

Model-Based Diagnosis with Multiple Observations

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August 14, 2019 | **IJCAI**

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Motivation

Software fault localization – find the culprit!

```
1 void foo(bool b)
2 {
3     int x = 0;
4
5     x++;
6     if (b)
7         x++;
8     else
9         x++;
10
11     assert(x != 2);
12 }
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b = true:

$\Delta = \{\{3\}, \{5\}, \{6\}, \{7\}\}$

b = false:

$\Delta = \{\{3\}, \{5\}, \{6\}, \{9\}\}$

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both traces:

$\Delta = \{\{3\}, \{5\}, \{7, 9\}\}$

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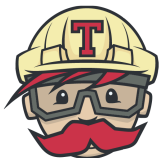
b = false:

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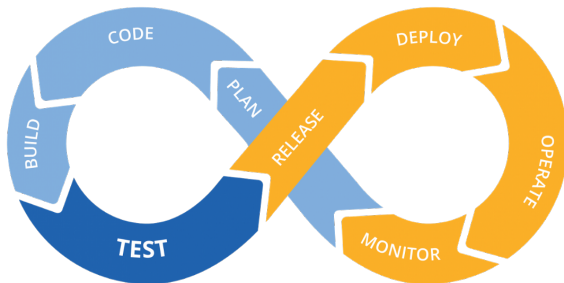
Meanwhile in real life...



Travis CI



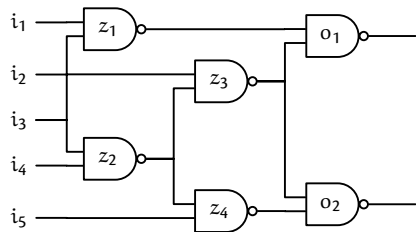
Jenkins



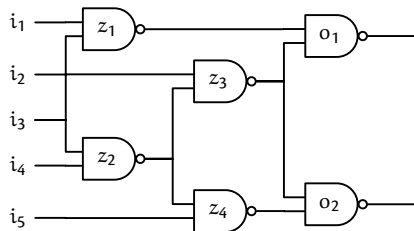
continuous integration (**lots of traces!**)

Model-based diagnosis

Model-based diagnosis

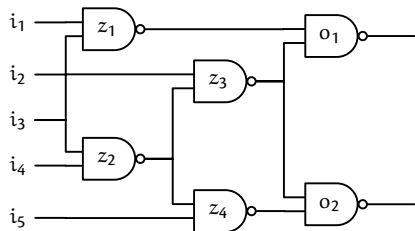


Model-based diagnosis



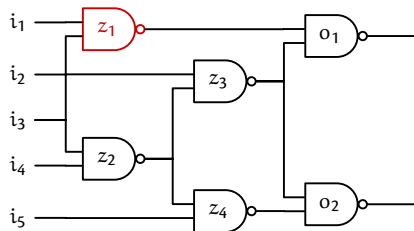
$$\begin{aligned} \text{Comps} &\triangleq \{z_1, z_2, z_3, z_4, o_1, o_2\} \\ \text{SD} &\triangleq \bigwedge_{c \in \text{Comps}} (\text{Ab}(c) \vee F_c) \end{aligned}$$

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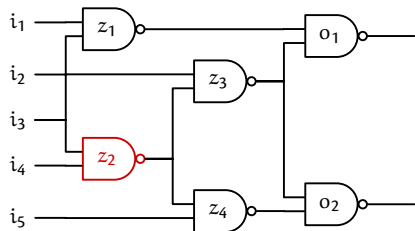
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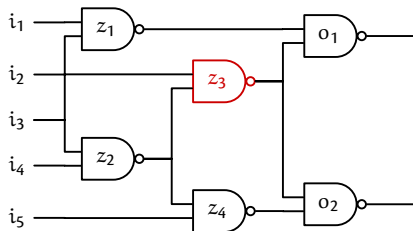
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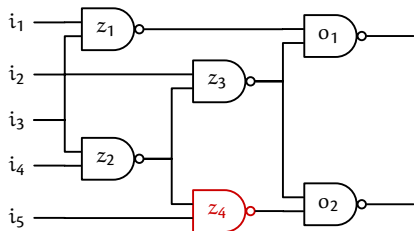
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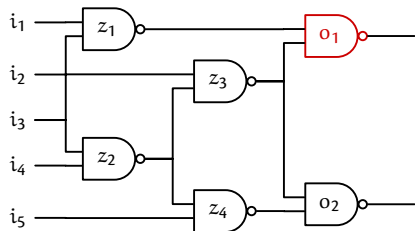
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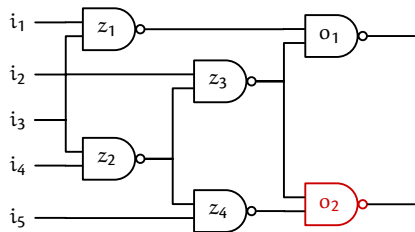
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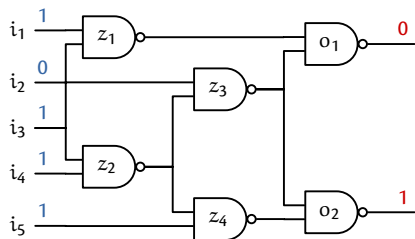
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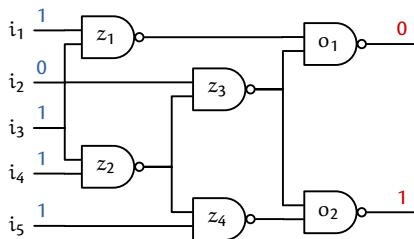
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$$\text{Obs} = \{ \langle i_1, i_2, i_3, i_4, i_5 \rangle = \langle 1, 0, 1, 1, 1 \rangle, \langle o_1, o_2 \rangle = \langle 0, 1 \rangle \}$$

Model-based diagnosis



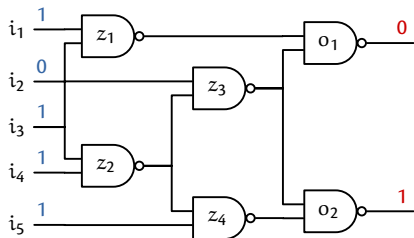
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$$\text{SD} \wedge \text{Obs} \wedge \bigwedge_{c \in \text{Comps}} \neg \text{Ab}(c) \models \perp$$

Model-based diagnosis



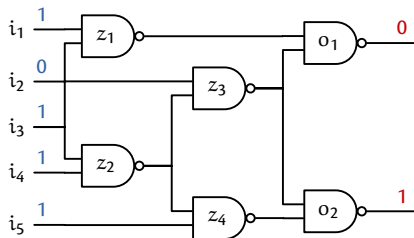
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Obs \triangleq $\{i_1, \neg i_2, i_3, i_4, i_5, \neg o_1, o_2\}$

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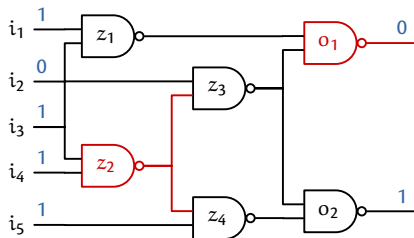
$$\text{SD} \wedge \text{Obs} \wedge \bigwedge_{c \in \text{Comps}} \neg \text{Ab}(c) \models \perp$$



find $\Delta \subseteq \text{Comps}$ s.t.

$$\text{SD} \wedge \text{Obs} \wedge \bigwedge_{c \in \Delta} \text{Ab}(c) \wedge \bigwedge_{c \in \text{Comps} \setminus \Delta} \neg \text{Ab}(c) \not\models \perp$$

Model-based diagnosis



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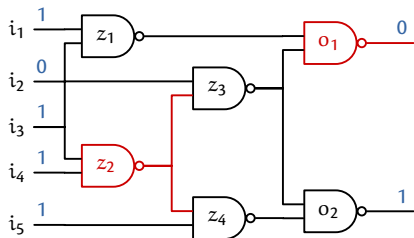


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$$\Delta = \{z_2, o_1\}$$

Model-based diagnosis



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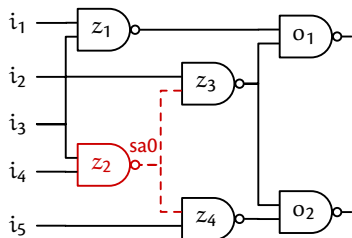
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$\Delta = \{z_2, o_1\}$ — minimize Δ , e.g. with MaxSAT

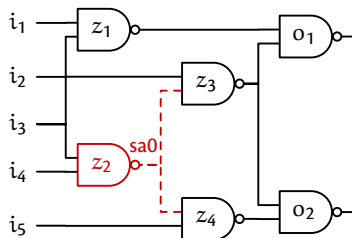
Multiple observations?

MBD with multiple observations



Comps	\triangleq	$\{z_1, z_2, z_3, z_4, o_1, o_2\}$
SD	\triangleq	$\bigwedge_{c \in \text{Comps}} (\text{Ab}(c) \vee F_c)$
F_{z_1}	\triangleq	$\text{CNF}(z_1 \leftrightarrow \neg(i_1 \wedge i_3))$
F_{z_2}	\triangleq	$\text{CNF}(z_2 \leftrightarrow \mathbf{0})$
F_{z_3}	\triangleq	$\text{CNF}(z_3 \leftrightarrow \neg(i_2 \wedge z_2))$
F_{z_4}	\triangleq	$\text{CNF}(z_4 \leftrightarrow \neg(z_2 \wedge i_5))$
F_{o_1}	\triangleq	$\text{CNF}(o_1 \leftrightarrow \neg(z_1 \wedge z_3))$
F_{o_2}	\triangleq	$\text{CNF}(o_2 \leftrightarrow \neg(z_3 \wedge z_4))$

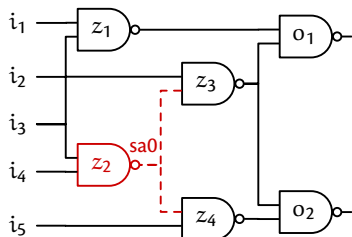
MBD with multiple observations



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 F_{z_2} &\triangleq \text{CNF}(z_2 \leftrightarrow \mathbf{0}) \\
 F_{z_3} &\triangleq \text{CNF}(z_3 \leftrightarrow \neg(i_2 \wedge z_2)) \\
 F_{z_4} &\triangleq \text{CNF}(z_4 \leftrightarrow \neg(z_2 \wedge i_5)) \\
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 \end{aligned}$$

Observation	$\langle i_1, i_2, i_3, i_4, i_5, o_1, o_2 \rangle$	Diagnoses
Obs ₁	$\langle \theta, 1, 1, \theta, 1, \mathbf{1}, \mathbf{1} \rangle$	$D_1 = \{\{z_2\}, \{z_3\}, \{z_1, z_4\}, \{z_1, o_2\}, \{z_4, o_1\}, \{o_1, o_2\}\}$
Obs ₂	$\langle 1, 1, 1, \theta, 1, 1, \mathbf{1} \rangle$	$D_2 = \{\{z_2\}, \{z_3\}, \{z_4\}, \{o_2\}\}$
Obs ₃	$\langle 1, \theta, \theta, \theta, 1, \theta, \mathbf{1} \rangle$	$D_3 = \{\{z_2\}, \{z_4\}, \{o_2\}, \{z_3, o_1\}\}$

MBD with multiple observations

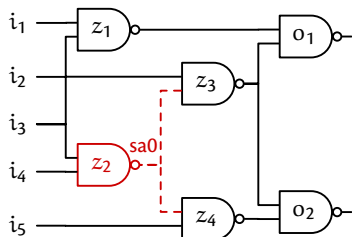


$$\begin{aligned}
 \text{Comps} &\triangleq \{z_1, z_2, z_3, z_4, o_1, o_2\} \\
 \text{SD} &\triangleq \bigwedge_{c \in \text{Comps}} (\text{Ab}(c) \vee F_c) \\
 F_{z_1} &\triangleq \text{CNF}(z_1 \leftrightarrow \neg(i_1 \wedge i_3)) \\
 F_{z_2} &\triangleq \text{CNF}(z_2 \leftrightarrow \mathbf{0}) \\
 F_{z_3} &\triangleq \text{CNF}(z_3 \leftrightarrow \neg(i_2 \wedge z_2)) \\
 F_{z_4} &\triangleq \text{CNF}(z_4 \leftrightarrow \neg(z_2 \wedge i_5)) \\
 F_{o_1} &\triangleq \text{CNF}(o_1 \leftrightarrow \neg(z_1 \wedge z_3)) \\
 F_{o_2} &\triangleq \text{CNF}(o_2 \leftrightarrow \neg(z_3 \wedge z_4))
 \end{aligned}$$

Observation	$\langle i_1, i_2, i_3, i_4, i_5, o_1, o_2 \rangle$	Diagnoses
Obs ₁	$\langle \emptyset, 1, 1, \emptyset, 1, \mathbf{1}, \mathbf{1} \rangle$	$D_1 = \{\{z_2\}, \{z_3\}, \{z_1, z_4\}, \{z_1, o_2\}, \{z_4, o_1\}, \{o_1, o_2\}\}$
Obs ₂	$\langle 1, 1, 1, \emptyset, 1, 1, \mathbf{1} \rangle$	$D_2 = \{\{z_2\}, \{z_3\}, \{z_4\}, \{o_2\}\}$
Obs ₃	$\langle 1, \emptyset, \emptyset, \emptyset, 1, \emptyset, \mathbf{1} \rangle$	$D_3 = \{\{z_2\}, \{z_4\}, \{o_2\}, \{z_3, o_1\}\}$

state-of-the-art approaches enumerate **96 aggregated diagnoses** while

MBD with multiple observations



$$\begin{aligned}
 \text{Comps} &\triangleq \{z_1, z_2, z_3, z_4, o_1, o_2\} \\
 \text{SD} &\triangleq \bigwedge_{c \in \text{Comps}} (\text{Ab}(c) \vee F_c) \\
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 F_{z_2} &\triangleq \text{CNF}(z_2 \leftrightarrow \mathbf{0}) \\
 F_{z_3} &\triangleq \text{CNF}(z_3 \leftrightarrow \neg(i_2 \wedge z_2)) \\
 F_{z_4} &\triangleq \text{CNF}(z_4 \leftrightarrow \neg(z_2 \wedge i_5)) \\
 F_{o_1} &\triangleq \text{CNF}(o_1 \leftrightarrow \neg(z_1 \wedge z_3)) \\
 F_{o_2} &\triangleq \text{CNF}(o_2 \leftrightarrow \neg(z_3 \wedge z_4))
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Observation	$\langle i_1, i_2, i_3, i_4, i_5, o_1, o_2 \rangle$	Diagnoses
Obs ₁	$\langle \emptyset, 1, 1, \emptyset, 1, \mathbf{1}, \mathbf{1} \rangle$	$D_1 = \{\{z_2\}, \{z_3\}, \{z_1, z_4\}, \{z_1, o_2\}, \{z_4, o_1\}, \{o_1, o_2\}\}$
Obs ₂	$\langle 1, 1, 1, \emptyset, 1, 1, \mathbf{1} \rangle$	$D_2 = \{\{z_2\}, \{z_3\}, \{z_4\}, \{o_2\}\}$
Obs ₃	$\langle 1, \emptyset, \emptyset, \emptyset, 1, \emptyset, \mathbf{1} \rangle$	$D_3 = \{\{z_2\}, \{z_4\}, \{o_2\}, \{z_3, o_1\}\}$

state-of-the-art approaches enumerate **96 aggregated diagnoses** while

$$\text{ID} = \{\{z_2\}, \{z_1, z_4\}, \{z_1, o_2\}, \{z_3, o_1\}, \{z_3, o_2\}, \{z_4, o_1\}, \{z_3, z_4\}, \{o_1, o_2\}\}, \text{ i.e. } |\text{ID}| = 8$$

DiagCombine¹:

¹S. Lamraoui and S. Nakajima. *A formula-based approach for automatic fault localization of imperative programs*. In ICFEM, pp. 251–266, 2014.

DiagCombine¹:

1. *enumerate* **all diagnoses for each observation**

¹S. Lamraoui and S. Nakajima. *A formula-based approach for automatic fault localization of imperative programs*. In ICFEM, pp. 251–266, 2014.

DiagCombine¹:

1. *enumerate* **all diagnoses for each observation**
2. *compute* **all “combinations”**

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DiagCombine¹:

1. *enumerate* **all diagnoses** for each observation
2. *compute* **all “combinations”**



(exponentially) many redundant diagnoses

¹S. Lamraoui and S. Nakajima. *A formula-based approach for automatic fault localization of imperative programs*. In ICFEM, pp. 251–266, 2014.

Example of DiagCombine

D_1 $\{ \{0\}, \{2\} \}$

D_2 $\{ \{0\}, \{1,2\} \}$

\mathbb{D} $\{ \qquad \qquad \qquad \}$

Example of DiagCombine

D_1 $\{ \{0\}, \{2\} \}$

D_2 $\{ \{0\}, \{1,2\} \}$

\mathbb{ID} $\{ \{0\}, \quad \quad \quad \}$

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\mathbb{ID} $\{ \{0\}, \{0,1,2\}, \quad \}$

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\mathbb{ID} $\{ \{0\}, \{0,1,2\}, \{0,2\}, \quad \}$

Example of DiagCombine

$$D_1 \quad \{ \{0\}, \{2\} \}$$

$$D_2 \quad \{ \{0\}, \{1,2\} \}$$

$$\mathbb{ID} \quad \{ \{0\}, \{0,1,2\}, \{0,2\}, \{1,2\} \}$$

Example of DiagCombine

$$D_1 \quad \{ \{0\}, \{2\} \}$$

$$D_2 \quad \{ \{0\}, \{1,2\} \}$$

redundant diagnoses!

$$\mathbb{ID} \quad \{ \{0\}, \{0,1,2\}, \{0,2\}, \{1,2\} \}$$

Improved DiagCombine

$$(a) \quad \exists_{\Delta} \forall_{D_i} \quad \Delta \in D_i \Rightarrow \Delta \in \mathbb{D}$$

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Improved DiagCombine

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$$D_1 \quad \{ \{0\}, \{2\} \}$$

$$D_2 \quad \{ \{0\}, \{1, 2\} \}$$

$$\mathbb{ID} \quad \{ \quad \quad \quad \}$$

Improved DiagCombine

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Improved DiagCombine

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$$D_1 \quad \{ \quad \{2\} \}$$

$$D_2 \quad \{ \quad \{1, 2\} \}$$

$$\mathbb{ID} \quad \{ \{0\}, \quad \{1, 2\} \}$$

Improved DiagCombine

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$$D_1 \quad \{ \quad \{2\} \}$$

$$D_2 \quad \{ \quad \quad \}$$

$$\mathbb{ID} \quad \{ \{0\}, \{0, 1, 2\}, \{0, 2\}, \{1, 2\} \}$$

(a) and (b) **not always apply!**



no silver bullet

Implicit hitting set dualization

Implicit hitting set dualization

```
input   : SD, Obs1, ..., Obsm
output  :  $\mathbb{D} = \{\Delta_1, \Delta_2 \dots\}$ ,  $\mathbb{U} = \{\mathcal{U}_1, \mathcal{U}_2 \dots\}$ 

1 ( $\mathcal{H}_1, \dots, \mathcal{H}_m, S$ )  $\leftarrow$  Encode(SD, Obs1, ..., Obsm)
2 ( $\mathbb{D}, \mathbb{U}$ )  $\leftarrow$  ( $\emptyset, \emptyset$ )
3 while true:
4     ( $st, \Delta$ )  $\leftarrow$  MinHS( $\mathbb{U}, \mathbb{D}$ )                                # find a min HS of  $\mathbb{U}$  s.t.  $\mathbb{D}$ 
5     if not st:
6         break
7     foreach  $i \in \{1, \dots, m\}$ :
8         ( $st, \kappa$ )  $\leftarrow$  SAT( $\mathcal{H}_i \cup (S \setminus \Delta)$ )
9         if not st:
10             $\mathcal{U} \leftarrow$  Reduce( $\kappa$ )                                #  $\mathcal{U}$  is MUS of  $\mathcal{H}_i \cup (S \setminus \Delta)$ 
11             $\mathbb{U} \leftarrow \mathbb{U} \cup \{\mathcal{U}\}$ 
12            ReportExpl( $\mathcal{U}$ )                                        # report min explanation
13            break
14     else:                                                                # if the loop was not broken
15          $\mathbb{D} \leftarrow \mathbb{D} \cup \{\Delta\}$                             # block diagnosis  $\Delta$ 
16         ReportDiag( $\Delta$ )                                           # report min diagnosis
17     foreach  $i \in \{1, \dots, m\}$ :
18         if not SAT( $\mathcal{H}_i \cup \mathbb{D}$ ):                                # no more diagnoses exist
19             return
20 return
```

Implicit hitting set dualization

```
input   : SD, Obs1, ..., Obsm
output  :  $\mathbb{D} = \{\Delta_1, \Delta_2 \dots\}$ ,  $\mathbb{U} = \{\mathcal{U}_1, \mathcal{U}_2 \dots\}$ 

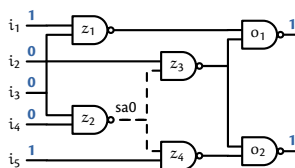
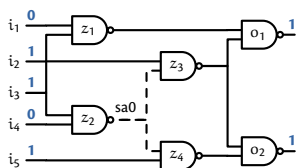
1 ( $\mathcal{H}_1, \dots, \mathcal{H}_m, S$ )  $\leftarrow$  Encode(SD, Obs1, ..., Obsm)
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```


Implicit hitting set dualization

```
input   :  $SD, Obs_1, \dots, Obs_m$ 
output  :  $\mathbb{D} = \{\Delta_1, \Delta_2 \dots\}, \mathbb{U} = \{\mathcal{U}_1, \mathcal{U}_2 \dots\}$ 

1 ( $\mathcal{H}_1, \dots, \mathcal{H}_m, S$ )  $\leftarrow$  Encode( $SD, Obs_1, \dots, Obs_m$ )
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19       if not SAT( $\mathcal{H}_i \cup \mathbb{D}$ ):
20         return
21   return
22   # no more diagnoses exist
```

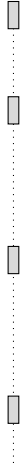
HSD – example



MinHS



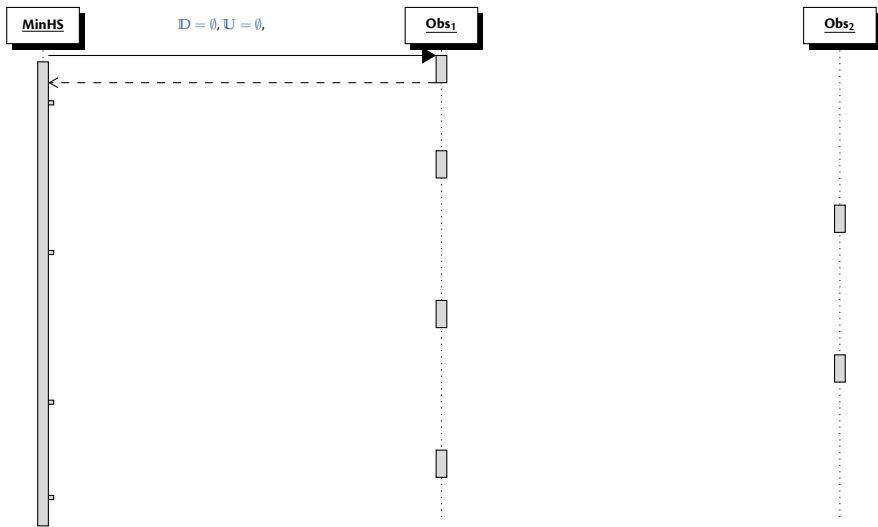
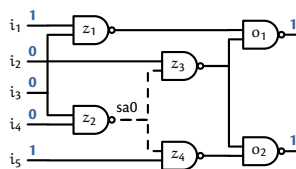
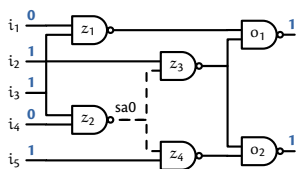
Obs₁



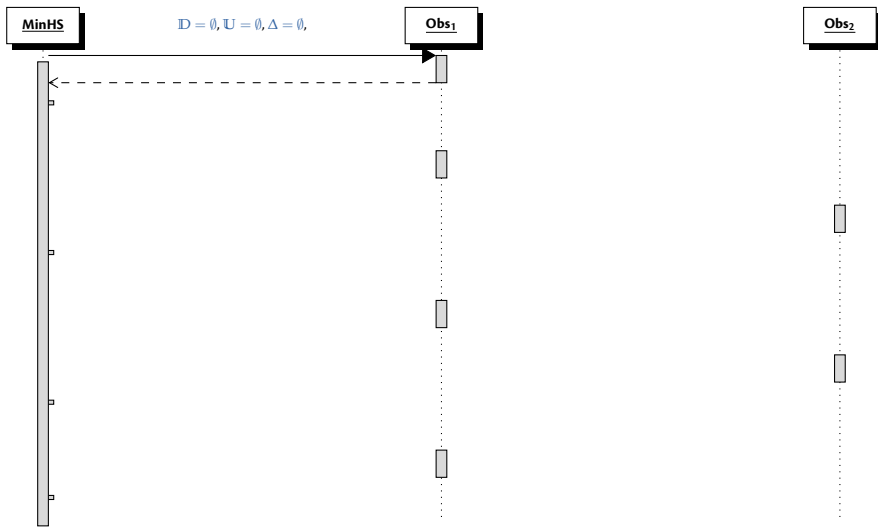
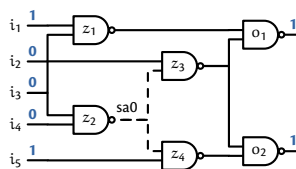
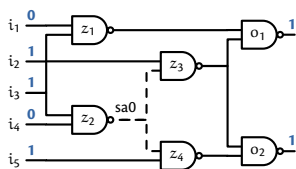
Obs₂



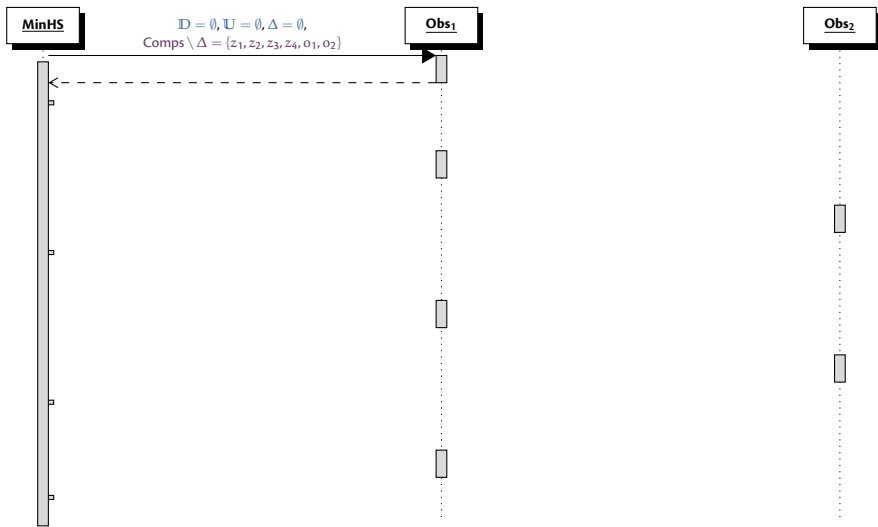
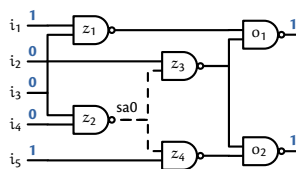
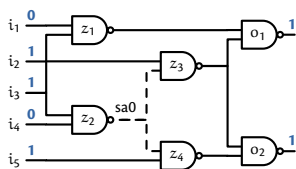
HSD – example



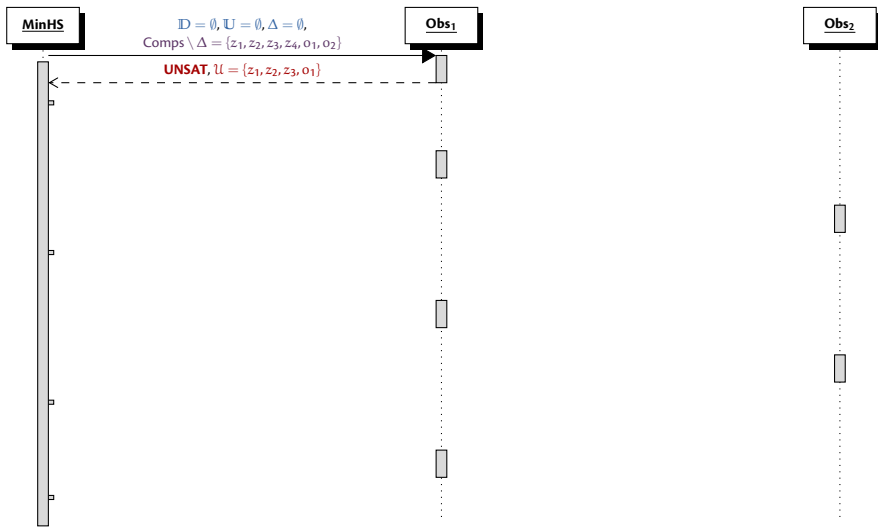
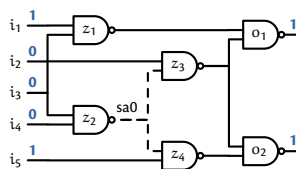
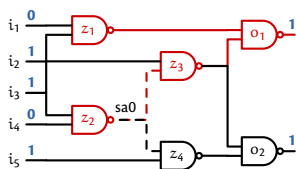
HSD – example



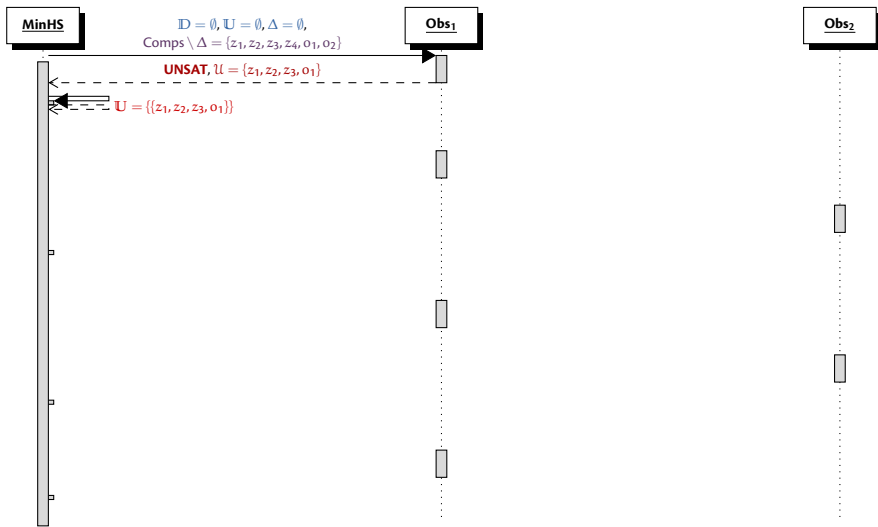
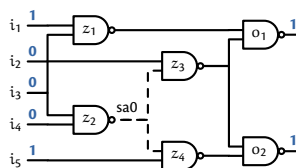
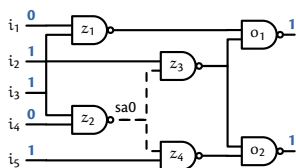
HSD – example



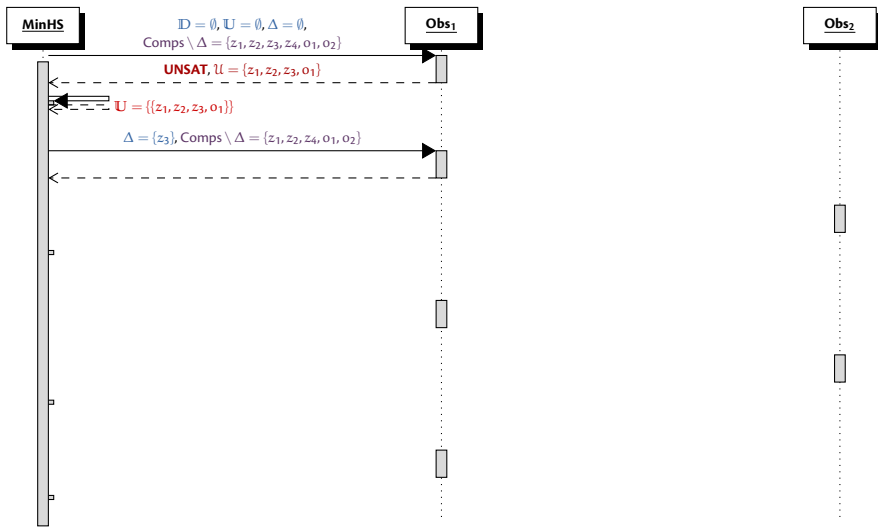
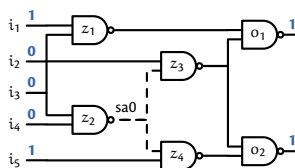
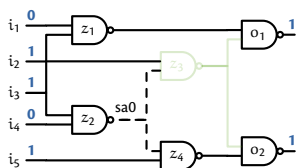
HSD – example



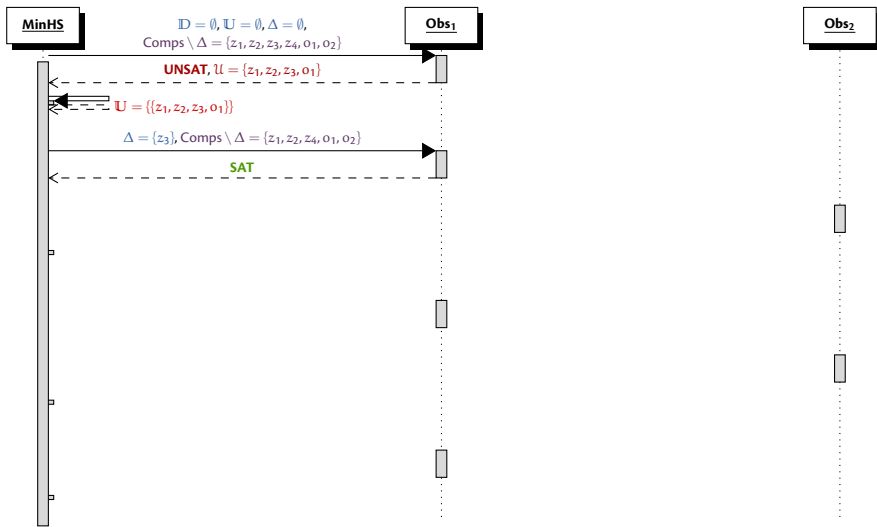
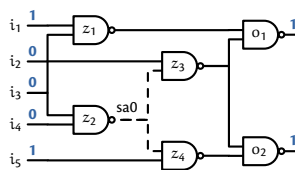
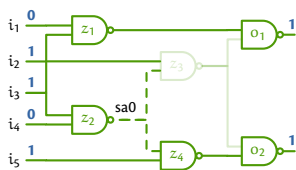
HSD – example



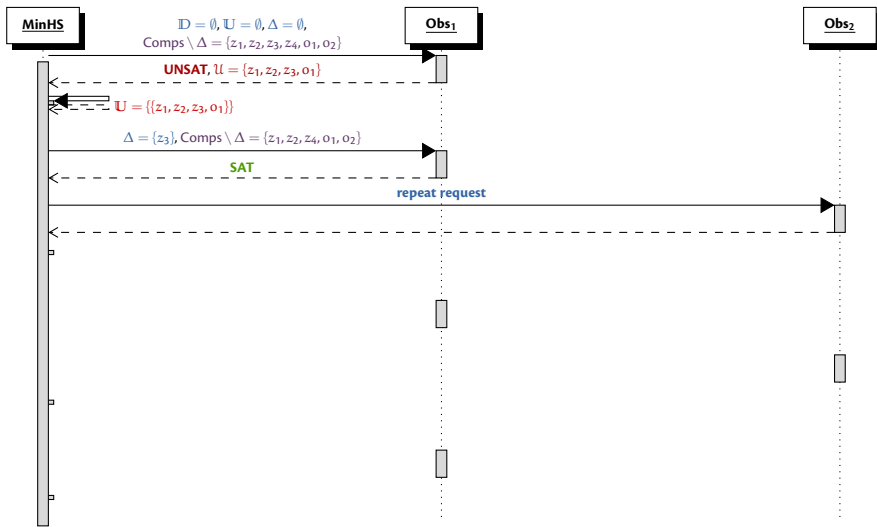
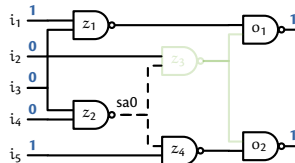
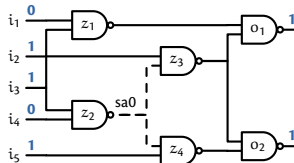
HSD – example



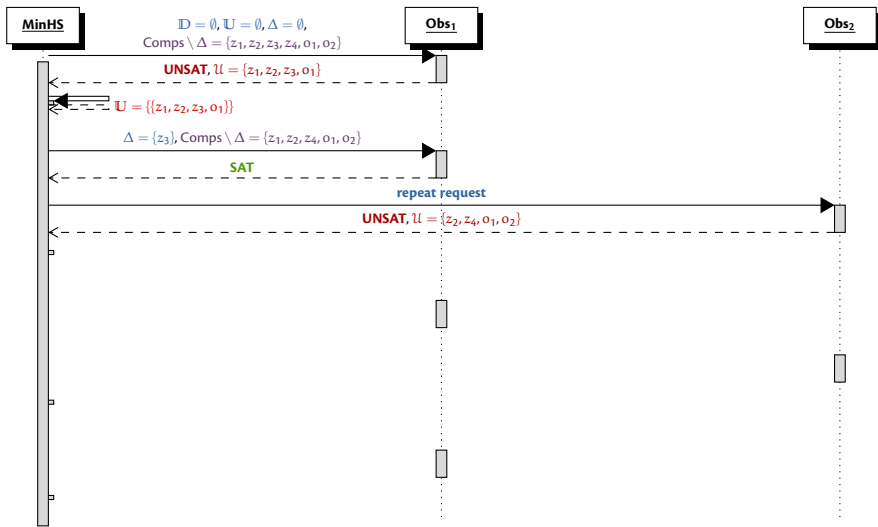
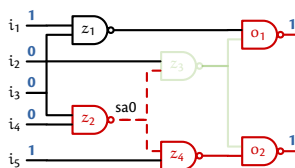
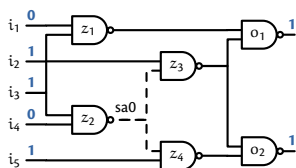
HSD – example



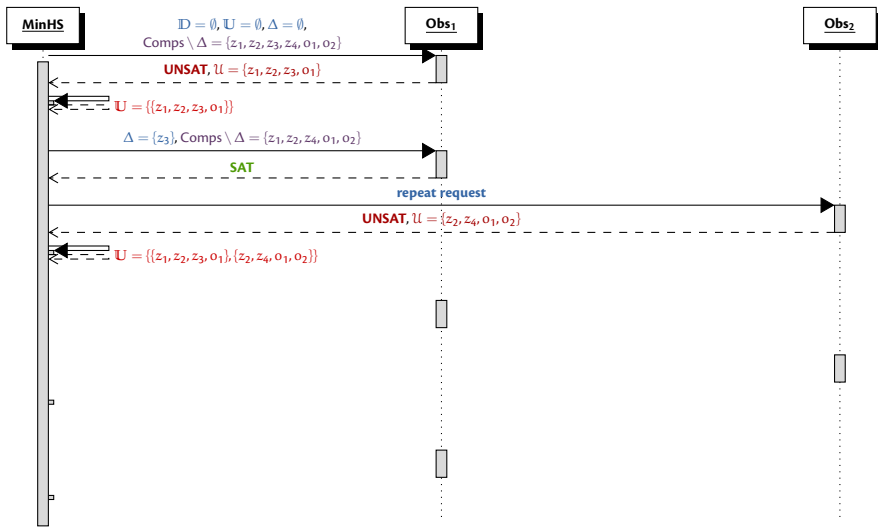
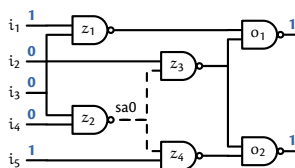
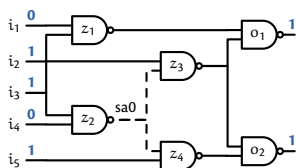
HSD – example



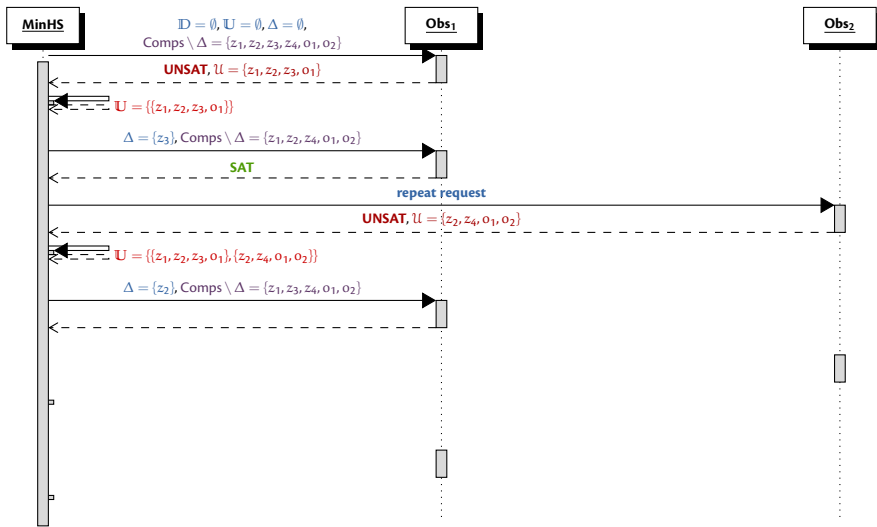
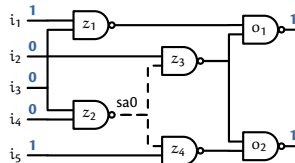
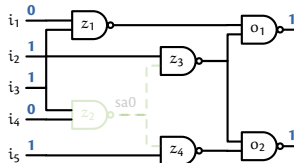
HSD – example



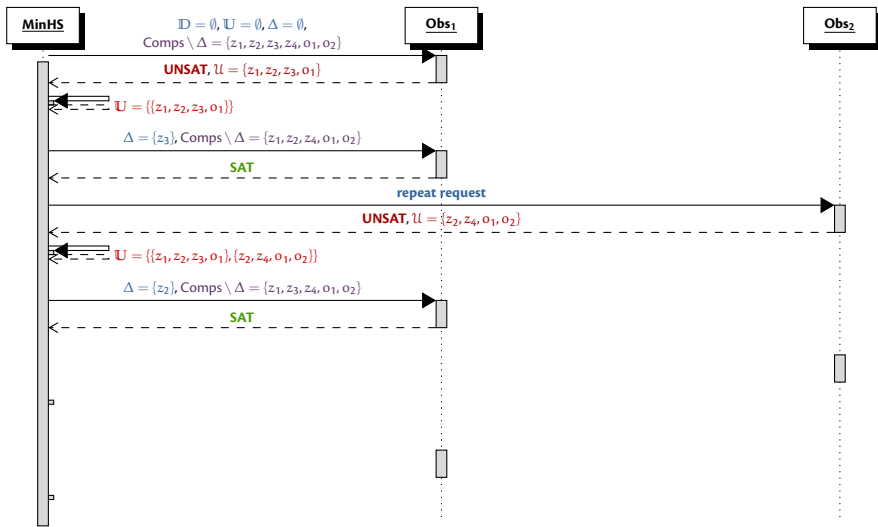
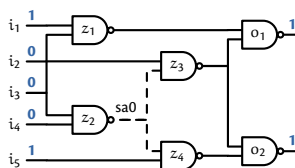
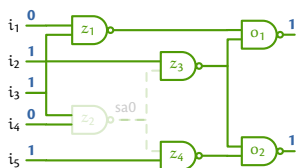
HSD – example



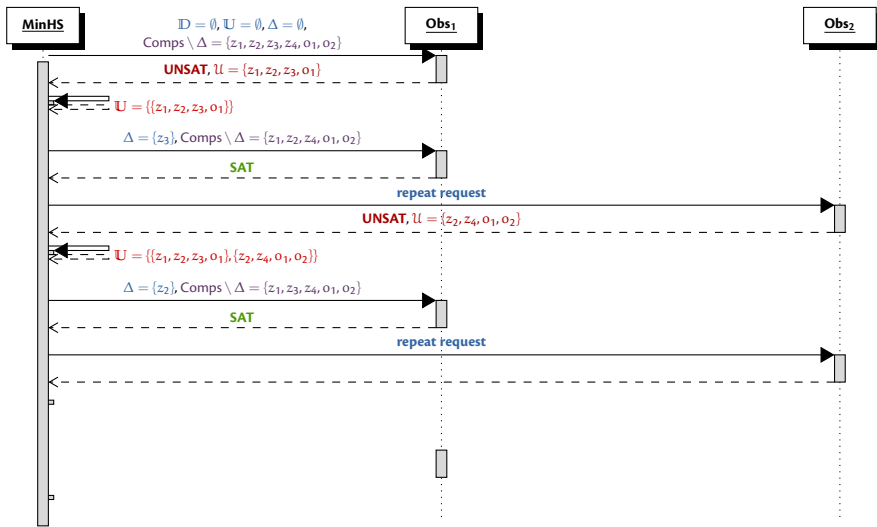
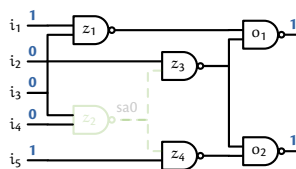
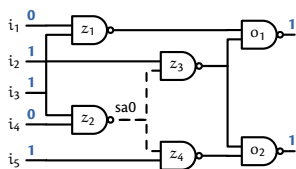
HSD – example



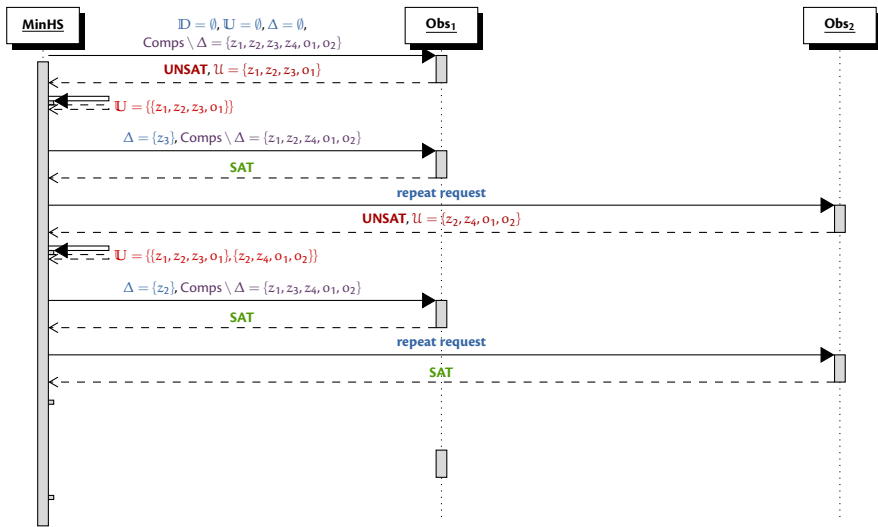
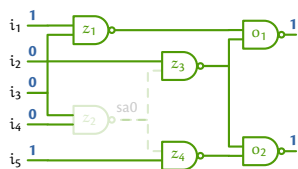
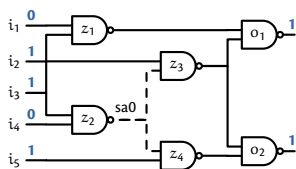
HSD – example



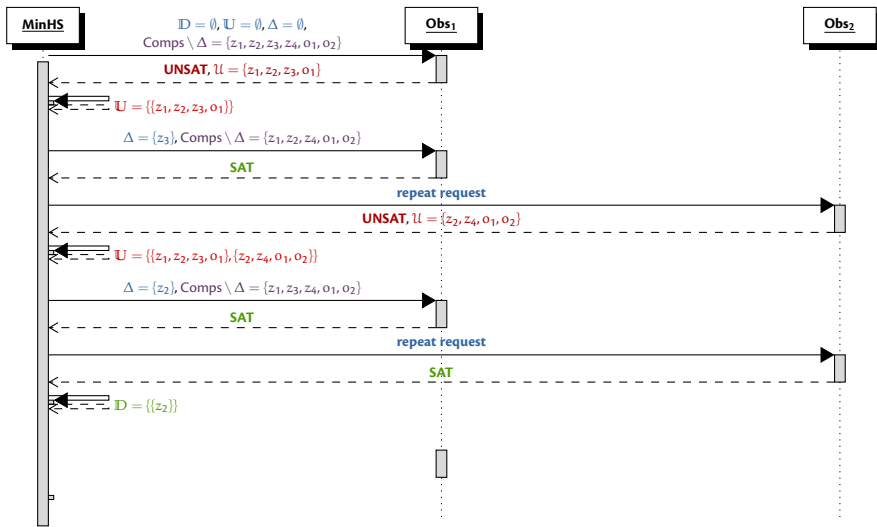
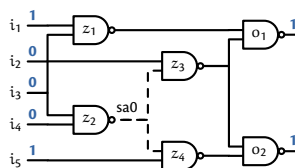
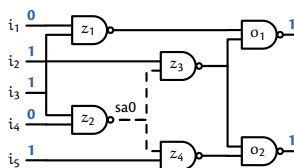
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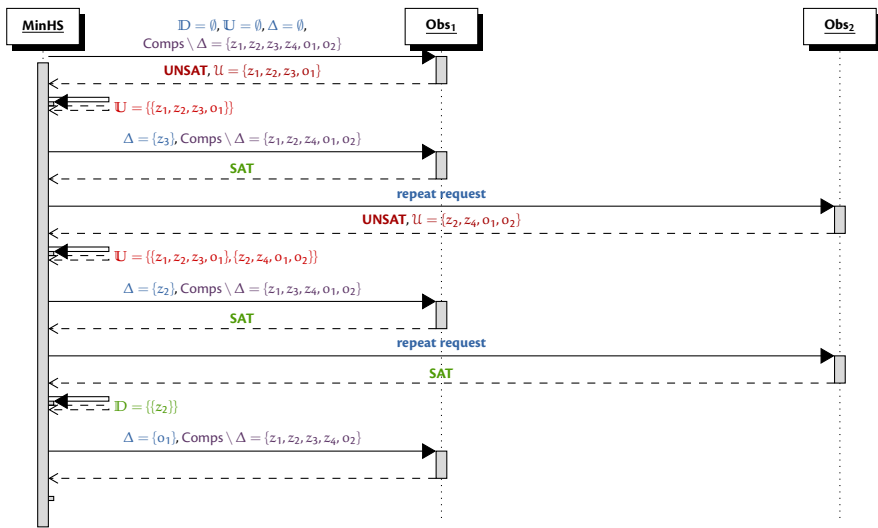
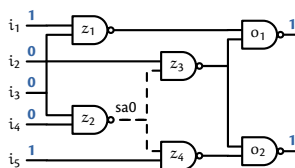
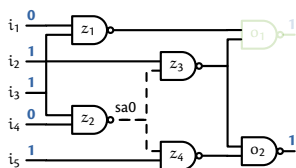
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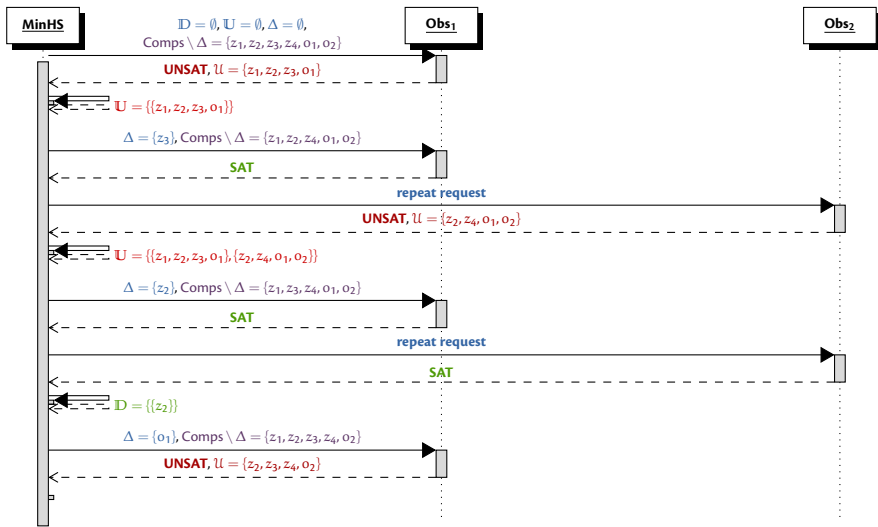
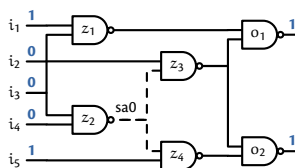
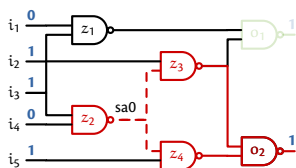
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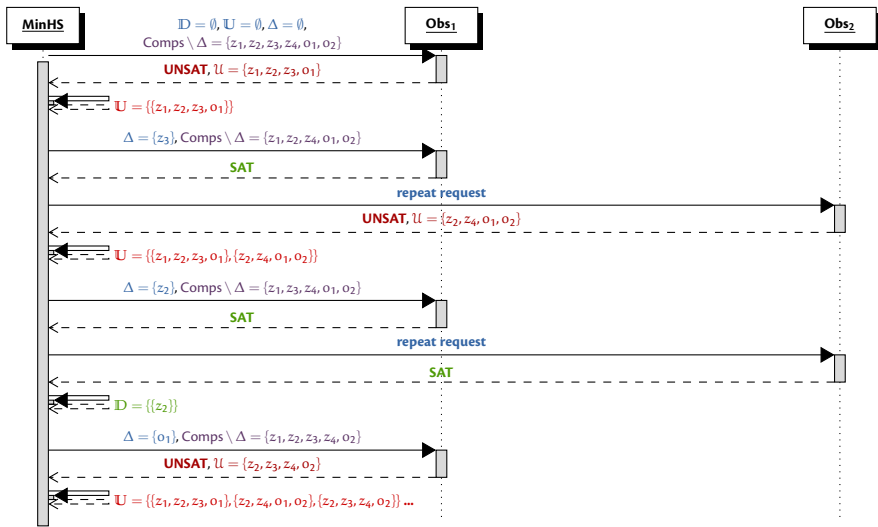
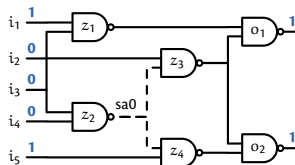
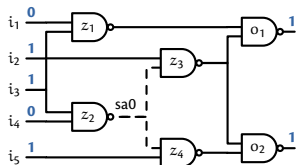
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Experimental results

Experimental evaluation²

- **ISCAS85 circuits** + **single stuck-at faults**

²<https://github.com/alexeyignatiev/mbd-mobs>

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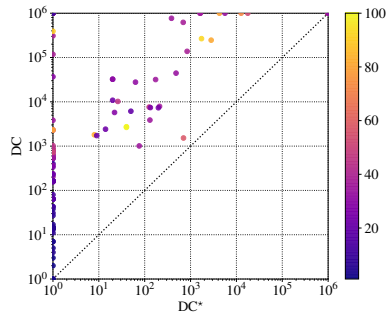
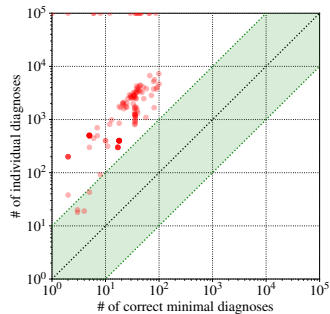
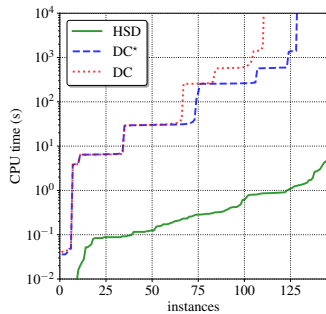
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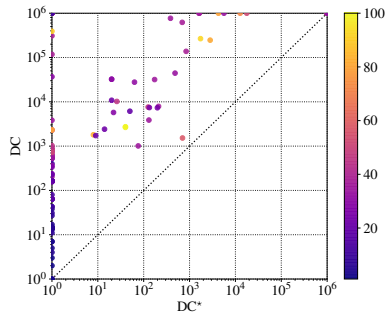
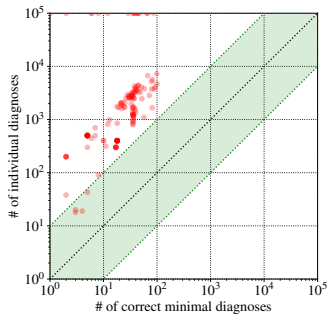
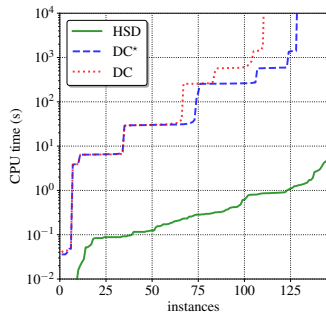
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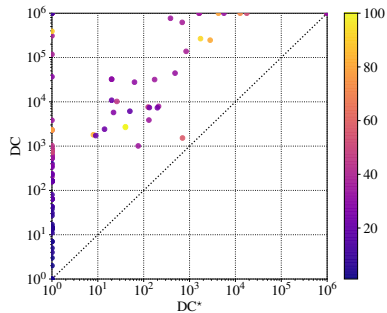
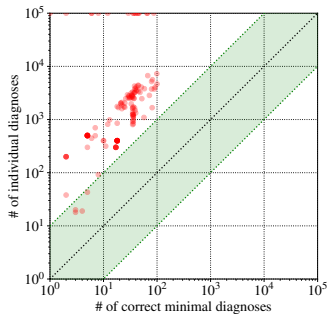
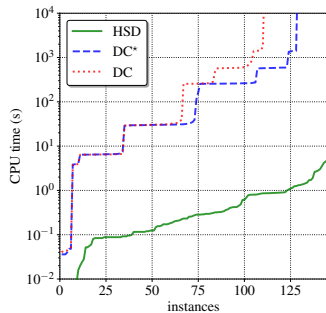


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HSD — 2–4 orders of magnitude performance improvement

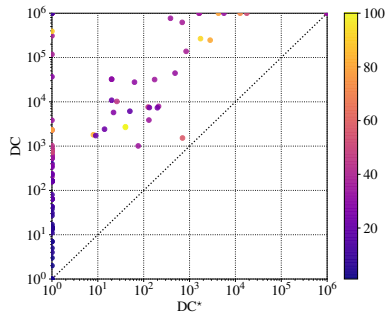
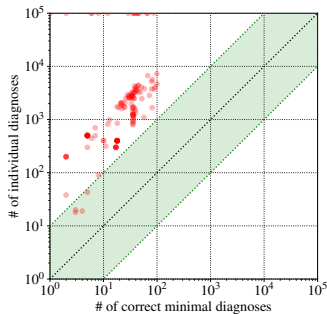
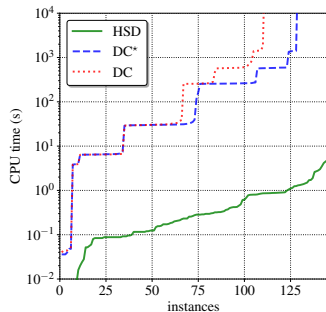
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DC vs. DC* — 1–6 orders of magnitude less “garbage”
(but still a lot!)

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 - machine learning models?
 - etc...

Questions?