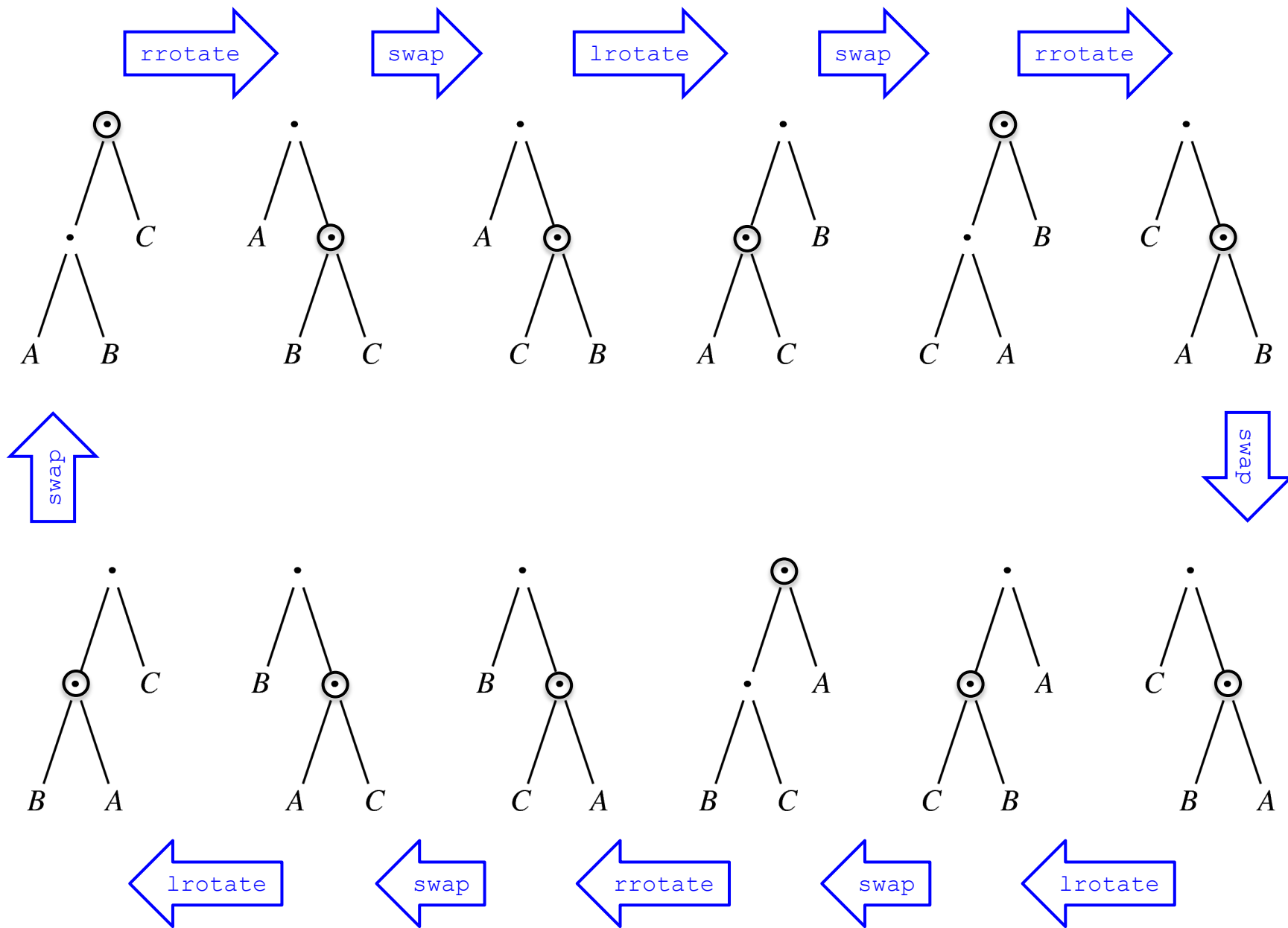
left-linear fragment

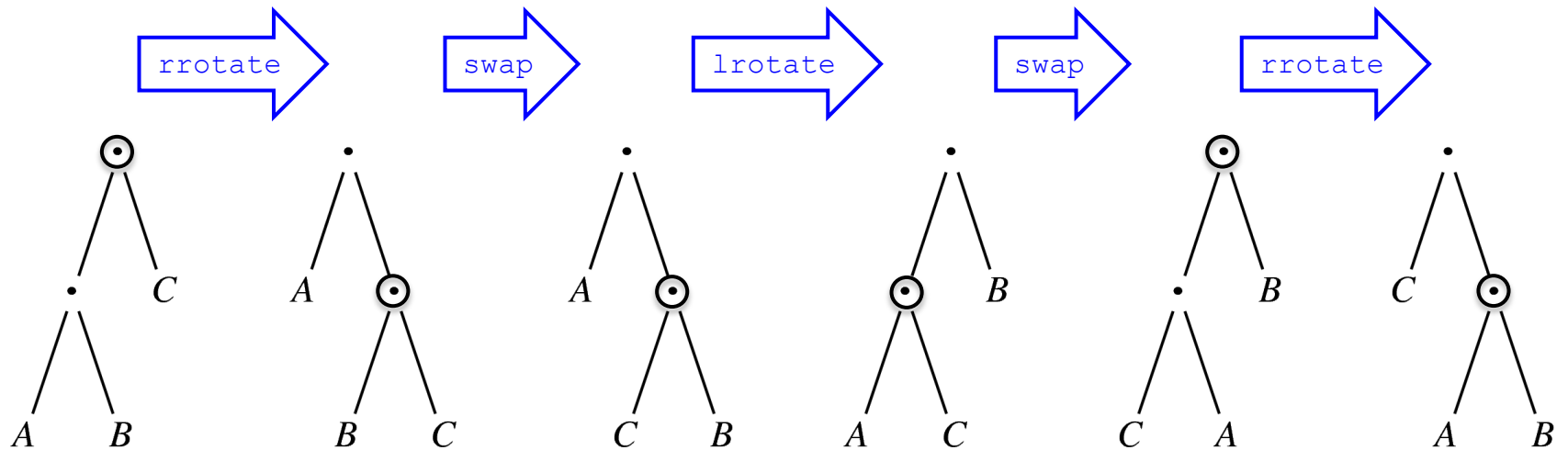


Vtree Fragments



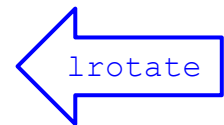
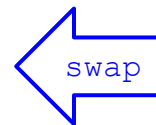
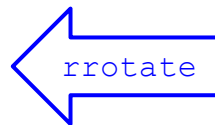
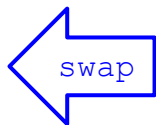
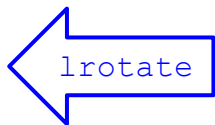
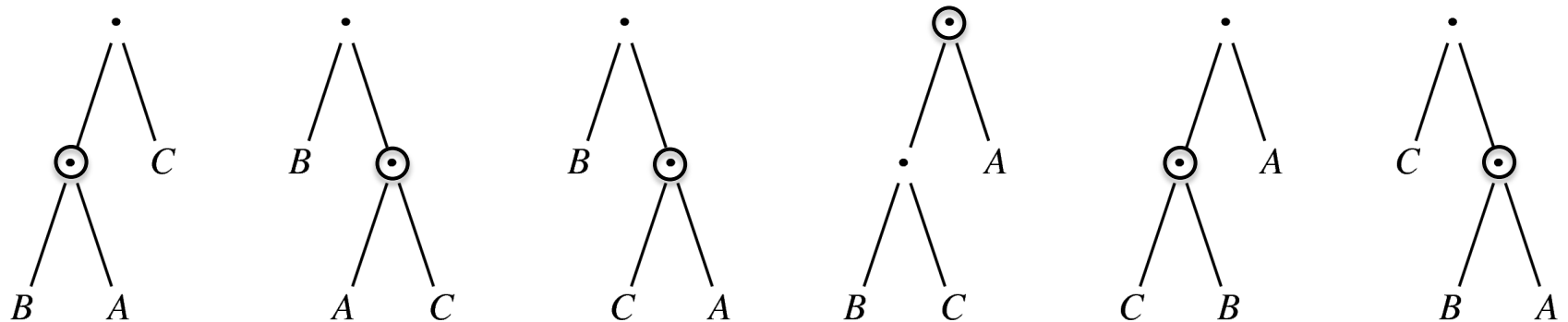
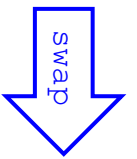
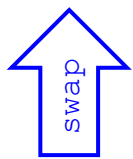
right-linear fragment





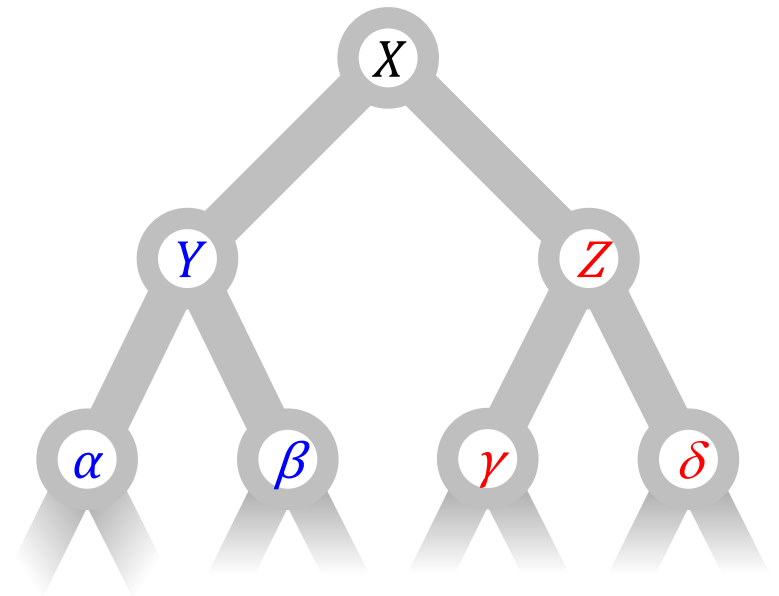
Fragment Operations

Next, Previous, Goto, ...



Greedy Vtree Search

- Traverse vtree bottom-up
- Try enumerating 12 vtrees of left-linear fragment
- Try enumerating 12 vtrees of right-linear fragment
- 24 vtrees in total
- Greedily accept best vtree
- Prune parts of search space

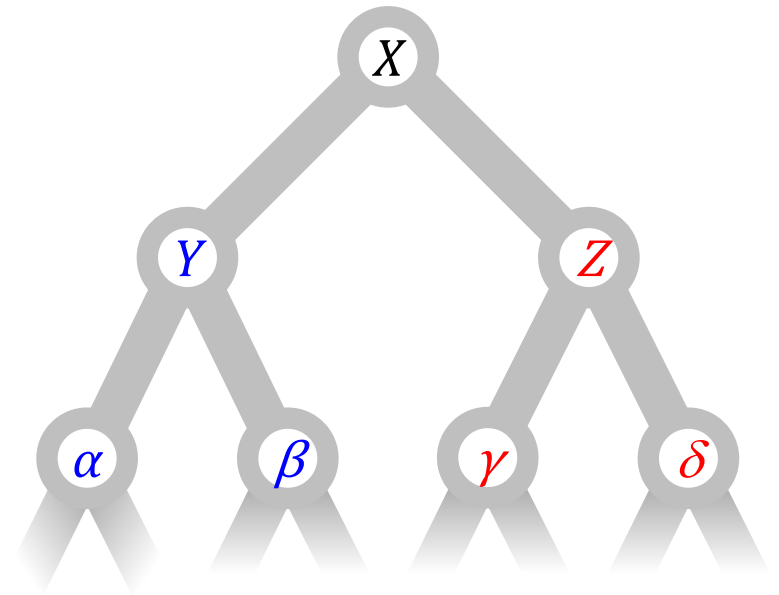




The SDD Package

Opportunities

- vtree search algorithms
- Triggers for vtree search
- Static methods for constructing vtrees
- Heuristics for scheduling
Apply operations





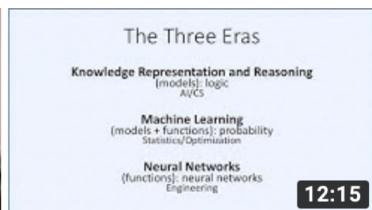
The SDD Package

- <http://reasoning.cs.ucla.edu/sdd>
- Written in C
- Available as open-source
- Code for compiling CNFs/DNFs into SDDs (includes heuristic for scheduling Apply)
- Two manuals: beginner and advanced

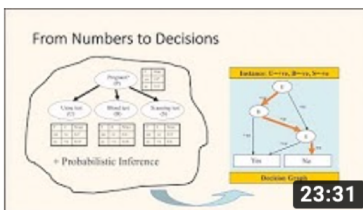
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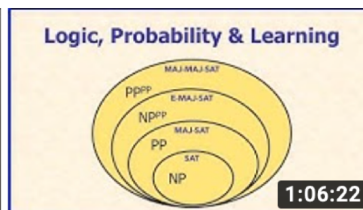
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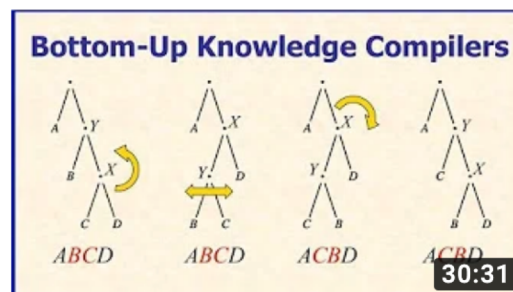
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